

1. hodina

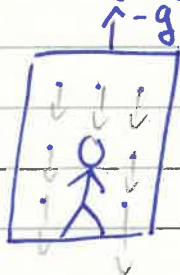
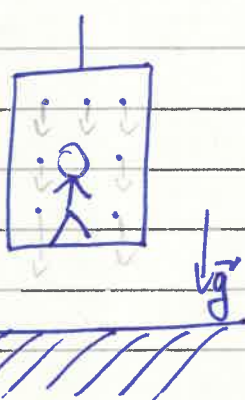
Výchozí principy

- Princip ekvivalence

$$m\vec{a} = -\frac{GMm}{r^2}\vec{r}_0$$
$$m\vec{a} = m\vec{g}$$

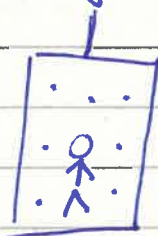
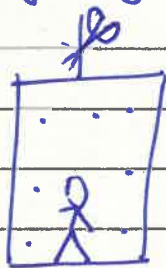
~~žet~~

- Lokální inerciální systém



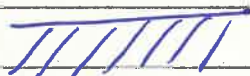
nerozlišitelné systémy
z pohledu pozoratelů uvnitř

V rychlých systémech se fyzikální procesy dějí
stejně jako v odpovídajícím gravitačním poli

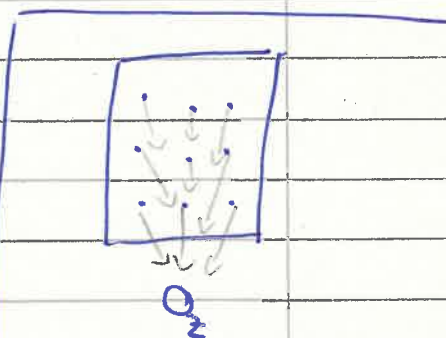


nerozlišitelné systémy

LIS



V reálně radajících systémech platí STR.
Lokálně



V každém bodě libovolného posteročasu
 lze zavést lokálně inerciální systém,
 tj. takový lokálně kartezijský systém souřadnic,
 ve kterém v dostatečně malém okolí uvažovaného bodu
 mají v něm všechny přírodní zákony stejnou formu jako v STR

Princip obecní kovariance

$$\begin{aligned} \Phi'(x') &= \Phi(x) \quad \text{skalár} \\ V'^{\mu}(x') &= \frac{\partial x'^{\mu}}{\partial x^{\nu}} V^{\nu}(x) \quad \text{vektor} \end{aligned}$$

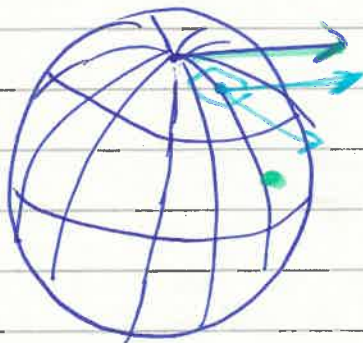
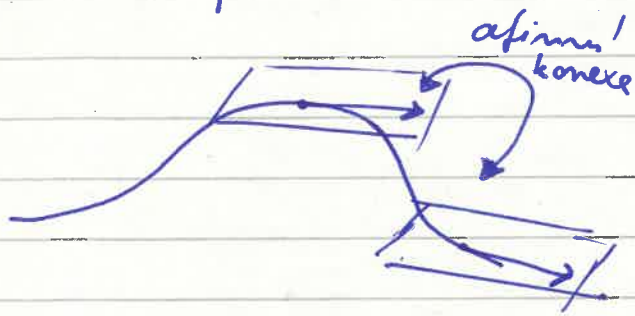
$$A'_a(x') = \frac{\partial x^{\beta}}{\partial x'^a} A_{\beta}(x) \quad \text{kovektor}$$

⋮

Poznámka:

- ① Zákony platí v STR
- ② PE $\Rightarrow$ platí ve stejném tvaru v lib. LISu
- ③ POK: zápis to v tenzorovém tvaru
a bude to platit obecně

Paralelní přenos



① STR

$p \mapsto x^\mu(p)$

$x^\mu(p)$



$$\frac{dV^\alpha}{dp} = 0 \quad \text{v kartézském systému}$$

② Lis : $\{\xi^\alpha\}_{\alpha=0}^3 \dots$ zars

③ $(\xi^\alpha) \rightarrow (x^\mu)$ („globální“)

Vektor : $V^{\hat{\alpha}} = \frac{\partial \xi^\alpha}{\partial x^{\hat{\nu}}} V^{\hat{\nu}}$

~~ale~~ $\frac{dV^{\hat{\alpha}}}{dp} = 0$

$\rightarrow \frac{d}{dp} \left(\frac{\partial \xi^\alpha}{\partial x^{\hat{\nu}}} V^{\hat{\nu}} \right) = \frac{\partial^2 \xi^\alpha}{\partial x^{\hat{\nu}} \partial x^{\hat{\rho}}} \frac{dx^{\hat{\rho}}}{dp} V^{\hat{\nu}} + \frac{\partial \xi^\alpha}{\partial x^{\hat{\nu}}} \frac{dV^{\hat{\nu}}}{dp}$

Chci „osvobodit“ $\frac{dV^{\hat{\nu}}}{dp}$

nasobím inverzní maticí $\frac{\partial x^{\hat{\rho}}}{\partial \xi^\alpha}$

$$\frac{dV^{\hat{\alpha}}}{dp} + \frac{\partial x^{\hat{\rho}}}{\partial \xi^\alpha} \frac{\partial^2 \xi^\alpha}{\partial x^{\hat{\nu}} \partial x^{\hat{\rho}}} V^{\hat{\nu}} \frac{dx^{\hat{\rho}}}{dp} = 0$$

Paralelní přenos

2. hodina

Zachová se kvadrat rektoru?

$$\eta_{\alpha\beta} \hat{V}^{\hat{\alpha}} \hat{V}^{\hat{\beta}} = \eta_{\alpha\beta} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} V^{\mu} \frac{\partial \xi^{\beta}}{\partial x^{\nu}} V^{\nu} \rightarrow g_{\mu\nu} = \eta_{\alpha\beta} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \frac{\partial \xi^{\beta}}{\partial x^{\nu}}$$

$$\eta^{\rho\sigma} \hat{V}_{\hat{\rho}} \hat{V}_{\hat{\sigma}} = \eta^{\rho\sigma} \frac{\partial x^{\mu}}{\partial \xi^{\rho}} V_{\mu} \frac{\partial x^{\nu}}{\partial \xi^{\sigma}} V_{\nu} \rightarrow g^{\mu\nu} = \eta^{\rho\sigma} \frac{\partial x^{\mu}}{\partial \xi^{\rho}} \frac{\partial x^{\nu}}{\partial \xi^{\sigma}}$$

$$g^{\mu\lambda} g_{\mu\nu} = \eta^{\rho\sigma} \frac{\partial x^{\mu}}{\partial \xi^{\rho}} \frac{\partial x^{\lambda}}{\partial \xi^{\sigma}} \eta_{\alpha\beta} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \frac{\partial \xi^{\beta}}{\partial x^{\nu}} =$$

$$= \eta^{\rho\sigma} \eta_{\alpha\beta} \frac{\partial x^{\mu}}{\partial \xi^{\rho}} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \frac{\partial x^{\lambda}}{\partial \xi^{\sigma}} \frac{\partial \xi^{\beta}}{\partial x^{\nu}} =$$

$$= \eta^{\rho\sigma} \eta_{\alpha\beta} \delta^{\mu}_{\rho} \delta^{\alpha}_{\mu} \delta^{\lambda}_{\sigma} \delta^{\beta}_{\lambda} = \delta^{\rho}_{\sigma} \delta^{\mu}_{\mu} \delta^{\lambda}_{\lambda} \delta^{\alpha}_{\alpha} =$$

$$= \delta^{\mu}_{\nu}$$

Vztah $g_{\mu\nu}$ a $\Gamma^{\alpha}_{\beta\mu}$:

$$+ g_{\mu\nu,\rho} = \eta_{\alpha\beta} \left(\frac{\partial^2 \xi^{\alpha}}{\partial x^{\mu} \partial x^{\rho}} \frac{\partial \xi^{\beta}}{\partial x^{\nu}} + \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \frac{\partial^2 \xi^{\beta}}{\partial x^{\nu} \partial x^{\rho}} \right) =$$

$$= \eta_{\alpha\beta} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \Gamma^{\mu}_{\nu\rho} \frac{\partial \xi^{\beta}}{\partial x^{\nu}} + \eta_{\alpha\beta} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \frac{\partial \xi^{\beta}}{\partial x^{\nu}} \Gamma^{\nu}_{\mu\rho} =$$

$$= g_{\nu\mu} \Gamma^{\mu}_{\nu\rho} + g_{\mu\nu} \Gamma^{\nu}_{\mu\rho} = \Gamma_{\nu\mu\rho} + \Gamma_{\mu\nu\rho}$$

$$+ g_{\rho\mu,\nu} = \Gamma_{\mu\rho\nu} + \Gamma_{\rho\mu\nu}$$

$$- g_{\nu\rho,\mu} = \Gamma_{\nu\rho\mu} + \Gamma_{\rho\nu\mu}$$

$$\frac{1}{2} (g_{\mu\nu,\rho} + g_{\rho\mu,\nu} - g_{\nu\rho,\mu}) = \overset{\text{Christoffel}}{\Gamma_{\mu\nu\rho}} \text{ (Levi-Civita symbol)}$$

Christoffelovy symboly 1. druhu

$$\begin{aligned}
\frac{d}{dp}(g_{\mu\nu} V^\mu V^\nu) &= g_{\mu\nu, \rho} \frac{dx^\rho}{dp} V^\mu V^\nu + g_{\mu\nu} \frac{dV^\mu}{dp} V^\nu + g_{\mu\nu} V^\mu \frac{dV^\nu}{dp} = \\
&= g_{\mu\nu, \rho} \frac{dx^\rho}{dp} V^\mu V^\nu - g_{\mu\nu} \Gamma_{\mu\lambda}^\alpha V^\lambda \frac{dx^\alpha}{dp} V^\nu - g_{\mu\nu} V^\mu \Gamma_{\nu\lambda}^\alpha V^\lambda \frac{dx^\alpha}{dp} = \\
&= g_{\mu\nu, \lambda} \frac{dx^\lambda}{dp} V^\mu V^\nu - g_{\mu\nu} \Gamma_{\mu\lambda}^\alpha V^\lambda \frac{dx^\alpha}{dp} V^\nu - g_{\mu\nu} V^\mu \Gamma_{\nu\lambda}^\alpha V^\lambda \frac{dx^\alpha}{dp} = \\
&= g_{\mu\nu, \lambda} \frac{dx^\lambda}{dp} V^\mu V^\nu - \Gamma_{\mu\lambda}^\alpha V^\lambda V^\mu \frac{dx^\alpha}{dp} - \Gamma_{\nu\lambda}^\alpha V^\lambda V^\nu \frac{dx^\alpha}{dp} = \\
&= (g_{\mu\nu, \lambda} - \Gamma_{\mu\lambda}^\alpha - \Gamma_{\nu\lambda}^\alpha) V^\mu V^\nu \frac{dx^\lambda}{dp} = 0
\end{aligned}$$

Pro kovektory:

Pro tenzor?

Je paralelu' pēmas abecīnē kovariantu'?

$$\frac{dV'^{\mu}}{dp} + \Gamma^{\mu}_{\lambda\lambda} V'^{\lambda} \frac{dx'^{\lambda}}{dp} = 0$$

$$\frac{dV'^{\mu}}{dp} + \frac{\partial x'^{\mu}}{\partial \xi^{\alpha\beta}} \frac{\partial^2 \xi^{\alpha\beta}}{\partial x'^{\lambda} \partial x'^{\lambda}} V'^{\lambda} \frac{dx'^{\lambda}}{dp} = 0$$

$$V'^{\lambda} = \frac{\partial x'^{\lambda}}{\partial x^{\alpha}} V^{\alpha}, \quad \frac{dx'^{\lambda}}{dp} = \frac{\partial x'^{\lambda}}{\partial x^{\sigma}} \frac{dx^{\sigma}}{dp}$$

$$\frac{dV'^{\mu}}{dp} = \frac{d}{dp} \left(\frac{\partial x'^{\mu}}{\partial x^{\alpha}} V^{\alpha} \right) =$$

$$= \frac{\partial x'^{\mu}}{\partial x^{\alpha}} \frac{dV^{\alpha}}{dp} + \frac{\partial^2 x'^{\mu}}{\partial x^{\alpha} \partial x^{\beta}} \frac{dx^{\beta}}{dp} V^{\alpha}$$

$$\frac{\partial^2 \xi^{\alpha\beta}}{\partial x'^{\lambda} \partial x'^{\lambda}} = \frac{\partial}{\partial x'^{\lambda}} \left(\frac{\partial \xi^{\alpha\beta}}{\partial x^{\sigma}} \frac{\partial x^{\sigma}}{\partial x'^{\lambda}} \right) =$$

$$= \frac{\partial^2 \xi^{\alpha\beta}}{\partial x^{\sigma} \partial x^{\alpha}} \frac{\partial x^{\sigma}}{\partial x'^{\lambda}} \frac{\partial x^{\alpha}}{\partial x'^{\lambda}} + \frac{\partial \xi^{\alpha\beta}}{\partial x^{\sigma}} \frac{\partial^2 x^{\sigma}}{\partial x'^{\lambda} \partial x'^{\lambda}}$$

$$\Gamma^{\mu}_{\lambda\lambda} = \frac{\partial x'^{\mu}}{\partial x^{\nu}} \frac{\partial x^{\nu}}{\partial \xi^{\alpha\beta}} \left(\frac{\partial^2 \xi^{\alpha\beta}}{\partial x^{\sigma} \partial x^{\alpha}} \frac{\partial x^{\sigma}}{\partial x'^{\lambda}} \frac{\partial x^{\alpha}}{\partial x'^{\lambda}} + \frac{\partial \xi^{\alpha\beta}}{\partial x^{\sigma}} \frac{\partial^2 x^{\sigma}}{\partial x'^{\lambda} \partial x'^{\lambda}} \right) =$$

$$= \frac{\partial x'^{\mu}}{\partial x^{\nu}} \frac{\partial x^{\sigma}}{\partial x'^{\lambda}} \frac{\partial x^{\alpha}}{\partial x'^{\lambda}} \Gamma^{\nu}_{\sigma\alpha} + \frac{\partial x'^{\mu}}{\partial x^{\nu}} \frac{\partial^2 x^{\nu}}{\partial x'^{\lambda} \partial x'^{\lambda}}$$

Dasodime:

$$\rightarrow \frac{\partial x'^{\mu}}{\partial x^{\alpha}} \frac{dV^{\alpha}}{dp} + \frac{\partial x'^{\mu}}{\partial x^{\nu}} \frac{\partial x^{\rho}}{\partial x'^{\mu}} \frac{\partial x^{\alpha}}{\partial x^{\rho}} \Gamma^{\nu}_{\rho\alpha} \frac{\partial x'^{\mu}}{\partial x^{\sigma}} \sqrt{g} \frac{\partial x'^{\sigma}}{\partial x^{\sigma}} \frac{dx^{\sigma}}{dp} =$$

$$= \frac{\partial x'^{\mu}}{\partial x^{\alpha}} \left(\frac{dV^{\alpha}}{dp} + \Gamma^{\alpha}_{\mu\sigma} \sqrt{g} \frac{dx^{\sigma}}{dp} \right)$$

2byk2:

$$\frac{\partial^2 x'^{\mu}}{\partial x^{\alpha} \partial x^{\beta}} \frac{dx^{\beta}}{dp} \sqrt{g} + \frac{\partial x'^{\mu}}{\partial x^{\nu}} \frac{\partial^2 x^{\nu}}{\partial x^{\alpha} \partial x^{\beta}}$$

Geodetika

• geodetika jako přímky v obecném prostoročase

① g = metrika, paralelní se její tečnou vektor přenášejí paralelně

$$\frac{d^2 x^\mu}{d\tau^2} + \Gamma_{\mu\lambda}^{\nu} \frac{dx^\lambda}{d\tau} \frac{dx^\mu}{d\tau} = 0$$

+ počáteční podmínky

② Charakter geodetiky se nachází

② časupodobný případ

$$LIS: \frac{d^2 \xi^\alpha}{d\tau^2} = 0$$

$$\frac{d}{d\tau} \left(\frac{d\xi^\alpha}{d\tau} \right) = \frac{d}{d\tau} \left(\frac{\partial \xi^\alpha}{\partial x^\mu} \frac{dx^\mu}{d\tau} \right) =$$

$$= \frac{\partial \xi^\alpha}{\partial x^\mu} \frac{d^2 x^\mu}{d\tau^2} + \frac{\partial^2 \xi^\alpha}{\partial x^\mu \partial x^\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}$$

$$\rightarrow \frac{d^2 \xi^\alpha}{d\tau^2} + \frac{\partial \xi^\alpha}{\partial x^\mu} \frac{\partial^2 \xi^\alpha}{\partial x^\mu \partial x^\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} = 0$$

naše částice se pohybuje po geodetice
vzhledem k

3. hodina

Geodetiky

Rovnice pro paralelní přenos:

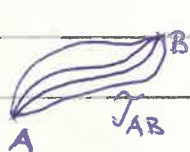
$$\frac{dV^\alpha}{dp} + \Gamma^\alpha_{\beta\gamma} V^\beta \frac{dx^\gamma}{dp} = 0$$

- pro volbu křivky nelze $V^\alpha = \frac{dx^\alpha}{dp}$

jme ziskali rovnice geodetiky

- Homogenní přímocný pohyb:

$$a^\alpha = 0 \rightarrow \frac{d^2 x^\alpha}{d\tau^2} + \Gamma^\alpha_{\beta\gamma} \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau} = 0 \text{ (čámpodobný pohyb)}$$



$$\tau_{AB} = \int_A^B d\tau, \quad ds^2 = -c^2 d\tau^2$$

geometrizované jednotky: $c=1, G=1$

Variace:

Variace

$$\delta \tau_{AB} = \int_A^B \delta \sqrt{-g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}} = \int_A^B \frac{-g_{\mu\nu, \rho} \delta x^\rho \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} - 2g_{\mu\nu} \frac{d\delta x^\mu}{d\tau} \frac{dx^\nu}{d\tau}}{2\sqrt{-g_{\mu\nu} \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau}}} d\tau =$$

$$= \int_A^B \left(-\frac{1}{2} g_{\mu\nu, \rho} \delta x^\rho \frac{dx^\mu}{d\tau} \frac{dx^\nu}{d\tau} - \frac{d\delta x^\mu}{d\tau} \frac{dx^\nu}{d\tau} g_{\mu\nu} \right) d\tau \stackrel{P.P.}{=}$$

$$= \int_A^B \left[-\frac{1}{2} g_{\mu\nu, \rho} \delta x^\rho u^\mu u^\nu + \frac{d}{d\tau} (g_{\mu\nu} u^\nu) \delta x^\mu \right] d\tau =$$

$$\int_A^B \frac{d}{d\tau} (g_{\mu\nu} u^\nu) \delta x^\mu d\tau$$

$$= \int_A^B \left(-\frac{1}{2} g_{\mu\nu, \rho} u^\mu u^\nu + g_{\rho\nu, \mu} u^\mu u^\nu + g_{\rho\nu} \frac{du^\nu}{d\tau} \right) \delta x^\rho d\tau =$$

$$= \int_A^B \left(-\frac{1}{2} g_{\mu\nu, \rho} + \frac{1}{2} g_{\rho\nu, \mu} + \frac{1}{2} g_{\rho\mu, \nu} \right) u^\mu u^\nu + g_{\rho\nu} \frac{du^\nu}{d\tau} \delta x^\rho d\tau =$$

$$= \int_A^B \left(g_{\rho\nu} \frac{du^\nu}{d\tau} + \frac{1}{2} \Gamma_{\mu\nu}^\alpha u^\mu u^\nu \right) \delta x^\rho d\tau =$$

$$= \int_A^B \left(g_{\rho\alpha} \frac{du^\alpha}{d\tau} + g_{\rho\alpha} \Gamma_{\mu\nu}^\alpha u^\mu u^\nu \right) \delta x^\rho d\tau =$$

$$= \int_A^B g_{\rho\alpha} \left(\frac{du^\alpha}{d\tau} + \Gamma_{\mu\nu}^\alpha u^\mu u^\nu \right) \delta x^\rho d\tau = 0 \Leftrightarrow \text{geodetika}$$

+ počáteční podmínky $x^\mu(p=p_0)$, $\frac{dx^\mu}{dp}(p=p_0)$

+ "okrajová podmínka" $g_{\mu\nu} \frac{dx^\mu}{dp} \frac{dx^\nu}{dp} \stackrel{?}{\leq} 0$

(N₂) afiniu' parametrizace geodetiky:

Re geodetiky: $\frac{dx^\alpha}{dp^2} + \Gamma^\alpha_{\alpha\beta} \frac{dx^\alpha}{dp} \frac{dx^\beta}{dp} = 0$

$p \rightarrow q(p)$:

$$\frac{d}{dp} \left(\frac{dx^\alpha}{dq} \frac{dq}{dp} \right) + \Gamma^\alpha_{\alpha\beta} \frac{dx^\alpha}{dq} \frac{dq}{dp} \frac{dx^\beta}{dq} \frac{dq}{dp} = 0$$

$$\frac{d^2 x^\alpha}{dq^2} \left(\frac{dq}{dp} \right)^2 + \frac{dx^\alpha}{dq} \frac{d^2 q}{dp^2} + \Gamma^\alpha_{\alpha\beta} \frac{dx^\alpha}{dq} \frac{dx^\beta}{dq} \left(\frac{dq}{dp} \right)^2 = 0$$

$$\rightarrow \frac{d^2 x^\alpha}{dq^2} + \Gamma^\alpha_{\alpha\beta} \frac{dx^\alpha}{dq} \frac{dx^\beta}{dq} = - \frac{dx^\alpha}{dq} \frac{d^2 q}{dp^2} \left(\frac{dq}{dp} \right)^2 = 0$$

↑
pro afinu' parametrizace
(linearu' transformace parametru)

Kleboňová

• Newtonovská limita rovnice geodetiky

1) „slabé gravitační pole“

$O(h^2)$

$$g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}, |h_{\mu\nu}| \ll 1 \text{ včetně derivací}$$

$$g^{\mu\nu} = \eta^{\mu\nu} - h^{\mu\nu}$$

$$\begin{aligned} \sigma^\alpha_\mu &= g_{\mu\nu} g^{\nu\alpha} = (\eta_{\mu\nu} + h_{\mu\nu})(\eta^{\nu\alpha} + h^{\nu\alpha}) = \\ &= \delta^\alpha_\mu - \eta_{\mu\nu} h^{\nu\alpha} + \eta^{\nu\alpha} h_{\mu\nu} + O(h^2) \end{aligned}$$

$$\rightarrow \eta_{\mu\nu} h^{\nu\alpha} = \eta^{\nu\alpha} h_{\mu\nu} \quad / \eta^{\alpha\mu}$$

$$\rightarrow h^{\alpha\beta} = \eta^{\alpha\mu} \eta^{\nu\beta} h_{\mu\nu}$$

④ Christoffelovy symboly

$$\Gamma^\mu_{\alpha\beta} = \frac{1}{2} g^{\mu\sigma} (g_{\sigma\alpha,\beta} + g_{\sigma\beta,\alpha} - g_{\alpha\beta,\sigma}) = \frac{1}{2} \eta^{\mu\sigma} (h_{\sigma\alpha,\beta} + h_{\sigma\beta,\alpha} - h_{\alpha\beta,\sigma})$$

② Pomalý pohyb

$$| \frac{dx^i}{dt} | \ll 1 \equiv c$$

$$\rightarrow | \frac{dt}{dx} | \rightarrow | \frac{dx^i}{dx} | \ll | \frac{dt}{dx} |, | \dot{x}^i | \ll | \dot{t} |$$

③ Stacionární pole / metrika

$$g_{\mu\nu,0} = 0, \text{ tj. } h_{\mu\nu,0} = 0$$

$$\frac{d^2 x^\alpha}{d\tau^2} + \Gamma_{\alpha\beta}^{\gamma} \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau} = 0$$

$$\Gamma_{\alpha\beta}^{\gamma} \left(\frac{dt}{d\tau} \right)^2 + 2 \Gamma_{\alpha\beta}^{\gamma} \frac{dt}{d\tau} \frac{dx^\beta}{d\tau} + \Gamma_{\beta\gamma}^{\alpha} \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau}$$

$$\Gamma_{\alpha\beta}^{\gamma} = \frac{1}{2} g^{\alpha\gamma} (h_{\beta\alpha,0} + h_{\alpha\beta,0} - h_{00,\alpha}) = -\frac{1}{2} h_{00,\alpha}$$

$$\rightarrow \left[\frac{d^2 x^\alpha}{d\tau^2} - \frac{1}{2} h_{00,\alpha} \left(\frac{dt}{d\tau} \right)^2 = 0 \right] \text{ Newtonsche's limit}$$

$$\text{Newton: } \frac{d^2 x^i}{dt^2} = -\Phi''$$

$$\mu=0: \frac{d^2 t}{d\tau^2} = 0, \Gamma_{\alpha\beta}^0 = 0$$

$$\frac{dt}{d\tau} = \text{konst}$$

$$\mu=i: \frac{d^2 x^i}{d\tau^2} - \frac{1}{2} h_{00,i} \left(\frac{dt}{d\tau} \right)^2 = 0$$

$$\frac{d}{d\tau} \left(\frac{dx^i}{dt} \frac{dt}{d\tau} \right) = \frac{d^2 x^i}{dt^2} \left(\frac{dt}{d\tau} \right)^2 + \underbrace{\frac{dx^i}{dt} \frac{d^2 t}{d\tau^2}}_0$$

$$\rightarrow \frac{d^2 x^i}{dt^2} - \frac{1}{2} h_{00,i} = 0 \rightarrow \Phi \quad \boxed{h_{00} = -2\Phi + C}$$

$$\boxed{g_{00} = -1 - 2\Phi}$$

$$\text{ne sondernh'ch polwelloch: } g_{00} = -1 - \frac{2\Phi}{c^2}$$

Γ^T - "insensitiv" Φ

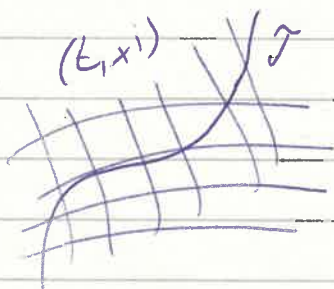
(Gloska)

- Dilataci času a posun frekvence ~ grav. pole

$$\text{dilatace: } d\tau = \sqrt{-ds^2} = \sqrt{-g_{\mu\nu} dx^\mu dx^\nu} =$$

$$= \sqrt{g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}} dt =$$

$$= \sqrt{g_{00} - 2g_{0i} \frac{dx^i}{dt} - g_{ij} \frac{dx^i}{dt} \frac{dx^j}{dt}}$$



$$v^i = 0: d\tau = \sqrt{-g_{00}} dt$$

$$\text{STR: } d\tau = \sqrt{1-v^2} dt$$

Posun frekvence:

$$\frac{\nu_B}{\nu_A} = \frac{\frac{d\tau_B}{dt_B}}{\frac{d\tau_A}{dt_A}} = \sqrt{\frac{-g_{00}(A)}{-g_{00}(B)}} \frac{dt_A}{dt_B}$$

$v^i = 0$ na A, B

$$0 = ds^2 = g_{\mu\nu} dx^\mu dx^\nu = g_{00} dt^2 + 2g_{0i} dt dx^i - g_{ij} dx^i dx^j$$

$$\text{čas } t_{AB} = \int_A^B dt = \int_A^B \frac{-g_{0i} dx^i \pm \sqrt{(g_{0i} dx^i)^2 - g_{00} g_{ij} dx^i dx^j}}{g_{00}}$$

kdymozlovici' na t?

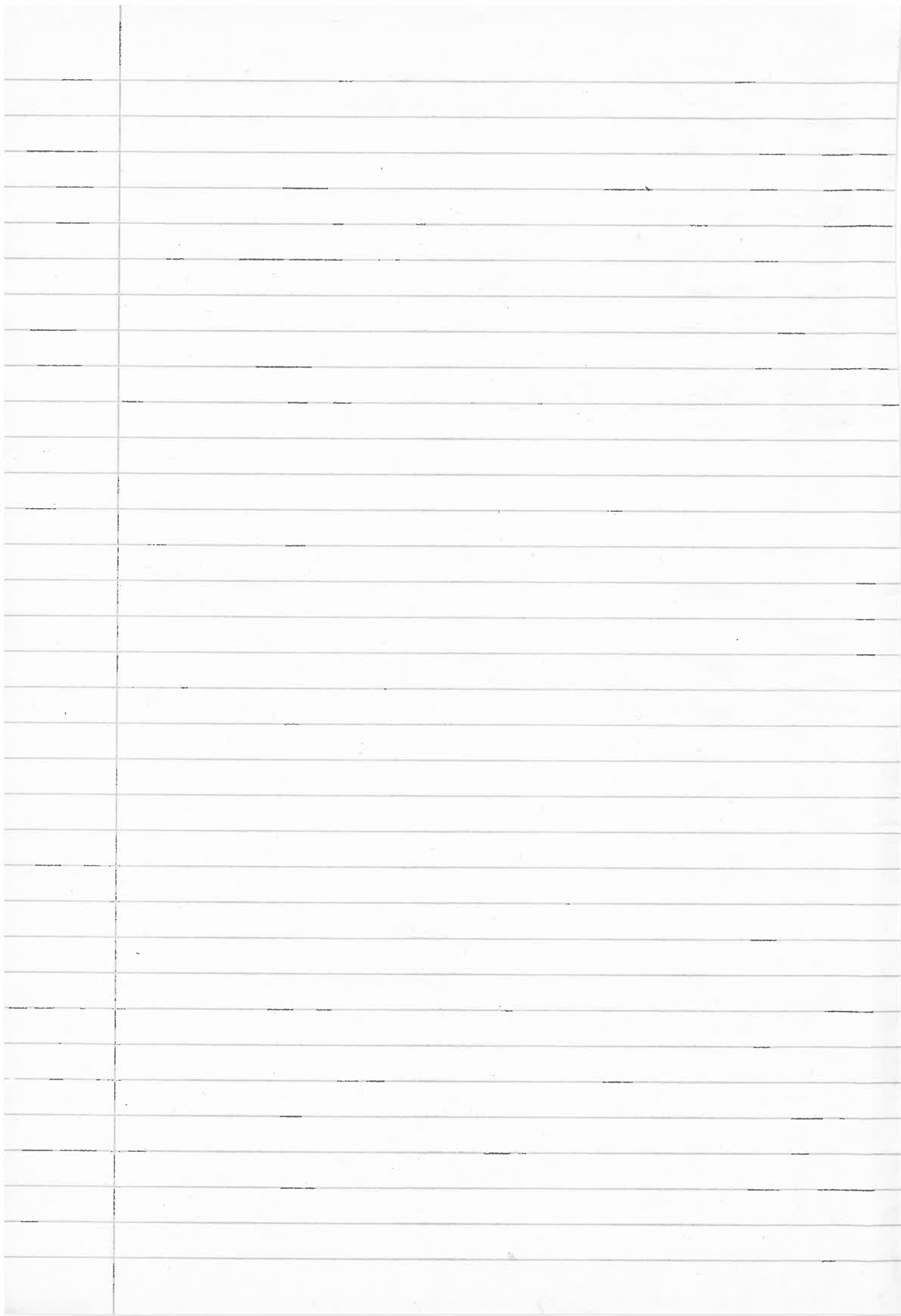
$$\text{pokud } g_{\mu\nu,0} = 0$$

$$\frac{v_B}{v_A} = \sqrt{\frac{-g_{00}(A)}{-g_{00}(B)}} \text{ po stacionarni metriki}$$

Newtonovski limita:

$$\frac{v_B}{v_A} = \sqrt{\frac{1+2\Phi_A}{1+2\Phi_B}} \approx 1 + \Phi_A - \Phi_B$$

$$\frac{\Delta v}{v_A} := \frac{v_B - v_A}{v_A} = \Phi_A - \Phi_B$$



4. přednáška (Geodetiky)

Opakování: paralelní přenos ~ zachování'm postročení

Při paralelním přenosu se zachováno následující výraz:

$$\frac{d}{dp} (g_{\mu\nu} V^\mu W^\nu) = 0$$

→ speciálně pro $\frac{d}{dp} (g_{\mu\nu} V^\mu V^\nu) = 0$

U paralelní přenos zachováno časoprostorová charakteristika

$$\boxed{\frac{dV^\mu}{dp} + \Gamma_{\rho\sigma}^{\mu} V^\rho \frac{dx^\sigma}{dp} = 0}$$

Nová tenzor
(stejná afinní konexe)

Geodetiky:

Základní vlastnosti:

① "Nejpřímější křivky"

P.D pro $V^\mu = \frac{dx^\mu}{dp}$ $\frac{dV^\mu}{dp} = \frac{d^2 x^\mu}{dp^2} + \Gamma_{\rho\sigma}^{\mu} \frac{dx^\rho}{dp} \frac{dx^\sigma}{dp} = 0 \quad \left| \frac{dx^\mu}{dp} \right|_{p=p_0} = \frac{dx^\mu}{dp} \Big|_{p=p_0}$

② Sřetocary volných testovacích částic

P. Equivalence $\rightarrow$ LIS $a^\alpha = \frac{d^2 \xi^\alpha}{d\tau^2} = 0$

$$\frac{d}{d\tau} \left(\frac{\partial \xi^\alpha}{\partial x^\rho} \frac{\partial x^\rho}{\partial \tau} \right) = \frac{\partial \xi^\alpha}{\partial x^\rho} \frac{\partial^2 x^\rho}{\partial \tau^2} + \frac{\partial^2 \xi^\alpha}{\partial x^\rho \partial x^\sigma} \frac{\partial x^\rho}{\partial \tau} \frac{\partial x^\sigma}{\partial \tau} = 0 \quad \left| \frac{\partial x^\mu}{\partial \xi^\alpha} \right|$$

Chceme "zerobodit"

$\rightarrow \frac{\partial^2 x^\mu}{\partial \tau^2} + \Gamma_{\rho\sigma}^{\mu} \frac{\partial x^\rho}{\partial \tau} \frac{\partial x^\sigma}{\partial \tau} = 0$

Geodetika je zachováva' časoprostorový charakter

Pomocí čtyřrychlostí:

$$\frac{dx^\mu}{d\tau} + \Gamma^\mu_{\rho\sigma} u^\rho u^\sigma = 0$$

Geometrizované' jednání:

$$C \equiv 1, G \equiv 1$$

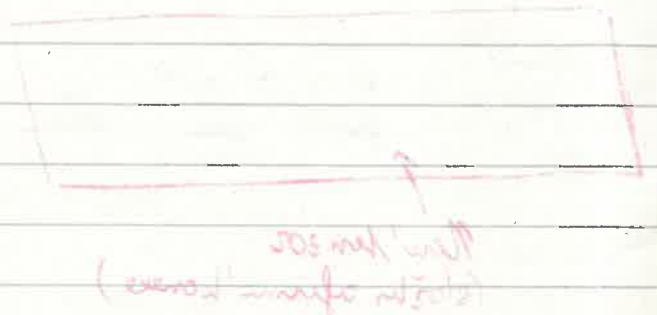
$$g_{\mu\nu} u^\mu u^\nu = -c^2 = -1$$

③ vlastnost geodetiky:
extremální a postarocase



$$x_{AB} = \int_A^B d\tau \rightarrow \delta x_{AB} = \int_A^B \delta d\tau$$

$$\delta d\tau = \delta \sqrt{-g_{\mu\nu} dx^\mu dx^\nu} = \frac{1}{2} \frac{\delta g_{\mu\nu} dx^\mu dx^\nu}{\sqrt{-g_{\mu\nu} dx^\mu dx^\nu}}$$



"libodono, eme" 

3. vlastnost geodetiky:
Geodetika je extremála ~ postarocasi



Buho urašujeme časopodobno' geodetiku

$$\mathcal{T}_{AB} = \int_A^B d\mathcal{T}_{AB} \rightarrow \delta \mathcal{T}_{AB} = \int_A^B \delta d\mathcal{T}_{AB}$$

$$\begin{aligned} \delta d\mathcal{T}_{AB} &= \delta \sqrt{-g_{\mu\nu} dx^\mu dx^\nu} = \frac{1}{2} \frac{1}{\sqrt{-g_{\mu\nu} dx^\mu dx^\nu}} (-g_{\mu\nu, \rho} dx^\rho dx^\mu dx^\nu - 2g_{\mu\nu} dx^\mu dx^\nu) = \\ &= \frac{1}{2} \frac{-g_{\mu\nu, \rho} dx^\rho dx^\mu dx^\nu - 2g_{\mu\nu} dx^\mu dx^\nu}{\sqrt{-g_{\mu\nu} dx^\mu dx^\nu}} d\mathcal{T} = \\ &= \left(\frac{1}{2} g_{\mu\nu, \rho} u^\mu u^\nu dx^\rho - g_{\mu\nu} u^\mu \frac{dx^\nu}{d\mathcal{T}} \right) d\mathcal{T} \end{aligned}$$

$$\begin{aligned} \rightarrow \delta \mathcal{T}_{AB} &= \int_A^B \left[-\frac{1}{2} g_{\mu\nu, \rho} u^\mu u^\nu + \frac{d}{d\mathcal{T}} (g_{\mu\nu} u^\nu) \right] dx^\rho d\mathcal{T} = \\ &= \int_A^B \left(-\frac{1}{2} g_{\mu\nu, \rho} u^\mu u^\nu + g_{\rho\nu} u^\nu + g_{\mu\nu} \frac{du^\nu}{d\mathcal{T}} \right) dx^\rho d\mathcal{T} = (*) \end{aligned}$$

$$\begin{aligned} -\frac{1}{2} g_{\mu\nu, \rho} u^\mu u^\nu + g_{\rho\nu} u^\nu &= -\frac{1}{2} g_{\mu\nu, \rho} u^\mu u^\nu + \frac{1}{2} g_{\rho\nu, \mu} u^\mu u^\nu + \frac{1}{2} g_{\rho\mu, \nu} u^\mu u^\nu = \\ &= \frac{1}{2} (-g_{\mu\nu, \rho} + g_{\rho\nu, \mu} + g_{\rho\mu, \nu}) u^\mu u^\nu = \Gamma_{\rho\mu\nu} u^\mu u^\nu \end{aligned}$$

Bu pomenut'.

Každy' tenzor lze rozložit na symetrickou a antisymetrickou část:

$$T^{\mu\nu} = \frac{1}{2} (T^{\mu\nu} + T^{\nu\mu}) + \frac{1}{2} (T^{\mu\nu} - T^{\nu\mu}) \wedge S^{\mu\nu} A_{\mu\nu}$$

$$*) = \int_A^B g_{\rho\alpha} \left(\frac{du^\alpha}{d\mathcal{T}} + \Gamma_{\mu\nu}^\alpha u^\mu u^\nu \right) dx^\rho d\mathcal{T} = 0$$

$$*) \Gamma_{\rho\mu\nu} = g_{\rho\alpha} \Gamma_{\mu\nu}^\alpha \rightarrow \frac{du^\alpha}{d\mathcal{T}} + \Gamma_{\mu\nu}^\alpha u^\mu u^\nu = 0$$

Geodetický jevištedy zobecněním přímku do křivekho prostoru

Neafinní parametrizace (rovnic geodetický)

$$p \rightarrow q(p) : \underbrace{\frac{dx^\alpha}{dp^2}}_I + \Gamma_{\beta\alpha}^{\gamma} \underbrace{\frac{dx^\beta}{dp} \frac{dx^\alpha}{dp}}_{II} = 0$$

$$I = \frac{d}{dp} \left(\frac{dx^\alpha}{dq} \frac{dq}{dp} \right) = \frac{dx^\alpha}{dq} \frac{dq^2}{dp^2} + \frac{dx^{\alpha 2}}{dq^2} \left(\frac{dq}{dp} \right)^2$$

$$II = \frac{dx^\beta}{dq} \frac{dx^\alpha}{dq} \left(\frac{dq}{dp} \right)^2$$

$$\rightarrow \frac{dx^{\alpha 2}}{dq^2} \left(\frac{dq}{dp} \right)^2 + \frac{dx^\alpha}{dq} \frac{dq^2}{dp^2} + \Gamma_{\beta\alpha}^{\gamma} \frac{dx^\beta}{dq} \frac{dx^\alpha}{dq} \left(\frac{dq}{dp} \right)^2$$

$$\frac{dx^{\alpha 2}}{dq^2} + \Gamma_{\beta\alpha}^{\gamma} \frac{dx^\beta}{dq} \frac{dx^\alpha}{dq} = - \left(\frac{dp}{dq} \right)^2 \frac{dq^2}{dp^2} \frac{dx^\alpha}{dq}$$

Obečny' hron rovnice geodetický, po neafinní parametrizaci

$$g_{\mu\nu} \frac{dx^\mu}{ds} \frac{dx^\nu}{ds} = 1 \quad (*)$$

Newtonovská limita (geodetiky)

Předpoklady pro řešení:

① $g_{\mu\nu} = \eta_{\mu\nu} + h_{\mu\nu}$, $|h_{\mu\nu}| \ll 1$ a derivujeme

$$g^{\alpha\beta} = \eta^{\alpha\beta} - h^{\alpha\beta}$$

$$\& g_{\mu\alpha} g^{\alpha\beta} = (\eta_{\mu\alpha} + h_{\mu\alpha})(\eta^{\alpha\beta} - h^{\alpha\beta}) = \delta_{\mu}^{\beta} + h^{\beta}_{\mu} - h^{\beta}_{\mu} + O(h^2) = \delta_{\mu}^{\beta}$$

tj. předpoklad slabého grav. pole

$$\begin{aligned} \Gamma^{\alpha}_{\beta\gamma} &= \frac{1}{2} (\eta^{\alpha\mu} - h^{\alpha\mu}) (h_{\mu\beta,\gamma} + h_{\mu\gamma,\beta} - h_{\beta\gamma,\mu}) = \\ &= \frac{1}{2} \eta^{\alpha\mu} (h_{\mu\beta,\gamma} + h_{\mu\gamma,\beta} - h_{\beta\gamma,\mu}) \approx O(h) \end{aligned}$$

② předpoklad pomalého pohybu:

$$\left| \frac{dx^i}{d\tau} \right| \ll \left| \frac{dt}{d\tau} \right| \Leftrightarrow \left| \frac{dx^i}{dt} \right| \left| \frac{dt}{d\tau} \right| \ll \left| \frac{dt}{d\tau} \right| \Leftrightarrow \left| \frac{dx^i}{dt} \right| \ll 1 = c$$

Rovnice geodetiky: $\frac{dx^{\alpha}}{d\tau^2} + \Gamma^{\alpha}_{\beta\gamma} \frac{dx^{\beta}}{d\tau} \frac{dx^{\gamma}}{d\tau} = 0$

$$\frac{dx^{\alpha}}{d\tau^2} + \Gamma^{\alpha}_{00} \left(\frac{dt}{d\tau} \right)^2 + 2 \cancel{\Gamma^{\alpha}_{0j} \frac{dt}{d\tau} \frac{dx^j}{d\tau}} + \cancel{\Gamma^{\alpha}_{jj} \frac{dx^j}{d\tau} \frac{dx^j}{d\tau}} = 0$$

tyto členy lze zanedbat

③ Dále předpokládáme stacionární pole: $g_{\mu\nu,0} = 0$

$$\rightarrow \Gamma^{\alpha}_{00} = \frac{1}{2} \eta^{\alpha\mu} (\cancel{h_{\mu 0,0}} + \cancel{h_{0\mu,0}} - h_{00,\mu}) = -\frac{1}{2} h_{00,\alpha}$$

Získáme tedy rovnici:

$$\frac{dx^{\alpha 2}}{d\tau^2} - \frac{1}{2} h_{00, i} \left(\frac{dx^i}{d\tau} \right)^2 = 0$$

$$\mu=0: \frac{dt^2}{d\tau^2} = 0 \rightarrow \frac{dt}{d\tau} = \text{konst.}$$

$$\mu=i: \underbrace{\frac{dx^{i 2}}{d\tau^2}}_A - \frac{1}{2} h_{00, i} \left(\frac{dx^i}{d\tau} \right)^2 = 0$$

$$A = \frac{d}{d\tau} \left(\frac{dx^i}{d\tau} \frac{dt}{d\tau} \right) = \frac{dx^i}{dt^2} \left(\frac{dt}{d\tau} \right)^2 + \underbrace{\frac{dx^i}{dt} \frac{dt^2}{d\tau^2}}_0$$

$$\rightarrow \frac{dx^i}{dt^2} = \frac{1}{2} h_{00, i}$$

Kam můžeme?

Podle Newtona: $\frac{dx^i}{dt^2} = -\Phi_{, i}$

a tedy $h_{00} = -2\Phi + \text{konst}$
volba $k=0$

$$\rightarrow g_{00} = -1 - 2\Phi$$

V jednotkách SI: $g_{00} = -1 - \frac{2\Phi}{c^2}$

Analogie:

Metrika odpovídá grav. potenciálu

Christoffelovy symboly odpovídají intenzitě grav. pole

5. přednáška

Dilatace času a posun frekvence v gravitačním poli

$$d\tau^2 = -ds^2$$

$$\rightarrow d\tau = \sqrt{-g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}} dt$$

$$\text{STR: } g_{\mu\nu} = \eta_{\mu\nu} \rightarrow d\tau = \sqrt{\eta_{00} - \eta_{ij} v^i v^j} dt = \sqrt{1 - v^2} dt$$

jestliže $v=0$, pak $d\tau = dt$ (STR!)
neplatí v OTR!

předpokládáme, že jsme v OTR a $v=0$:

$$\frac{dx^i}{dt} = 0 \rightarrow d\tau = \sqrt{-g_{00}} dt, \text{ kde } g_{00} = g_{00}(x, y, z)$$

Posun frekvence: 

$$\frac{\nu_B}{\nu_A} = \frac{d\tau_A}{d\tau_B} = \sqrt{\frac{-g_{00}(A)}{-g_{00}(B)}} \frac{dt_A}{dt_B}$$

$$t_{AB} = \int_A^B dt \dots t_{AB}(\text{~~z~~}), \text{ kde } z \text{ je doba, "lehn" nerovnosti na čase.}$$

$$0 = ds^2 = g_{\mu\nu} dx^\mu dx^\nu = g_{00} dt^2 + 2g_{0j} dt dx^j + g_{ij} dx^i dx^j$$

$$dt = \frac{-2g_{0j} dx^j \pm \sqrt{(2g_{0j} dx^j)^2 - g_{00} g_{ij} dx^i dx^j}}{2g_{00}}$$

$\rightarrow t_{AB}$ je nerovnosti na čase, jestliže $\boxed{g_{\mu\nu,0} = 0}$

$$\text{pak lze psát: } \frac{\nu_B}{\nu_A} = \frac{d\tau_A}{d\tau_B} = \sqrt{\frac{-g_{00}(A)}{-g_{00}(B)}}, \text{ tj. } \frac{dt_A}{dt_B} = 1$$

Newtonovska' limita :

$$h_{00} = g_{00} = -1 - 2\Phi$$

$$\rightarrow \frac{v_B}{v_A} = \frac{\sqrt{1+2\Phi_A}}{\sqrt{1+2\Phi_B}} = \frac{1+\Phi_A}{1+\Phi_B} = (1+\Phi_A)(1-\Phi_B) =$$

$$= 1 + \Phi_A - \Phi_B + O(\Phi^2)$$

$$\boxed{\frac{\Delta v}{v_A} = \frac{v_B - v_A}{v_A} = \Phi_A - \Phi_B}$$

Příklady:

Sféricky symetrické pole:

$$\Phi = -\frac{GM}{c^2 R}$$

$$\frac{\Delta v}{v_A} = \Phi_A - \Phi_B (R \rightarrow \infty) = -\frac{GM}{c^2 R}$$

Homogenní grav. pole:

$$\Phi = \frac{g \Delta l}{c^2}$$

$$\frac{\Delta v}{v_A} = \frac{-g \Delta l}{c^2}, \Delta l = l_B - l_A$$

interice:

$$h v_B = h v_A + \Delta E_{\text{potenciální}} \sim \text{grav. pole} \\ - \frac{h v_A}{c^2} g \Delta l, v_B = v_A \left(1 - \frac{g \Delta l}{c^2}\right)$$



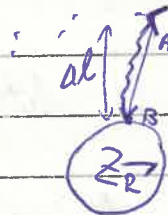
$$ct_{AB} = \Delta l + \frac{1}{2} g t_{AB}^2$$

$$\rightarrow t_{AB} = \frac{\Delta l}{c}, \quad \alpha = g t_{AB} = \frac{g \Delta l}{c}$$

$$\text{Doppler: } \nu_B = \nu_A (1 - \alpha) = \nu_A \left(1 - \frac{g \Delta l}{c^2}\right)$$

Případ s obíhajícím satelitem

$$\frac{\nu_B}{\nu_A} = \frac{\sqrt{(-g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt})_A}}{\sqrt{-g_{00}(B)}}$$



Newtonovská limita: $O(\Phi^2)$ $O(\Phi^2)$ $O(\Phi)$ $O(\Phi)$ $m \frac{v^2}{r} = \frac{GM}{r^2} m$ $v^2 = \frac{GM}{r} = -\Phi$ stabilní orbita

$$\frac{\nu_B}{\nu_A} = \frac{\sqrt{(-g_{00} - h_{00} - 2h_{0j}v^j - v^2 - h_{ij}v^i v^j)_A}}{\sqrt{g_{00} - h_{00}}}$$

$$= \frac{\sqrt{1 + 2\Phi_A + \Phi_A}}{\sqrt{1 + 2\Phi_B}} = \frac{1 + \frac{3}{2}\Phi_A}{1 + \Phi_B} = 1 + \frac{3}{2}\Phi_A - \Phi_B$$

Geometrická rovnost

$$\begin{aligned} \frac{\Delta \nu}{\nu_A} &= \frac{\nu_B - \nu_A}{\nu_A} = \frac{3}{2} \Phi_A - \Phi_B = -\frac{3}{2} \frac{GM}{R + \Delta l} + \frac{GM}{R} = \\ &= \frac{-3MR + 2MR + 2M\Delta l}{2R(R + \Delta l)} = \frac{-MR + 2M\Delta l}{2R(R + \Delta l)} \end{aligned}$$

$$\rightarrow \frac{\Delta \nu}{\nu_A} = -\frac{GM}{2R^2} \frac{R - 2\Delta l}{R + \Delta l}$$

pro $\Delta l = \frac{R}{2}$ je poměr nulový

Speciální případy:

$$\Delta l \rightarrow \infty \Rightarrow \frac{\Delta \nu}{\nu_A} = \frac{GM}{Rc^2}$$

$$\Delta l \rightarrow 0 \Rightarrow \frac{\Delta \nu}{\nu_A} = -\frac{GM}{2Rc^2}$$

přísol' gravitocíu' efekt společně s přechým
dopplerovým efektem

Pro $\Delta l = \frac{R}{2}$ se vyruší

Dilatace času a satelitní navigace:

$$\frac{\nu_B - \nu_A}{\nu_A} = -\frac{GM}{2Rc^2} \frac{R - 2\Delta l}{R + \Delta l}$$

$$\frac{\frac{1}{d\tilde{\nu}_B} - \frac{1}{d\tilde{\nu}_A}}{\frac{1}{d\tilde{\nu}_A}} = \frac{\frac{d\tilde{\nu}_A - d\tilde{\nu}_B}{d\tilde{\nu}_B d\tilde{\nu}_A}}{\frac{d\tilde{\nu}_B}{d\tilde{\nu}_A d\tilde{\nu}_B}} = \frac{d\tilde{\nu}_A - d\tilde{\nu}_B}{d\tilde{\nu}_A}$$

$$d\tilde{\nu}_A - d\tilde{\nu}_B = -\frac{GM}{2Rc^2} \frac{R - 2\Delta l}{R + \Delta l} d\tilde{\nu}_B$$

$\rightarrow 0$ pro $\Delta l > \frac{R}{2}$

$$1 \text{ den} = 86400 \text{ s} : |d\tilde{\nu}_A - d\tilde{\nu}_B| = (3 \cdot 10^{-5} \text{ s}) \left| \frac{R - 2\Delta l}{R + \Delta l} \right|$$

$$c |d\tilde{\nu}_A - d\tilde{\nu}_B| = 9 \text{ km} \left| \frac{R - 2\Delta l}{R + \Delta l} \right|$$

$$\text{pro } \Delta l = 20200 \text{ km} : c |d\tilde{\nu}_A - d\tilde{\nu}_B| = 11,52 \text{ km/den}$$

Kovariantní derivace (Ricci - Levi-Civita)

$$P.D.: \frac{dV^\mu}{dp} + \Gamma_{\rho\sigma}^\mu V^\rho \frac{dx^\sigma}{dp} = 0$$

Je-li V^μ definováno; mimo danou křivku,
necht' je to napříklod vektorové pole, pak lze psát:

$$\frac{dV^\mu}{dp} = \underbrace{V_{;\alpha}^\mu}_{\text{lineární tenzor!}} \frac{dx^\alpha}{dp}$$

4 rovnice pro P.D.:

$$\underbrace{\left(\frac{\partial V^\mu}{\partial x^\alpha} + \Gamma_{\rho\sigma}^\mu V^\rho \right)}_{\equiv V_{;\alpha}^\mu} \frac{dx^\alpha}{dp} = 0$$

Kovariantní derivace vektoru

Leibnitz:

$$(fV^\mu)_{;\alpha} \stackrel{?}{=} f_{;\alpha} V^\mu + f V_{;\alpha}^\mu = f_{;\alpha} V^\mu + f (V_{;\alpha}^\mu + \Gamma_{\rho\sigma}^\mu V^\rho)$$

$$(fV^\mu)_{;\alpha} = (fV^\mu)_{;\alpha} + \Gamma_{\rho\sigma}^\mu f V^\rho = f_{;\alpha} V^\mu + f V_{;\alpha}^\mu + \Gamma_{\rho\sigma}^\mu f V^\rho$$

P.D. pro kovektory:

$$\frac{dW_\alpha}{dp} - \Gamma_{\alpha\beta}^\sigma W_\sigma \frac{dx^\beta}{dp} = 0$$

$$\rightarrow \underbrace{(W_{\alpha;\beta} - \Gamma_{\alpha\sigma}^\sigma W_\sigma)}_{W_{\alpha;\beta}} \frac{dx^\beta}{dp} = 0$$

$W_{\alpha;\beta}$ Kovariantní derivace kovektoru

Analogicky pro obecný tenzor

Absolutní derivace:

Kovariantní derivace ve směru

Ynačin: D

$$\frac{DV^\alpha}{dp} = V^\alpha_{;\sigma} \frac{dx^\sigma}{dp} = \frac{dV^\alpha}{dp} + \Gamma^\alpha_{\sigma\rho} V^\rho \frac{dx^\sigma}{dp}$$

$$\frac{DW_\alpha}{dp} = W_{\alpha;\beta} \frac{dx^\beta}{dp} = \frac{dW_\alpha}{dp} - \Gamma^\sigma_{\alpha\beta} W_\sigma \frac{dx^\beta}{dp}$$

$$P.D.: \frac{DV^\alpha}{dp} = 0$$

$$R.G.: \frac{D^2 x^\mu}{dp^2} = 0$$

$$\text{Pro čaropodobné geodetiky: } \frac{D^2 x^\mu}{ds^2} = 0$$

$$\frac{d}{dp} (g_{\mu\nu} V^\mu W^\nu) = \frac{D}{dp} (g_{\mu\nu} V^\mu W^\nu) = 0$$

$$\begin{aligned} g_{\mu\nu;\sigma} &= g_{\mu\nu,\sigma} - \Gamma^\rho_{\mu\sigma} g_{\rho\nu} - \Gamma^\rho_{\nu\sigma} g_{\mu\rho} = \\ &= g_{\mu\nu,\sigma} - \Gamma_{\nu\mu\sigma} - \Gamma_{\mu\nu\sigma} = 0 \end{aligned}$$

Metrika je kovariantně konstantní

6. prednáška

Poznámka: Levi-Civita konexe

$$\nabla_X Y - \nabla_Y X = [X, Y] + T(X, Y)$$

Tensor torze

$$Y^\alpha{}_{;\sigma} X^\sigma - X^\alpha{}_{;\sigma} Y^\sigma = Y^\alpha{}_{;\sigma} X^\sigma - X^\alpha{}_{;\sigma} Y^\sigma + T^\alpha{}_{\sigma\alpha} X^\sigma Y^\alpha$$

$$\cancel{Y^\alpha{}_{;\sigma} X^\sigma} + \cancel{\Gamma^\alpha{}_{\sigma\alpha} Y^\sigma X^\sigma} - \cancel{X^\alpha{}_{;\sigma} Y^\sigma} - \cancel{\Gamma^\alpha{}_{\sigma\alpha} X^\sigma Y^\alpha} = \dots + T^\alpha{}_{\sigma\alpha} X^\sigma Y^\alpha$$

Nulová torze odhroďa symetrie složí afinné konexe

$$\forall X: \nabla_X g = 0 \quad | \quad g_{\mu\nu;\rho} = 0$$

$$X_{\mu;\rho} = (g_{\mu\alpha} X^\alpha)_{;\rho} = \underbrace{g_{\mu\alpha;\rho}}_{\neq 0} X^\alpha + g_{\mu\alpha} X^\alpha{}_{;\rho}$$

Krübst

$$V_{\mu;\lambda\lambda} - V_{\mu;\lambda\lambda} \equiv W_{\mu\lambda;\lambda} - W_{\lambda\mu;\lambda} =$$

$$= W_{\mu\lambda;\lambda} - \Gamma_{\lambda\lambda}^{\mu} W_{\rho\lambda} + \Gamma_{\lambda\lambda}^{\rho} W_{\rho\mu} - W_{\lambda\mu;\lambda} +$$

$$V_{\mu;\lambda\lambda} - V_{\mu;\lambda\lambda} \equiv W_{\mu\lambda;\lambda} - W_{\lambda\mu;\lambda} =$$

$$= W_{\mu\lambda;\lambda} - \Gamma_{\lambda\lambda}^{\mu} W_{\rho\lambda} - \Gamma_{\lambda\lambda}^{\rho} W_{\rho\lambda} -$$

$$- W_{\lambda\mu;\lambda} + \Gamma_{\lambda\lambda}^{\mu} W_{\rho\lambda} + \Gamma_{\lambda\lambda}^{\rho} W_{\rho\mu} =$$

$$= (V_{\mu;\lambda\lambda} - \Gamma_{\lambda\lambda}^{\mu} V_{\rho\lambda})_{;\lambda} - \Gamma_{\lambda\lambda}^{\rho} (V_{\rho;\lambda\lambda} - \Gamma_{\rho\lambda}^{\sigma} V_{\sigma}) -$$

$$- (V_{\lambda;\mu\lambda} - \Gamma_{\mu\lambda}^{\sigma} V_{\sigma})_{;\lambda} + \Gamma_{\mu\lambda}^{\rho} V_{\rho;\lambda\lambda} - \Gamma_{\mu\lambda}^{\sigma} V_{\sigma} =$$

=

Kürzest

$$V_{\nu;\lambda\lambda} - V_{\nu;\lambda\lambda} \equiv W_{\nu\lambda;\lambda} - W_{\nu\lambda;\lambda} =$$

$$= W_{\nu\lambda;\lambda} - \Gamma_{\nu\lambda}^{\sigma} W_{\sigma\lambda} - \Gamma_{\lambda\lambda}^{\sigma} W_{\nu\sigma} -$$

$$- W_{\nu\lambda;\lambda} + \Gamma_{\nu\lambda}^{\sigma} W_{\sigma\lambda} + \Gamma_{\lambda\lambda}^{\sigma} W_{\nu\sigma} =$$

$$= (\cancel{V_{\nu;\lambda}} - \Gamma_{\nu\lambda}^{\sigma} V_{\sigma})_{;\lambda} - \Gamma_{\nu\lambda}^{\sigma} (V_{\sigma\lambda} - \Gamma_{\sigma\lambda}^{\alpha} V_{\alpha}) -$$

$$- (\cancel{V_{\nu;\lambda}} - \Gamma_{\nu\lambda}^{\sigma} V_{\sigma})_{;\lambda} + \Gamma_{\nu\lambda}^{\sigma} (V_{\sigma\lambda} - \Gamma_{\sigma\lambda}^{\alpha} V_{\alpha}) =$$

$$= (\Gamma_{\nu\lambda;\lambda}^{\sigma} - \Gamma_{\nu\lambda;\lambda}^{\sigma} + \Gamma_{\nu\lambda}^{\sigma} \Gamma_{\sigma\lambda}^{\alpha} - \Gamma_{\nu\lambda}^{\sigma} \Gamma_{\sigma\lambda}^{\alpha}) V_{\alpha} = \boxed{R_{\nu\lambda\lambda}^{\sigma} V_{\sigma}}$$

Riemann'scher Tensor

Kovarianten Riemann'scher Tensor:

$$R_{\mu\nu\lambda\sigma} = g_{\mu\sigma} R^{\sigma}_{\nu\lambda\lambda} = \textcircled{\#} \leftarrow \begin{array}{l} \text{metrika neu' konstant!} \\ \text{ne'ci parc. derivaci} \end{array} \quad \begin{array}{l} \sigma \leftrightarrow \sigma \\ \lambda \leftrightarrow \lambda \end{array}$$

$$= \underbrace{\Gamma_{\mu\nu\lambda;\lambda}}_A - \underbrace{g_{\mu\sigma;\lambda} \Gamma_{\nu\lambda}^{\sigma}}_{C_1} - \underbrace{\Gamma_{\mu\nu\lambda;\lambda}}_B + \underbrace{g_{\mu\sigma;\lambda} \Gamma_{\nu\lambda}^{\sigma}}_{D_1} + \underbrace{\Gamma_{\mu\sigma\lambda} \Gamma_{\nu\lambda}^{\sigma}}_{C_2} - \underbrace{\Gamma_{\mu\sigma\lambda} \Gamma_{\nu\lambda}^{\sigma}}_{D_2} =$$

$$A = \frac{1}{2} (g_{\mu\nu;\lambda\lambda} + g_{\lambda\mu;\nu\lambda} - g_{\nu\lambda;\mu\lambda})$$

$$B = \frac{1}{2} (g_{\mu\lambda;\nu\lambda} + g_{\lambda\mu;\nu\lambda} - g_{\nu\lambda;\mu\lambda})$$

$$C_1 + C_2 = (-g_{\mu\sigma;\lambda} + \Gamma_{\mu\sigma\lambda}) \Gamma_{\nu\lambda}^{\sigma} = (-\Gamma_{\mu\sigma\lambda} - \Gamma_{\sigma\mu\lambda} + \Gamma_{\mu\sigma\lambda}) \Gamma_{\nu\lambda}^{\sigma}$$

$$D_1 + D_2 = (g_{\mu\sigma;\lambda} - \Gamma_{\mu\sigma\lambda}) \Gamma_{\nu\lambda}^{\sigma} = (\Gamma_{\mu\sigma\lambda} + \Gamma_{\sigma\mu\lambda} - \Gamma_{\mu\sigma\lambda}) \Gamma_{\nu\lambda}^{\sigma}$$

$$\Rightarrow R_{\mu\nu\lambda\sigma} = \frac{1}{2} (g_{\mu\lambda;\nu\sigma} + g_{\nu\lambda;\mu\sigma} - g_{\mu\sigma;\nu\lambda} - g_{\nu\sigma;\mu\lambda}) +$$

$$+ g_{\mu\sigma} (\Gamma_{\mu\lambda}^{\sigma} \Gamma_{\nu\lambda}^{\sigma} - \Gamma_{\mu\lambda}^{\sigma} \Gamma_{\nu\lambda}^{\sigma})$$

Symetrie Riemannova tenzoru:

- $R^\sigma_{\nu\mu\lambda}$

↑
Antisymetrie

- $R^\sigma_{[\nu\mu\lambda]} = R^\sigma_{\nu\mu\lambda} + R^\sigma_{\mu\lambda\nu} + R^\sigma_{\lambda\nu\mu} = 0 \quad (\neq)$
(1. Bianchiho identita)

- $R_{\mu\nu\lambda\sigma}$

↑
antisymetrie

- $R_{\mu\nu\lambda\sigma} = R_{\sigma\lambda\mu\nu}$

(tato symetrie nem' nero'vise' a plyne z

- $\epsilon^{\sigma\nu\mu\lambda} R_{\mu\nu\lambda\sigma} = 0 \quad (\neq)$
(taky' nem' nero'vise')

Kolik mo' Riemannův tenzor nero'visly'ch slo'žek?

$$R_{\mu\nu\lambda\sigma} \dots 6 \times 6 = 36$$

$$R_{\mu\nu\lambda\sigma} = 0 \dots 16$$

$$36 - 16 = 20$$

Obecný vztah pro počet nero'visly'ch slo'žek tenzoru
křivosti: $n = \frac{1}{12} d^2 (d^2 - 1)$, d je dimenze

2. Bianchova identita

Odhrovení:

$$\text{Ricci: } W_{\mu\nu;\alpha\beta} - W_{\mu\alpha;\beta\nu} = R^{\sigma}_{\mu\alpha\beta} W_{\sigma\nu} + R^{\sigma}_{\nu\alpha\beta} W_{\sigma\mu}$$

$$W_{\mu\nu} = V_{\nu;\mu}$$

$$V_{\mu;\alpha;\beta} - V_{\mu;\beta;\alpha} = R^{\sigma}_{\mu\alpha\beta} V_{\sigma} + R^{\sigma}_{\nu\alpha\beta} V_{\sigma;\mu} \quad (*)$$

Ricci po $V_{\nu;\mu}$:

$$V_{\nu;\alpha;\beta} - V_{\nu;\beta;\alpha} = R^{\sigma}_{\nu\alpha\beta} V_{\sigma} + R^{\sigma}_{\nu\alpha\beta} V_{\sigma;\mu} \quad (\#)$$

$$(\#) - (*) \div$$

$[\mu\alpha\beta]$ cykl.

$[\mu\alpha\beta]$ cykl.

$$V_{\nu;\alpha;\beta} - V_{\nu;\beta;\alpha} + V_{\nu;\beta;\alpha} - V_{\nu;\alpha;\beta} = 0$$

liši se sudou permutací

liši se sudou permutací

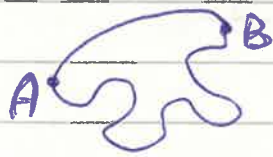
Prostě se vždy počtou členy liši se sudou permutací, takže cyklickým posčením indexů vzniknou ty samé členy a odečtení se

$$\rightarrow R^{\sigma}_{\nu[\mu\alpha\beta]} = 0$$

Geometrický význam Riemannova tenzoru křivosti

Obecné podmínky integrability:

$$dT^{\dots} = f^{\dots} p dx^p$$



$$T^{\dots}(B) = T^{\dots}(A) + \int_A^B f^{\dots} p dx^p$$

$$\oint f^{\dots} p dx^p \stackrel{?}{=} 0$$

↑ křivost? = 0



Stokes:

Paž přenos nesouvisí na křivce

$$\oint_{\gamma} f^{\dots} p dx^p = \iint_S f^{\dots} p (\underbrace{d_{(1)} x^p d_{(2)} x^q}_{ds^{pq} \text{ antisymetrické}}) =$$

$$= \iint_S (f^{\dots} p \sigma - f^{\dots} \sigma p) d_{(1)} x^p d_{(2)} x^q = (*)$$

↑ nerobí se a jede se oběma směry a neantisymetizace

$$(*) = 0 \Leftrightarrow f^{\dots} p \sigma = f^{\dots} \sigma p$$

Příklad:

$$dA = \vec{f} \cdot d\vec{r} = f_i dx^i$$

$$\rightarrow \oint f_i dx^i = 0 \Leftrightarrow f_{i,j} = f_{j,i} \Leftrightarrow \text{nat } \vec{f} = \vec{0}$$

$$\cdot \text{Pfaffovy formy, } d\theta, ds = \frac{d\theta}{T}$$

• souřadnicová transformace

$$dx^\mu = \frac{\partial x^\mu}{\partial x^\nu} dx^\nu$$

$$f^\mu_\nu \cdot \frac{\partial x^\mu}{\partial x^\alpha} \frac{\partial x^\alpha}{\partial x^\nu} = f^\mu_{\alpha,\nu} = f^\mu_{\alpha,\nu}$$

$$\Leftrightarrow \frac{\partial^2 x^\mu}{\partial x^\alpha \partial x^\nu} = \frac{\partial^2 x^\mu}{\partial x^\nu \partial x^\alpha}$$

Integrabilita P.P.:

$$\frac{dV^\mu}{dp} + \Gamma^\mu_{\sigma\rho} V^\sigma \frac{dx^\rho}{dp} = 0$$

$$dV^\mu + \Gamma^\mu_{\sigma\rho} V^\sigma dx^\rho = 0$$

$$(V^\mu_{,\sigma} + \Gamma^\mu_{\sigma\rho} V^\rho) dx^\sigma = 0$$

0, pokud to má platit po všech γ

γ : n dráha předchozích úvah:

$$f^\mu_{,\sigma} = -\Gamma^\mu_{\sigma\rho} V^\rho$$

$$f^\mu_{\sigma,\epsilon} = f^\mu_{\epsilon,\sigma} :$$

$$\Gamma^\mu_{\sigma\epsilon,\rho} V^\rho + \Gamma^\mu_{\sigma\rho,\epsilon} V^\rho = \Gamma^\mu_{\epsilon,\sigma,\rho} V^\rho + \Gamma^\mu_{\epsilon\rho,\sigma} V^\rho$$

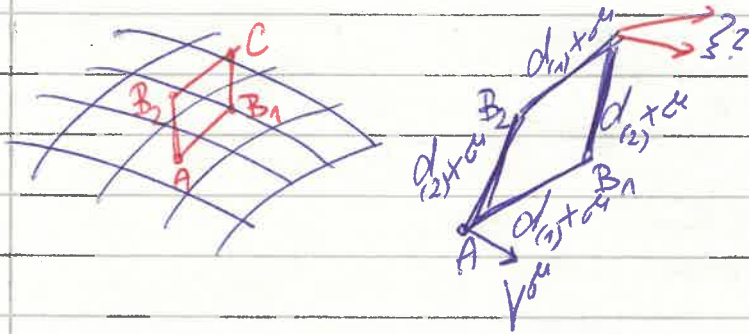
$$\Gamma^\mu_{\sigma\epsilon,\rho} V^\rho + \Gamma^\mu_{\sigma\rho,\epsilon} V^\rho = \Gamma^\mu_{\epsilon,\sigma,\rho} V^\rho + \Gamma^\mu_{\epsilon\rho,\sigma} V^\rho$$

$$(\Gamma^\mu_{\sigma\epsilon,\rho} - \Gamma^\mu_{\epsilon,\sigma,\rho} + \Gamma^\mu_{\sigma\rho,\epsilon} - \Gamma^\mu_{\epsilon\rho,\sigma}) V^\rho = 0$$

$$\rightarrow R^\mu_{\sigma\epsilon\rho} V^\rho = 0 \rightarrow R^\mu_{\sigma\epsilon\rho} = 0$$

7. přednáška

Integrabilità P.D. (godrudo')



$$\left. \begin{aligned} d_{(1)}^* x^{\mu}(B_2) &= d_{(1)}^* x^{\mu}(A) + O(d^2) \\ d_{(2)}^* x^{\mu}(B_1) &= d_{(2)}^* x^{\mu}(A) + O(d^2) \end{aligned} \right\} (*)$$

$$V^u(A \rightarrow B_1)$$

$$dV^4 = - \Gamma^4_{\alpha\beta\gamma} V^\alpha d\tau^\beta d\tau^\gamma$$

$$\rightarrow V^{\mu}(A \rightarrow Z_1) = V^{\mu} - \Gamma^{\mu}_{\rho\alpha} V^{\rho} d_{(1)}^{\alpha} + \alpha(A)$$

$$\begin{aligned} V^{\mu\mu}(A \rightarrow B_1 \rightarrow C) &= V^{\mu\mu}(A \rightarrow B_1) - \Gamma_{\mu\mu}^{\mu\mu} V^{\mu\mu}(B_1) V^{\mu\mu}(A \rightarrow B_1) d_{(2)} x^{\mu}(B_1) = \\ &= V^{\mu\mu} - \Gamma_{\mu\mu}^{\mu\mu} V^{\mu\mu} d_{(1)} x^{\mu}(A) - \left(\Gamma_{\mu\mu}^{\mu\mu} + \Gamma_{\mu\mu, \mu\mu}^{\mu\mu} d_{(1)} x^{\mu} \right) (V^{\mu\mu} - \Gamma_{\mu\mu}^{\mu\mu} d_{(1)} x^{\mu}) d_{(2)} x^{\mu}(B_1) = \\ &= V^{\mu\mu} - \Gamma_{\mu\mu}^{\mu\mu} V^{\mu\mu} d_{(1)} x^{\mu}(A) - \Gamma_{\mu\mu}^{\mu\mu} V^{\mu\mu} d_{(2)} x^{\mu}(B_1) + \\ &+ \Gamma_{\mu\mu}^{\mu\mu} \Gamma_{\mu\mu}^{\mu\mu} d_{(1)} x^{\mu}(A) d_{(2)} x^{\mu}(B_1) - \Gamma_{\mu\mu, \mu\mu}^{\mu\mu} d_{(1)} x^{\mu}(A) d_{(2)} x^{\mu}(B) + O(d^3) \end{aligned}$$

[Handwritten signature]

$$V^{\sigma}(A \rightarrow B_2 \rightarrow C) - V^{\sigma}(A \rightarrow B_1 \rightarrow C) =$$

$$= \Gamma_{\sigma}^{\mu} V^{\rho} (d_{(1)} x^{\sigma}(A) + d_{(2)} x^{\sigma}(B_1) - d_{(2)} x^{\sigma}(A) - d_{(1)} x^{\sigma}(B_2)) +$$

0 не зодбує (об'єднує)

$$+ \Gamma_{\sigma, \lambda}^{\mu} V^{\rho} d_{(1)} x^{\sigma} d_{(2)} x^{\lambda} - \Gamma_{\sigma, \lambda}^{\mu} V^{\rho} d_{(2)} x^{\sigma} d_{(1)} x^{\lambda} +$$

$$+ \Gamma_{\sigma, \lambda}^{\mu} \Gamma_{\rho}^{\nu} V^{\rho} d_{(2)} x^{\lambda} d_{(1)} x^{\sigma} - \Gamma_{\sigma, \lambda}^{\mu} \Gamma_{\rho}^{\nu} V^{\rho} d_{(1)} x^{\lambda} d_{(2)} x^{\sigma} =$$

$$= (\Gamma_{\sigma, \lambda}^{\mu} - \Gamma_{\sigma, \lambda}^{\mu} + \Gamma_{\sigma, \lambda}^{\mu} \Gamma_{\rho}^{\nu} - \Gamma_{\sigma, \lambda}^{\mu} \Gamma_{\rho}^{\nu}) V^{\rho} d_{(1)} x^{\sigma} d_{(2)} x^{\lambda} =$$

$$= R_{\sigma, \lambda}^{\mu} V^{\rho} d_{(1)} x^{\sigma} d_{(2)} x^{\lambda}$$

Fyzikální význam Riemannova tenzoru

Newton $\rightarrow g_{00} = -1 - 2\Phi$

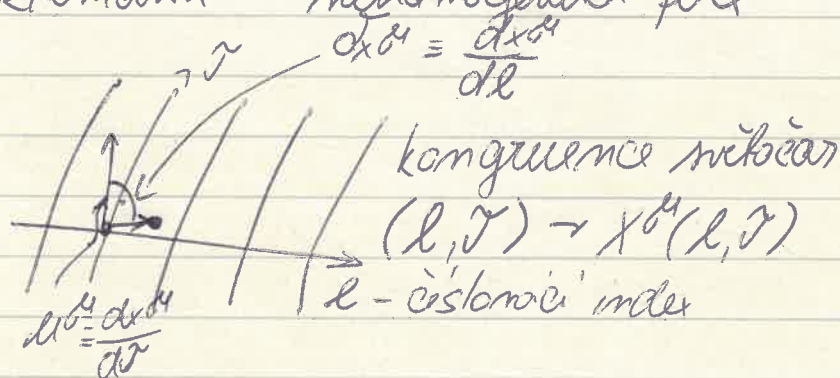
$$\Gamma_{\mu\nu\rho} = \frac{1}{2}(g_{\mu\nu,\rho} + g_{\rho\mu,\nu} - g_{\nu\rho,\mu})$$

$$R_{\dots} = \Gamma_{\dots,\mu}^{\mu} - \Gamma_{\dots,\mu}^{\mu} + \Gamma\Gamma - \Gamma\Gamma$$

metrika $\sim$ potenciál

Christoffel $\Gamma \sim$ intenzita pole

Riemann $\sim$ nehomogenita pole



$$\begin{aligned} \frac{D\dot{x}^\alpha}{d\tau} &= \frac{d\dot{x}^\alpha}{d\tau} + \Gamma_{\alpha\beta}^{\gamma} \dot{x}^\beta \dot{x}^\gamma = \\ &= \frac{d\dot{x}^\alpha}{d\tau} = \frac{d\dot{x}^\alpha}{dl} + \Gamma_{\alpha\beta}^{\gamma} \dot{x}^\beta \dot{x}^\gamma = \frac{D\dot{x}^\alpha}{dl} \end{aligned}$$

diffeomorfismus světových

$$\frac{d}{d\tau} (g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu) = \frac{D}{d\tau} (g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu) =$$

$$= g_{\mu\nu} \dot{x}^\mu \frac{D\dot{x}^\nu}{d\tau} = g_{\mu\nu} \dot{x}^\mu \frac{D\dot{x}^\nu}{dl} = \frac{1}{2} \frac{D}{dl} (g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu) = 0$$

$g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu$ jsou na sebe kolmé po celou dobu!

Relativ' zrychlen'!

$$\frac{D^2 \sigma_{x^\alpha}}{d^2 \tau} = \frac{D}{d\tau} \left(\frac{D \sigma_{x^\alpha}}{d\ell} \right) = \frac{D}{d\tau} \left(\ell^{\beta\gamma}_{i\alpha} \sigma_{x^\alpha} \right) =$$

$$= \ell^{\beta\gamma}_{i\alpha} \ell^{\beta\gamma}_{i\alpha} \sigma_{x^\alpha} + \ell^{\beta\gamma}_{i\alpha} \frac{D \sigma_{x^\alpha}}{d\ell} = \oplus$$

Ricci $\eta_{\mu, \alpha} \eta_{\mu, \beta} = R^{\gamma}_{\mu \alpha \beta} u^{\mu}$

$$\begin{aligned} (*) &= \dot{u}^\alpha \dot{u}^\beta \dot{u}^\gamma \dot{u}^\delta + R^\alpha{}_\beta \dot{u}^\beta \dot{u}^\gamma \dot{u}^\delta + \dot{u}^\alpha \dot{u}^\beta \dot{u}^\gamma \frac{D u^\beta}{d\tau} \\ &= -R^\alpha{}_\beta \dot{u}^\beta \dot{u}^\gamma \dot{u}^\delta + \frac{D}{d\tau} (\dot{u}^\alpha \dot{u}^\beta) = 0 \\ &= -R^\alpha{}_\beta \dot{u}^\beta \dot{u}^\gamma \dot{u}^\delta + \frac{D}{d\tau} \left(\frac{D u^\alpha}{d\tau} \right) = \text{geodesika} \\ &= -R^\alpha{}_\beta \dot{u}^\beta \dot{u}^\gamma \dot{u}^\delta \\ &= 0 \end{aligned}$$

Rovnice geodetické 'deviace

- Non omogeneità grav. pale è più discrepanza o Riemannovè senzore

 r_{LISu}

$$L^{\hat{u}} = (1, 0, 0, 0), \quad d_x L^{\hat{u}} = (0, dx^i)$$

$$\frac{d^2 x^i}{dx^2} = -R^i_{j00} dx^j$$

Решет ли зів'єт?

$$g^{\mu\nu} R_{\mu\nu\alpha\beta} = R^{\alpha}_{\beta} = R_{\beta}^{\alpha}$$

Piccolo Amore

Sedine' netivichil' süren' Riemann.

4 vlastnost' Riemannova tenzoru plyne, si

Riccio tenzor $R_{\nu\lambda}$ je symetricky

$$g^{\nu\lambda} R_{\nu\lambda} \equiv R^{\lambda}_{\lambda} \equiv R \quad \begin{array}{l} \text{skalarni invariant} \\ \text{Riccioho skalari} \end{array}$$

Tenzor energie a hybnosti $T^{\mu\nu}$

STR

- Nabitý nekoherební prach

$$\frac{dp^{\mu}}{d\tau} = \underbrace{q F^{\mu\nu}}_{m_0 u^{\nu}} u_{\nu} \quad \text{1. částice}$$

$F_L^{\mu\nu}$ - Lorentzova čtyřsila

$$\sum_{\mu\nu} F^{\mu\nu} u^{\nu} = \dots = -c^2 \frac{dm_0}{d\tau}$$

antisymetrický tenzor

Lorentzova čtyřsila je kolmá na u^{μ} : $F^{\mu\nu} u_{\nu} u_{\mu} = 0$

$$m_0 \frac{du^{\mu}}{d\tau} = q F^{\mu\nu} u_{\nu} = F_L^{\mu}$$

Nyní přejdeme k hustotě:

$$\frac{dm_0}{dV_0} \frac{du^{\mu}}{d\tau} = \frac{dF_L^{\mu}}{dV_0}$$

Hledáme hustotu, hledáme hustotu

u^{μ} jsou definovány jako pole "obklopen" prachem:

$$\oint_0 (u^{\mu}_{,\nu} u^{\nu}) = \Phi_L^{\mu}$$

$$\rightarrow (\oint_0 u^{\mu}_{,\nu} u^{\nu})_{,\mu} - \left[(\oint_0 u^{\nu})_{,\mu} u^{\mu} \right] = \Phi_L^{\mu}$$

neboť $(\oint_0 u^{\nu})_{,\mu}$ vyjadřuje rovnici kontinuity pro "hmotný proud" $\rightarrow \rho(c, \vec{r})$
 $\rightarrow \rho(c, \vec{r})$

$$T_{\text{prach}}^{\mu\nu} = \oint_0 u^{\mu} u^{\nu}$$

$$\rightarrow T_{\text{prach},\nu}^{\mu} = \Phi_L^{\mu}$$

$$T_{\text{prach}}^{00} = \oint_0 \gamma^2 c^2 = \rho c^2 \dots \text{hustota energie}$$

$$T_{\text{prach}}^{0i} = \oint_0 \gamma^2 c \dot{r}^i = \rho c^2 \dot{r}^i \frac{1}{c} \dots \frac{1}{c} \text{ tož hustota energie}$$

$$T_{\text{prach}}^{ij} = \oint_0 \gamma^2 \dot{r}^i \dot{r}^j = \rho \dot{r}^i \dot{r}^j \dots \text{tož hustota hybnosti} \dots c \text{ hustota hybnosti}$$

$$T_{EM}^{\mu\nu} = \frac{1}{\mu} (F^{\mu\sigma} F^{\nu}_{\sigma} - \frac{1}{4} \eta^{\mu\nu} F^{\rho\sigma} F_{\rho\sigma})$$

$$F_{\mu\nu} = \begin{pmatrix} 0 & -\vec{E}/c \\ \vec{E}/c & \epsilon_{jkl} B^k \end{pmatrix}$$

$$\begin{aligned} T_{EM}^{00} &= \frac{1}{\mu} \left(\underbrace{F^{00} F^0_0}_{\frac{1}{c^2} E^k E_k} + \frac{1}{4} \underbrace{F^{\rho\sigma} F_{\rho\sigma}}_{2B^2 - \frac{2E^2}{c^2}} \right) = \\ &= \frac{1}{2\mu} \left(\frac{E^2}{c^2} + B^2 \right) \stackrel{\frac{1}{\mu c^2} = \epsilon}{=} \frac{1}{2} (\vec{E} \cdot \vec{D} + \vec{H} \cdot \vec{B}) = w \end{aligned}$$

w = hustata energie EM pole

$$\begin{aligned} T^{0j} &= \frac{1}{\mu} (F^{0k} F^j_k - \frac{1}{4} \cdot 0) = \frac{1}{\mu c} \epsilon^{jk} E_k B^j = \\ &= \frac{1}{c} (\vec{E} \times \vec{H})_j = \frac{1}{c} \vec{S}_j \dots \frac{1}{c} \text{ tot hustata energie} \end{aligned}$$

$$\begin{aligned} T_{EM}^{ij} &= \frac{1}{\mu} (F^{i\sigma} F^j_{\sigma} - \frac{1}{4} \delta^{ij} F^{\rho\sigma} F_{\rho\sigma}) = \\ &= \frac{1}{\mu} (F^{i0} F^j_0 + F^{ik} F^j_k - \frac{1}{2} \delta^{ij} (B^2 - \frac{E^2}{c^2})) = \\ &= \frac{1}{\mu} \left(-\frac{1}{c^2} E^i E^j + \epsilon^{ikm} B_m \epsilon^{jkn} B_n - \frac{1}{2} \delta^{ij} (B^2 - \frac{E^2}{c^2}) \right) = \\ &= \frac{1}{\mu} \left(-\frac{1}{c^2} E^i E^j + \underbrace{(\delta^{ij} \delta^{mn} - \delta^{im} \delta^{jn}) B_m B_n}_{\delta^{ij} B^2 - B^i B^j} - \frac{1}{2} \delta^{ij} (B^2 - \frac{E^2}{c^2}) \right) = \end{aligned}$$

$$\begin{aligned} &= \frac{1}{\mu} \left(-\frac{1}{c^2} E^i E^j - B^i B^j + \frac{1}{2} \delta^{ij} B^2 + \frac{1}{2} \delta^{ij} \frac{E^2}{c^2} \right) = \\ &= \delta^{ij} w - E^i D^j - H^i B^j \end{aligned}$$

8. přednáška

Ukažme $T_{EM}^{\alpha\beta} = \frac{1}{\mu} (F^{\alpha\sigma} F^{\beta}_{\sigma} - \frac{1}{2} \eta^{\alpha\beta} F^{\rho\sigma} F_{\rho\sigma})$

$T_{EM, \nu}^{\alpha\beta} = \frac{1}{\mu} (F^{\alpha\sigma}_{, \nu} F^{\beta}_{\sigma} + F^{\alpha\sigma} \underbrace{F^{\beta}_{\sigma, \nu}}_{\mu \Phi_L^{\beta}} - \frac{1}{2} \eta^{\alpha\beta} F^{\rho\sigma}_{, \nu} F_{\rho\sigma}) = *$

$F_L^{\alpha\beta} = g F^{\alpha\beta} u_{\nu} \rightarrow \Phi_L^{\alpha\beta} = g_0 F^{\alpha\beta} u_{\nu} = F^{\alpha\beta} j_{\nu}$

$* = -\Phi_L^{\alpha\beta} + \frac{1}{\mu} (F^{\alpha\sigma, \rho} F^{\beta}_{\rho\sigma} - \frac{1}{2} F^{\rho\sigma, \alpha} F_{\rho\sigma}) =$

$= -\Phi_L^{\alpha\beta} + \frac{1}{\mu} (F^{\alpha\sigma, \rho} - \frac{1}{2} F^{\rho\sigma, \alpha}) F_{\rho\sigma} =$

$= -\Phi_L^{\alpha\beta} + \frac{1}{\mu} (\frac{1}{2} F^{\alpha\sigma\rho} - \frac{1}{2} F^{\alpha\rho\sigma} - \frac{1}{2} F^{\rho\sigma\alpha}) F_{\rho\sigma} =$

realizuje se pouze antisymetrická část

$= -\Phi_L^{\alpha\beta} + \frac{1}{2\mu} (F^{\alpha\sigma\rho} + F^{\rho\sigma\alpha} + F^{\alpha\rho\sigma}) F_{\rho\sigma} = -\Phi_L^{\alpha\beta}$

0 (cyklická permutace)

$T^{\alpha\beta}_{, \nu} = 0$, kde $T^{\alpha\beta} = T^{\alpha\beta}_{\text{poch}} + T^{\alpha\beta}_{EM}$

čtyř-divergence rovniceho systému je vždy 0!
ukážeme i vztah EM interakce poch

Idea'lui' sekutina (OTR)

$$T^{\mu\nu} = \rho u^{\mu} u^{\nu} + P h^{\mu\nu}$$

$$h^{\mu\nu} = g^{\mu\nu} + u^{\mu} u^{\nu}$$

$$\text{Simk: } T^{\mu\nu} = (\rho + P) u^{\mu} u^{\nu} + P g^{\mu\nu}$$

$$\begin{aligned} 0 &= T^{\mu\nu}_{; \nu} = \rho_{; \nu} u^{\mu} u^{\nu} + P_{; \nu} u^{\mu} u^{\nu} + (\rho + P) u^{\mu}_{; \nu} u^{\nu} + \\ &\quad + (\rho + P) u^{\mu} u^{\nu}_{; \nu} + P_{; \nu} g^{\mu\nu} = \\ &= \frac{d\rho}{d\tau} u^{\mu} + P_{; \nu} h^{\mu\nu} + (\rho + P) a^{\mu} + (\rho + P) u^{\mu} u^{\nu}_{; \nu} = \end{aligned}$$

$$\parallel u^{\mu}: \frac{d\rho}{d\tau} + (\rho + P) u^{\mu}_{; \nu} u^{\nu} = 0$$

Rernice kontinuity

$$\perp u^{\mu}: (\rho + P) a^{\mu} = - P_{; \nu} h^{\mu\nu}$$

Eulerovy poligbove' normice

Podmínky hydrostatické rovnováhy

- lokální stáje: $u^\alpha = (u^t, 0, 0, 0)$

$$g_{\mu\nu} u^\mu u^\nu = -1 = g_{tt}(u^t)^2 \rightarrow u^t = \sqrt{\frac{1}{-g_{tt}}}$$

$$u_\alpha = g_{\alpha\mu} u^\mu = g_{\alpha t} u^t$$

- statické metrika: $g_{\mu\nu,0} = 0 \wedge g_{\mu 0} = 0$

$$\rightarrow u_\alpha = u g_{\alpha t} u^t = (-\sqrt{-g_{tt}}, 0, 0, 0)$$

Dosazení do Eulerových rovnic:

$$\partial_\alpha u^\alpha = 0 \Rightarrow \partial_\alpha u^\alpha = u_{\alpha,\nu} u^\nu - \Gamma_{\alpha\nu}^\alpha u^\alpha u^\nu =$$

$$= \cancel{u_{\alpha,t} u^t} - \Gamma_{t\alpha t} (u^t)^2 = -\frac{1}{2} (\cancel{g_{t\alpha,t}} + \cancel{g_{t\alpha,t}} - \cancel{g_{\alpha t,t}}) (u^t)^2 =$$

$g_{\mu\nu,0} = 0$

$$= -\frac{1}{2} g_{tt,\alpha} \frac{1}{g_{tt}} = -\frac{1}{2} \frac{\partial}{\partial x^\alpha} \ln(g_{tt}) = \frac{\partial}{\partial x^\alpha} \ln \sqrt{-g_{tt}}$$

$$P_{i,\nu} h^\nu_\alpha = P(\sigma^\nu_\alpha - \sigma^\nu_0 \sigma^\alpha_0) \xrightarrow{\alpha=0 \Rightarrow 0} \xrightarrow{\alpha \neq 0 \Rightarrow} P_{i\alpha}$$

$\alpha = i$:

$$(\rho + P) \frac{\partial}{\partial x^i} \ln \sqrt{-g_{tt}} = -P_{,i}$$

$$g_{tt} = -e^{2\Phi} \quad | \quad \Phi \ll 1 \Rightarrow g_{tt} \approx -1 - 2\Phi$$

$$\rightarrow (\rho + P) \Phi_{,i} = -P_{,i}$$

Einsteinovy rovnice gravitačního pole

Newton: $\Delta \Phi = 4\pi \rho$ | $\vec{F}_g = -G \frac{M_1 M_2}{r^2} \vec{r}_0$

• nezávislá rychlost šíření
(neu'kastro'lu')

• neu'kovariantní

$$\square \Phi \equiv \Phi^{;a}_{;a} \equiv g^{\alpha\beta} \Phi_{;\alpha\beta}$$

• potřebujeme pracovat i jinde, než v klidovém systému

→ n. pravo: ~~$T_{\mu\nu}$~~ $T_{\mu\nu}$ linearity

vlevo: tenzor $\mu\nu$ ($g_{\alpha\beta}, g_{\alpha\beta}, \rho, g_{\alpha\beta}, \rho$)

Významnost Riemannova tenzoru:

tenzor „invariantní“ co do formy "prose"

tenzor ($g_{\alpha\beta}, g_{\alpha\beta}, \rho, g_{\alpha\beta}, \rho$) lze vyjádřit jen pomocí tenzor ($g_{\alpha\beta}, R^{\alpha}_{\gamma\delta\beta}$)

$$R_{\mu\nu\alpha\beta} = \frac{1}{2} (g_{\mu\alpha,\nu\beta} + g_{\nu\beta,\mu\alpha} - g_{\mu\beta,\nu\alpha} - g_{\nu\alpha,\mu\beta}) - g_{\mu\nu} (R^{\alpha\beta}_{\alpha\beta} - R^{\alpha\beta}_{\beta\alpha})$$

→ Chemické senzory (gas, $R^{\mu\nu}_{\mu\lambda\lambda}$) ↖ lineární!

kandidát:

$$R_{\mu\nu}, R, Rg_{\mu\nu}, g_{\mu\nu}$$

$$\rightarrow C_1 R_{\mu\nu} + C_2 R g_{\mu\nu} + C_3 g_{\mu\nu} = K T_{\mu\nu}$$

1. 2. Bianchova identity: $R^{\mu\nu}_{[\mu\lambda;\rho]} = 0$

• zákon zachování: $T^{\mu\nu}_{;\nu} = 0$

$$1. R^{\mu\nu}_{\mu\lambda;\rho} + R^{\mu\nu}_{\rho\mu;\lambda} + R^{\mu\nu}_{\lambda\rho;\mu} = 0 \quad | \mu \rightarrow \mu$$

$$R^{\nu}_{\lambda;\rho} + R^{\mu\nu}_{\rho\mu;\lambda} + R^{\mu\nu}_{\lambda\rho;\mu} = 0 \quad | \nu \rightarrow \lambda$$

$$R_{\lambda\rho} - R^{\lambda}_{\rho;\lambda} - R^{\mu}_{\rho;\mu} = 0$$

$$\rightarrow R_{\lambda\rho} = 2 R^{\lambda}_{\rho;\lambda}$$

$$C_1 R_{\rho}^{\nu} + C_2 R g_{\rho}^{\nu} + C_3 g_{\rho}^{\nu} \quad |_{;\nu}$$

$$\rightarrow C_1 R^{\nu}_{\rho;\nu} + C_2 R_{\rho;\nu} \sigma^{\nu}_{\rho} = 0$$

$$\rightarrow C_1 R^{\nu}_{\rho;\nu} + C_2 R_{\rho}^{\nu} = C_1 R^{\nu}_{\rho;\nu} + 2 C_2 R^{\nu}_{\rho;\nu} =$$

$$= (C_1 + 2 C_2) R^{\nu}_{\rho;\nu} = 0 \rightarrow C_2 = -\frac{C_1}{2}$$

$$\rightarrow R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} + \frac{C_3}{C_1} g_{\mu\nu} = \frac{K}{C_1} T_{\mu\nu}$$

"1"
"k"

9. přednáška

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} + \Lambda g_{\mu\nu} = k T_{\mu\nu}$$

Einsteinův tenzor $G_{\mu\nu}$

$$k = ?$$

K určení k použijeme Newtonovskou limitu

$$g_{00} = -1 - 2\Phi$$

$$\frac{dx^\mu}{d\tau^2} + \Gamma^\mu_{\alpha\beta} \frac{dx^\alpha}{d\tau} \frac{dx^\beta}{d\tau} = 0 \quad \text{jedine' nemáme! } \Gamma$$

$$\rightarrow \frac{d^2 x^i}{dt^2} = -\Phi^{,i} \quad \left\{ \begin{array}{l} \Gamma'_{00} = \Phi^{,i} \end{array} \right.$$

$$R^\mu_{\nu\alpha\beta} = \Gamma^\mu_{\alpha\lambda,\beta} - \Gamma^\mu_{\beta\lambda,\alpha} + \Gamma^\mu_{\alpha\beta}\Gamma^\lambda_{\gamma\delta} - \Gamma^\mu_{\beta\alpha}\Gamma^\lambda_{\gamma\delta}$$

$\mu \rightarrow 0$:

$$R_{\alpha\beta} = \Gamma^\mu_{\alpha\lambda,\beta} - \Gamma^\mu_{\beta\lambda,\alpha} + \Gamma^\mu_{\alpha\beta}\Gamma^\lambda_{\gamma\delta} - \Gamma^\mu_{\beta\alpha}\Gamma^\lambda_{\gamma\delta}$$

$$\rightarrow R_{00} = \Gamma'_{00,i} = \Phi^{,i}_{,i} = \Delta\Phi$$

Přoměna:

Stara Einsteinových tenzor:

$$g_{\mu\nu} (R_{\mu\nu} - \dots)$$

$$R - 2R + 4\Lambda = kT$$

$$R = 4\Lambda - kT$$

$$\rightarrow R_{\mu\nu} = k T_{\mu\nu} - \frac{1}{2} k T g_{\mu\nu} + 2 \Lambda g_{\mu\nu} - \Lambda g_{\mu\nu} =$$

$$= k (T_{\mu\nu} - \frac{1}{2} T g_{\mu\nu}) + \Lambda g_{\mu\nu}$$

— poznámka: novorojená
druhá časť Einsteinových rovníc

$$T_{\mu\nu} := \rho u_\mu u_\nu$$

$$\Delta \Phi = 4\pi \rho, |\rho| \ll 1 \quad |\Phi| \ll O(\Phi^2)$$

$$T_{00} = \rho u_0 u_0 = \rho u_0 g_{0\sigma} u^\sigma = \rho u_0 u^0 g_{00} = \rho (-1 - u_i u^i) g_{00} = \oplus$$

$g_{00} u^0 + g_{0i} u^i$
 $\ll 1$ (Newton. limit)

$$\oplus \approx \ominus \approx +\rho$$

$$T \equiv T^\sigma_\sigma = -\rho$$

$$\rightarrow R_{00} = k(\rho + \frac{1}{2} \rho g_{00}) = \frac{1}{2} k \rho = \Delta \Phi = 4\pi \rho$$

$\uparrow_{-1-2\Phi}$

$$\rightarrow k = 8\pi$$

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} + \Lambda g_{\mu\nu} = 8\pi T_{\mu\nu}$$

re standardizovaných jednotkách.

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} + \Lambda g_{\mu\nu} = \frac{8\pi G}{c^4} T_{\mu\nu}$$

~~Skólová~~

Kosmologický člen:

$$R_{\mu\nu} \dots = 8\pi T_{\mu\nu} - \Lambda g_{\mu\nu} \stackrel{\substack{\text{důkazová} \\ \text{identifikace}}}{=} 8\pi(\rho + p)u_{\mu}u_{\nu} + 8\pi P g_{\mu\nu} - \Lambda g_{\mu\nu}$$

Jak lze interpretovat Λ ?

Zdrojový člen:

$$\frac{1}{2} R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = -\Lambda g_{\mu\nu} \stackrel{!}{=} 8\pi T_{\mu\nu} = 8\pi(\rho + p)u_{\mu}u_{\nu} + 8\pi P g_{\mu\nu}$$

$$\Leftrightarrow P = -\rho \quad (\text{potřebujeme vyvážený rytmus})$$

$$\rightarrow -\Lambda = -8\pi\rho \rightarrow \rho = \frac{\Lambda}{8\pi}$$

Vlastnosti E. rovnice

nerovnoměrnost je metriska $\rightarrow$ 10 nerovností ch složí

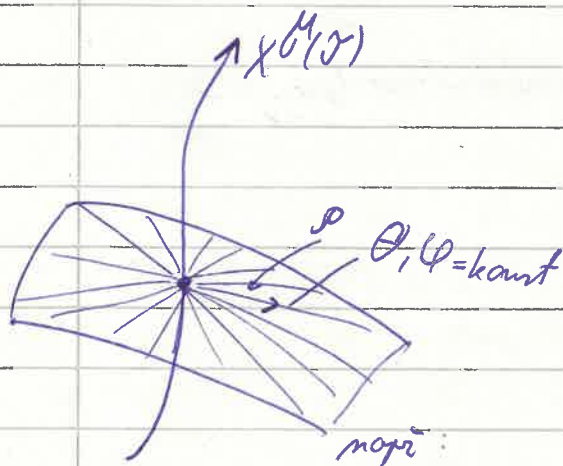
$$\text{rovnice} \rightarrow 10 \text{ rovnice} = 6 + 4$$

$\uparrow$ rovnice po metriskach

$\nwarrow$ zákon zachování po $T_{\mu\nu;\lambda} = 0$

Schwarzschildovo řešení E. rovnice

Přesně řečeno sféricky symetrické řešení



loko'lně: $g_{\mu\nu} \frac{\partial x^\mu}{\partial r} \frac{\partial x^\nu}{\partial \rho} = 0$

$g_{\mu\nu} \frac{\partial x^\mu}{\partial \rho} \frac{\partial x^\nu}{\partial \varphi} = 0$

atd. 03

$x^\mu = (r, \rho, \theta, \varphi): g_{\mu\nu} \delta_1^\mu \delta_3^\nu = g_{13}$

ij loko'lně: ~~ds~~ $g_{\mu\nu}$

$$ds^2 = +g_{rr}^{-1} dr^2 + g_{\rho\rho} d\rho^2 + g_{\theta\theta} d\theta^2 + g_{\varphi\varphi} d\varphi^2$$

Je taková metrika, rovnice "idele"?

radiální geodetiky:

$$\frac{dx^\mu}{d\rho^2} + \Gamma_{\alpha\beta}^{\mu} \frac{dx^\alpha}{d\rho} \frac{dx^\beta}{d\rho} = 0$$

volíme $x^1 \equiv \rho \Rightarrow \frac{dx^1}{d\rho} = \delta_1^\alpha$

$\Rightarrow \Gamma_{\alpha\beta}^{\mu} \delta_1^\alpha \delta_1^\beta = \Gamma_{11}^\mu = 0$

$$\frac{1}{2} g^{\mu\alpha} (g_{\alpha 1,1} + g_{1\alpha,1} - g_{11,\alpha}) = 0$$

$$g_{\mu\nu} \frac{dx^\mu}{d\sigma} \frac{dx^\nu}{d\sigma} = 1 \rightarrow g_{11} = 1 \text{ a plat' vr̃ide}$$

$$\rightarrow g^{\mu\alpha} g_{\alpha 1,1} = 0 \quad | g_{\alpha\mu}$$

$$\boxed{g_{\alpha 1,1} = 0}$$

1:51

g_{01} se poděíl postonov'ch geodetik podle g neměn'

Obecně mo' mezikřivka tvar:

$$ds^2 = g_{rr} dr^2 + \cancel{2g_{rp} dr dp} + g_{pp} dp^2 + \cancel{2g_{r\theta} dr d\theta} + \cancel{2g_{r\varphi} dr d\varphi} + \cancel{2g_{\theta\varphi} d\theta d\varphi} + \\ + g_{\varphi\varphi} d\varphi^2 + g_{\theta\theta} d\theta^2 + \cancel{2g_{\theta p} d\theta dp} + \cancel{2g_{\theta\varphi} d\theta d\varphi}$$

Předpoklady:

1. Sférická symetrie (*) $\rightarrow d\theta, d\varphi$

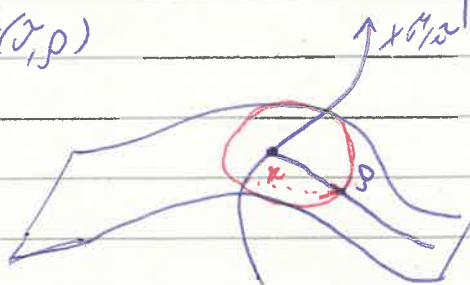
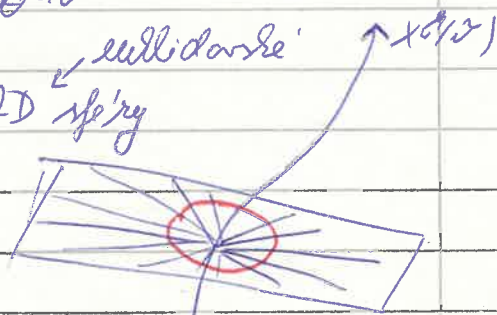
$$\rightarrow ds^2 = g_{rr} dr^2 + 1 \cdot dp^2 + g_{\varphi\varphi} d\varphi^2 + g_{\theta\theta} d\theta^2$$

2. pro nich $\{r = \text{konst}, p = \text{konst}\}$ mo' geometrii 2D sféry

$$\rightarrow g_{\theta\theta} d\theta^2 + g_{\varphi\varphi} d\varphi^2 = r^2(r, p) (d\theta^2 + \sin^2 \theta d\varphi^2)$$

$$\text{kde } \int_0^{2\pi} \int_0^\pi \sqrt{g_{\theta\theta} g_{\varphi\varphi}} d\theta d\varphi = 4\pi r^2(r, p)$$

$p = \text{konst}$
 $r = \text{konst}$



3. $g_{rr} = g_{rr}(r, p)$

$$\rightarrow ds^2 = \underbrace{g_{rr}(r, \varphi)}_{\text{}} dr^2 + \underbrace{\chi^2(r, \varphi)}_{\text{}} (d\theta^2 + \sin^2 \theta d\varphi^2) =$$

$$= g_{tt}(t, \pi) + g_{rr}(t, \pi) dr^2 + \pi^2 (d\theta^2 + \sin^2 \theta d\varphi^2)$$

$$\uparrow \quad \uparrow$$

$$(r, \varphi) \mapsto (t, \pi)$$

Najobecnější tvar metricky sféricky symetrického prostoročasu

10. přednáška:

Schwarzschild:

$$ds^2 = g_{tt}(t, r) dt^2 + g_{rr}(t, r) dr^2 + r^2 \underbrace{(d\theta^2 + \sin^2\theta d\varphi^2)}_{d\Omega^2}$$

Co potřebujeme?

$$g_{\mu\nu} \rightarrow \Gamma \dots \rightarrow R \dots \rightarrow R_{\mu\nu} \rightarrow R_{\mu\nu}$$

Označme $G_{\mu\nu} \equiv R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu}$ E. tensor

Pol:

$$G_0^0 = -\frac{\pi}{r^2} \frac{\partial g_{rr}}{\partial r} + g_{rr}(g_{rr} - 1)$$

$$G_1^1 = \frac{\pi}{r^2 g_{rr}} \frac{\partial g_{tt}}{\partial r} - g_{tt}(g_{rr} - 1)$$

$$G_{01} = \frac{\partial g_{tr}}{\partial t} \quad , \quad \text{zbytlé nejsou nezávislé rovnice}$$

$$G_{\mu\nu} + \Lambda g_{\mu\nu} = 8\pi T_{\mu\nu}$$

Řešíme vakuumové rovnice, tedy $G_{\mu\nu} = 0$

$$\rightarrow I. G_{01} = 0$$

$$\frac{\partial g_{nn}}{\partial t} = 0 \rightarrow g_{nn} = g_{nn}(r)$$

$$II. G^0 = 0 \quad \frac{dg_{nn}}{dr}$$

$$\rightarrow r \frac{\partial g_{nn}}{\partial r} = -g_{nn}(g_{nn} - 1)$$

$$\rightarrow \frac{dg_{nn}}{(g_{nn} - 1)g_{nn}} = -\frac{dr}{r}$$

$$\rightarrow \ln\left(\frac{g_{nn} - 1}{g_{nn}}\right) = -\ln \frac{r}{k}$$

$$1 - \frac{1}{g_{nn}} = + \frac{k}{r} \rightarrow \frac{1}{g_{nn}} = \frac{k + r}{r}$$

$$\rightarrow g_{nn} = \frac{r}{k + r} \quad g_{nn} = \frac{r}{r + k}$$

$$III. G^1 = 0$$

$$r \frac{\partial g_{tt}}{\partial r} = g_{tt}(g_{nn} - 1)$$

☞ Po vydělení této rovnice předchozí získáme:

$$\frac{g_{tt,r}}{g_{nn,r}} = -\frac{g_{tt}}{g_{nn}}$$

$$\rightarrow -\frac{g_{tt,r}}{g_{tt}} = \frac{g_{nn,r}}{g_{nn}}$$

$$(\ln |g_{tt}|)_{,r} + (\ln |g_{nn}|)_{,r} = 0$$

$$(\ln |g_{tt} g_{rr}|)_{,n} = 0$$

$$-g_{tt} g_{rr} = f(t) \quad \frac{1}{1 - \frac{r}{r_s}}$$

$$ds^2 = - \underbrace{\left(\frac{r-k}{r}\right)}_{1 - \frac{r_s}{r}} \underbrace{f(t) dt^2}_{\tilde{dt}^2} + \frac{r}{r-k} dr^2 + r^2 d\Omega^2$$

r_s ; lze volit $f(t) = 1$

Význam konstanty:

Newtonsko limito:

$$g_{tt} = -1 - 2\Phi \xrightarrow{\text{sfer. sym}} -1 + 2\frac{M}{r} \rightarrow K = 2M$$

$$ds^2 = -\left(1 - \frac{2GM}{c^2 r}\right) c^2 dt^2 + \frac{dr^2}{1 - \frac{2GM}{c^2 r}} + r^2 d\Omega^2$$

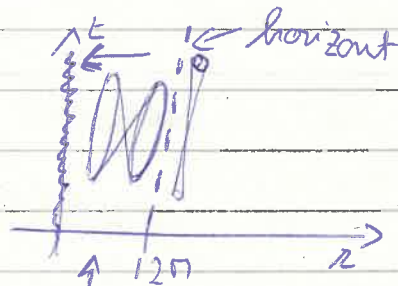
Vlastnost Schwarzschildovy metriky

- závisí na hmotnosti M
- pro $M=0 \rightarrow$ Minkowského př.
- r nekonečno (∞) je t vlastní čas
- metrika je statičtí, stacionární + diagonální
- navíc statičnost jsme nepředpokládali
- neexistují sférické gravitační vlny

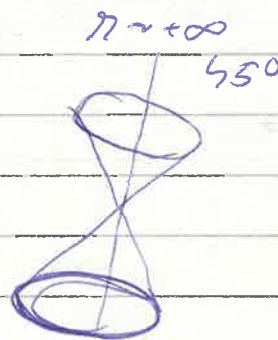
Trasy větelných křivek:

$ds^2 = 0$ ← radiálně polyl (d θ , d φ = 0)

$$\rightarrow -(-1 - \frac{2M}{r})dt^2 + \frac{dr^2}{1 - \frac{2M}{r}}$$



$$\frac{dt}{dr} = \pm \frac{1}{1 - \frac{2M}{r}}$$

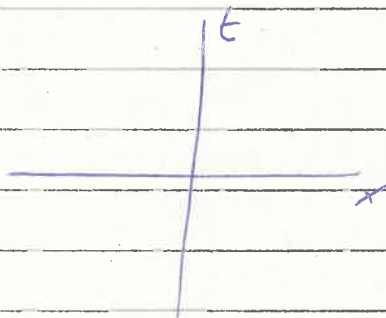


$R_{\mu\nu} R^{\mu\nu} = \frac{48M^2}{r^6}$ ← Schwarzschildova metrika

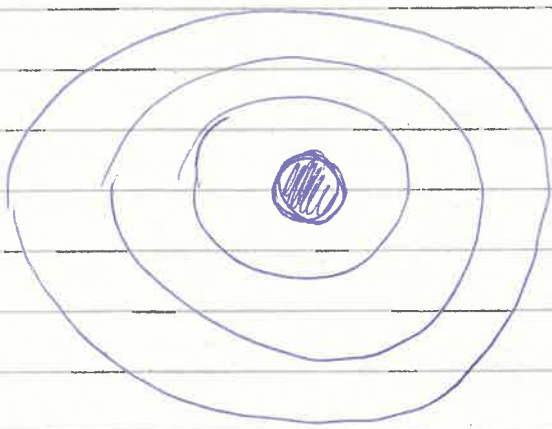
Kretschmannův skalár

→ $r=0$ je singularita porušující

horizont singularitní ner,
přechází a rolka souřadnic



normované vektorové pole k { $r=const$ }



normálne pole najdene jeho gradient:

$$\frac{\partial \pi}{\partial x^a}$$

jeho charakter je daný jeho: $g^{ab} \frac{\partial \pi}{\partial x^a} \frac{\partial \pi}{\partial x^b} = g^{rr} = \frac{1}{g_{rr}} = 1 - \frac{2M}{r}$
 $(0, 1, 0, 0)$

$$\boxed{g_{\mu\nu} g^{\nu\alpha} = \delta_{\mu}^{\alpha}} \quad \text{!}$$

pre $\pi \rightarrow \infty \rightarrow$ postupne podobe ^{nadploch} ~~metricky~~

pre $\pi = 2M \rightarrow$ veľkosť nadploch

• horizont je statická časť a miesto nebenečíta frekvencieho posunu

$$\frac{\lambda_B}{\lambda_A} = \sqrt{\frac{-g_{tt}(A)}{-g_{tt}(B)}}$$

• na horizonte sa pohybuje fyzikálne nízkom (t, r)

Pohyb volných testovacích částic

$$\frac{dx^\alpha}{d\tau^2} = \Gamma^\alpha_{\beta\gamma} \frac{dx^\beta}{d\tau} \frac{dx^\gamma}{d\tau} \quad \left| \frac{dx^\alpha}{d\tau} = u^\alpha \right.$$

$$\begin{aligned} \frac{du^\alpha}{d\tau} &= \Gamma^\alpha_{\beta\gamma} u^\beta u^\gamma = \nabla \\ &\quad \text{antisymetrický člen} \\ &= \frac{1}{2} (g_{\alpha,\beta} + g_{\beta,\alpha} - g_{\alpha,\alpha}) u^\beta u^\gamma = \\ &= \frac{1}{2} g_{\beta,\alpha} u^\beta u^\gamma \end{aligned}$$

$$\rightarrow g_{\beta,\alpha} = 0 \Rightarrow \frac{du^\alpha}{d\tau} = 0$$

$$g_{\beta,t} = 0 \Rightarrow -u_t^\beta = \text{konst}$$

$$g_{\beta,\varphi} = 0 \Rightarrow u_\varphi = \text{konst}$$

$$-u_t = -g_{tt} u^t = -g_{tt} \frac{dt}{d\tau} = \frac{-g_{tt}}{\sqrt{-g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}}} =$$

$$= \frac{-g_{tt}}{\sqrt{-g_{tt} - g_{rr} \frac{dr}{dt} \frac{dr}{dt}}} = \frac{-g_{tt}}{\sqrt{1 - \frac{2M}{r} - r^2 \dot{r}^2}} =$$

$$= \frac{1 - \frac{2M}{r}}{\sqrt{1 - \frac{2M}{r} - r^2 \dot{r}^2}} \xrightarrow{r \rightarrow \infty} \frac{1}{\sqrt{1 - r^2(\infty)}} = \gamma(\infty)$$

$$-p_t = -m u_t = E$$

$$u_\varphi = g_{\varphi\varphi} \dot{\varphi} = g_{\varphi\varphi} \frac{d\varphi}{dt} \frac{dt}{d\tau} = \overset{\omega - \text{ciklona' rychlost}}{\gamma^\varphi} g_{\varphi\varphi} \frac{1}{\sqrt{1 - \frac{2M}{r} - \alpha^2 \gamma^2}} =$$

$$\xrightarrow{r \rightarrow \infty} r^2 \sin^2 \theta \alpha^\varphi \frac{E}{m}$$

$$\Rightarrow p_\varphi = m u_\varphi = L$$

• Polozb je rovinný, 0°

ptáme se, zda rychlost je nulová:

$$\frac{du^\theta}{d\tau} = -\Gamma_{\alpha\beta}^\theta u^\alpha u^\beta = \dots = \Gamma_{\varphi\varphi}^\theta (u^\varphi)^2 = -\sin\theta \cos\theta (u^\varphi)^2 \stackrel{\theta = \frac{\pi}{2} \Rightarrow}{=} 0$$

$u^\theta = 0 \leftarrow \text{volba}$

Metoda efektivního potenciálu

$$g^{\alpha\beta} p_\alpha p_\beta = -m^2$$

$$g^{tt} \underbrace{(p_t)^2}_{E^2} + \underbrace{g^{\pi\pi} (p_\pi)^2}_{g^{\pi\pi} (p^\pi)^2} + g^{\varphi\varphi} \underbrace{(p_\varphi)^2}_{L^2} = -m^2$$

$$g^{\pi\pi} (p^\pi)^2 = -\frac{E^2}{g_{tt}} - \frac{L^2}{g_{\varphi\varphi}} - m^2$$

$$(p^\pi)^2 = \frac{E^2}{\underbrace{-g_{tt} g^{\pi\pi}}_{=1}} - \frac{1}{g^{\pi\pi}} \left(m^2 + \frac{L^2}{g_{\varphi\varphi}} \right) = E^2 -$$

$$= E^2 - \underbrace{\frac{1}{g^{\pi\pi}} \left(m^2 + \frac{L^2}{g_{\varphi\varphi}} \right)}_{\text{efektivní potenciál}}$$

časopodobne geodetiky:

vydělíme m^2 :

$$(u^r)^2 = \tilde{E}^2 - \tilde{V}^2, \quad \tilde{E} = \frac{E}{m}, \quad \tilde{L} = \frac{L}{m}$$

$$\tilde{V}^2 = \left(1 - \frac{2M}{r}\right) \left(1 + \frac{\tilde{L}^2}{r^2}\right)$$

Kepler, Newton:

$$\tilde{E} = \frac{1}{2} \left[(\dot{r})^2 + (r\dot{\varphi})^2 \right] + \Phi = -\frac{M}{r}$$

$$\tilde{L} = r^2 \dot{\varphi}, \quad r\dot{\varphi} = \frac{\tilde{L}}{r}$$

$$(\dot{r})^2 = 2(\tilde{E} - \tilde{V}_{\text{eff}})$$

$$\tilde{V}_{\text{eff}} = -\frac{M}{r} + \frac{\tilde{L}^2}{2r^2}$$

Newtonovskolimiton: $r \gg M$

$$\tilde{V} = \left(1 - \frac{M}{r}\right) \left(1 + \frac{\tilde{L}^2}{2r^2}\right) \doteq \underbrace{1}_{mc^2} - \frac{M}{r} + \frac{\tilde{L}^2}{2r^2}$$

11. přednáška

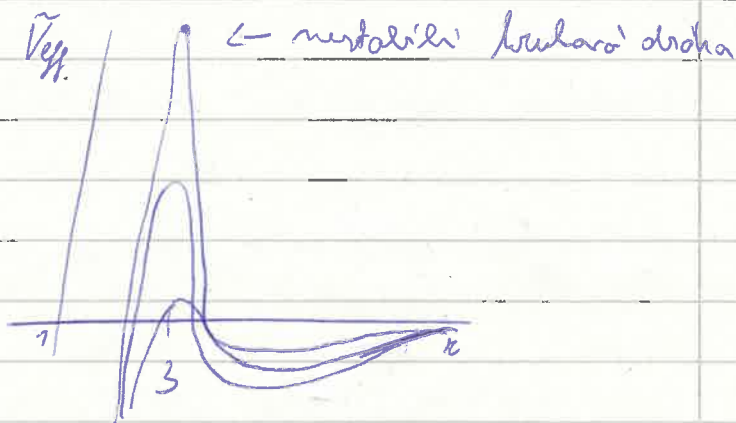
$$(p^r)^2 = E^2 - \underbrace{\left(1 - \frac{2M}{r}\right)}_{V^2} \left(m^2 + \frac{L^2}{r^2}\right)$$

radiační pohyb se odehrává tam kde $E^2 \geq V^2$, $E = \text{konst}$

Newton:



Schwarzschild:



Cocoonová nestabilní kulová dráha? Světlo?

Fyzikální slož rychlost: $ds^2 = g_{tt} dt^2 + g_{rr} dr^2 + r^2 (d\theta^2 + \sin^2\theta d\phi^2)$

$$\hat{r}^i = \frac{dx^i}{d\tau} = \frac{\sqrt{g_{ii}} dx^i}{d\tau} =$$

$$= \sqrt{g_{ii}} \frac{dx^i}{d\tau} \frac{d\tau}{dt} \frac{dt}{d\tau} = \hat{r}^i \dots \text{parabolická}$$

$\hat{r}^i$... částice
 t ... souřadnice

$\theta, \phi = \text{konst}$

$$* = \sqrt{g_{ii}} \frac{dx^i}{d\tau} \frac{1}{\sqrt{g_{tt}}} =$$

$$= \sqrt{-g_{tt} g_{ii}} \frac{dx^i}{dt} =$$

$$\tilde{E} = -u_t = -g_{tt} u^t$$

$$\Rightarrow u^t = \frac{E}{-g_{tt}}$$

$$\tilde{L} = u_\phi = g_{\phi\phi} u^\phi$$

$$u^\phi = \frac{\tilde{L}}{g_{\phi\phi}}$$

$$u^t = \frac{1}{\sqrt{-g_{tt}}}$$

$$-g_{tt}g_{rr} = 1$$

$$(\hat{r}^t)^2 = \frac{L^2 (u^t)^2}{\tilde{E}^2} \Rightarrow (\hat{r}^t)^2 = 1 - \frac{\tilde{V}^2}{\tilde{E}^2}$$

$$(\hat{r}^{\hat{\phi}})^2 = \sqrt{-g_{tt}g_{\phi\phi}} \frac{(u^{\hat{\phi}})^2}{\tilde{E}^2} = \frac{-g_{tt}}{g_{\phi\phi}} \frac{\tilde{L}^2}{\tilde{E}^2} =$$

$$= \frac{1 - \frac{2M}{r}}{r^2} \frac{\tilde{L}^2}{\tilde{E}^2}$$

Kružová dráha: $u^r = 0 \Rightarrow \tilde{E}^2 = \tilde{V}^2, \frac{\partial \tilde{V}^2}{\partial r} = 0$

$$\frac{\partial \tilde{V}^2}{\partial r} = \frac{\partial}{\partial r} \left(1 - \frac{2M}{r} \right) \left(r^2 + \frac{\tilde{L}^2}{r^2} \right) =$$

$$= \frac{2M}{r^2} \left(1 + \frac{\tilde{L}^2}{r^2} \right) + \left(1 - \frac{2M}{r} \right) \frac{\tilde{L}^2}{r^3} = 0$$

$$Mr^2 \left(1 + \frac{\tilde{L}^2}{r^2} \right) - r \left(1 - \frac{2M}{r} \right) \tilde{L}^2 = 0$$

$$Mr^2 + \tilde{L}^2 M - r \tilde{L}^2 + 2M \tilde{L}^2 = 0$$

$$\tilde{L}^2 (3M - r) + Mr^2 = 0$$

$$\Rightarrow \tilde{L}^2 = \frac{Mr^2}{r - 3M}$$

$$\tilde{E} = \tilde{V}^2(\tilde{L}) = \left(1 - \frac{2M}{r} \right) \left(1 + \frac{M}{r - 3M} \right) =$$

$$= 1 - \frac{2M^2}{r(r - 3M)} - \frac{2M}{r} + \frac{M}{r - 3M} =$$

$$= \frac{(r - 2M)^2}{r(r - 3M)}$$

$$(\hat{r}\hat{\varphi})^2 = \frac{\cancel{n-2M}}{\cancel{n}} \frac{\cancel{Mn}}{\cancel{n-3M}} \frac{\cancel{n(n-3M)}}{(n-2M)^2} = \frac{M}{n-2M}$$

$$\text{po } n=3M: \hat{r}\hat{\varphi} = 1 \equiv C$$

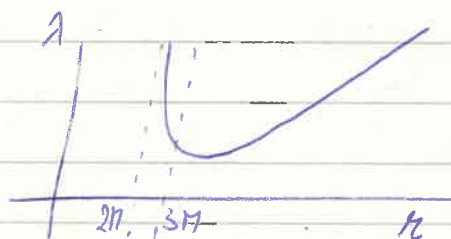
→ nestabiln' kruhova' dróha odpovedá' kruhové dróze metla

$$(\hat{p}^r)^2 \text{ po fotony: } (m=0)$$

$$(\hat{p}^r)^2 = E^2 - V^2 = E^2 \left(1 - \frac{1-\frac{2M}{r}}{r^2} \frac{\ell^2}{E^2} \right) =$$

$$= E^2 \left(1 - \underbrace{\frac{\ell^2}{r^2}}_{\geq 0} \right)$$

$$\Rightarrow \ell^2 \leq r^2$$



Kosmologie

• de Sitter: $R_{\text{dS}} = \Lambda_{\text{grav}}^{-1}$

• Friedmann

• G. Lemaître

• E. Hubble

$$\frac{c}{H} \sim 10^{26} \text{ m}, \quad 1 \text{ fermi} \sim 10^{-15} \text{ m}$$

$$\lambda_{\text{Planck}} \sim 10^{-35} \text{ m}$$

12. přednáška

Černá díra

• Teoretická předpověď – K. Schwarzschild

→ zobecnění Reimera: Schw. + rotace

1963 – Kerrova metrika (rotující objekt)

1930/31 Chandrasekhar

1939 Oppenheimer & Volkoff (TOV met.)
& Snyder

1964 Penrose („trapped surface“)

jádru galaxií – BH

Kosmologie

Zo'klodu' poroxoran'

$$1 \text{ pc} = 3,26 \text{ l.y.} = 206265 \text{ AU} = 3.09 \cdot 10^{18} \text{ cm}$$

galaxee ($10^7 \div 12$ kvird, $\phi 10^4 \div 6$ l.y.)
 $\odot \leftrightarrow \odot 10^{6 \div 7} \text{ l.y.}$

asociace : mish'sheynon

huy
mod huy (~~cluster~~ supercluster)

shox : $\sim 200 \text{ Mpc}$

$\sim$ porox. co'sh nemira $\sim 10^{12}$ galaxii'

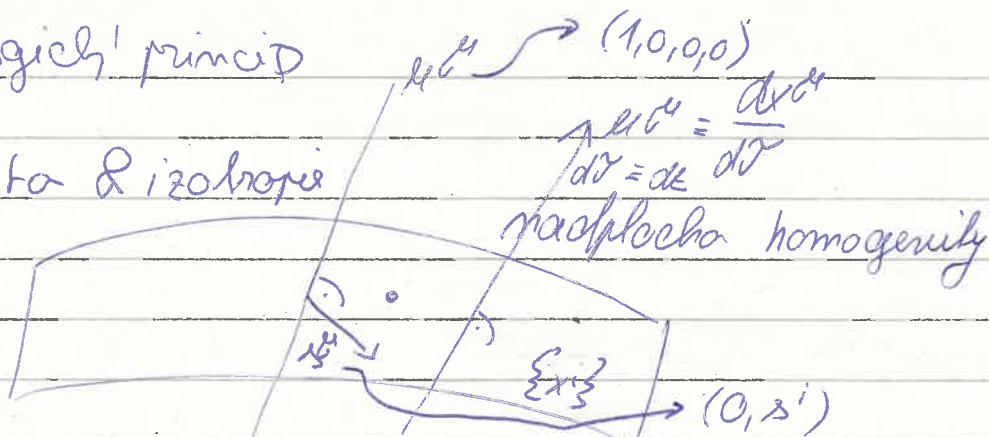
"Hubbleova xeyarso" $\alpha = H_0$
 $\uparrow$ modalenost

Hubblein oos $T \equiv \frac{L}{\alpha} = \frac{1}{H}$

relekh' zo'ren' (CMBR) ... 2,7 K

Kosmologický princíp

homogenita & izotropie



po každého pozorovateľa, kedy je v klidu voči „sebe“

$dt \sim$ približne vl. čeru kosmického času

$$g_{\mu\nu} x^\mu x^\nu = g_{0i} x^i \Rightarrow g_{0i} = 0$$

$$ds^2 = -dt^2 + \underbrace{g_{ij} dx^i dx^j}_{d\sigma^2}$$

→ aby sme vyhoveli predpokladu homogenity, tak máme byť schopní túto rovnicu podľa konstanty K = konst

$$K > 0, K < 0, K = 0$$

$$d\sigma^2 \stackrel{\mathbb{E}^3}{=} dr^2 + r^2(d\theta^2 + \sin^2\theta d\varphi^2)$$

3-sféra: možnosť do $\mathbb{E}^4$

3-hyperboloid: možnosť do Minkowskeho pr.

$$d\Sigma^2 = \sum_1^3 (dx^i)^2 \pm (dx^4)^2$$

$$\text{rovnica: } (x^4)^2 \pm \underbrace{\sum_1^3 (x^i)^2}_{r^2} = a^2$$

$$\left. \begin{aligned} x^1 &= r \sin\theta \cos\varphi \\ x^2 &= r \sin\theta \sin\varphi \\ x^3 &= r \cos\theta \end{aligned} \right\} \sum_1^3 (x^i)^2 = r^2$$

diferencijal namice po danom polju:

$$x^4 dx^4 \pm r dr = 0$$

$$\Rightarrow (dx^4)^2 = \frac{r^2 dr^2}{(x^4)^2} = \frac{r^2 dr^2}{a^2 \mp r^2}$$

$$\begin{aligned} \Rightarrow da^2 &= dr^2 + r^2 d\Omega \pm \frac{r^2 dr^2}{a^2 \mp r^2} = \\ &= \left(\frac{a^2 \pm r^2 \mp r^2}{a^2 \mp r^2} \right) dr^2 + r^2 d\Omega = \\ &= \frac{dr^2}{1 - K \frac{r^2}{a^2}} + r^2 d\Omega \end{aligned}$$

$K = \pm 1$: $K=1 \sim 3$ -sfera

$K=-1 \sim 3$ -hyperboloid

4D metrika:

$$ds^2 = -dt^2 + \frac{dr^2}{1 - K \frac{r^2}{a^2}} + r^2 d\Omega$$

transformace: $r := a \Sigma$

$$\Sigma \begin{cases} \sin \chi, & k=+1 \\ \chi, & k=0 \\ \sinh \chi, & k=-1 \end{cases}$$

$$ds^2 = -dt^2 + a^2 (d\chi^2 + \Sigma^2 d\Omega^2),$$

kde $a^2 = a(t)$

Friedmann - Lemaitre - Robertson - Walker metrika

FLRW metrika

$$ds^2 = -dt^2 + a^2(t) (dx^2 + \sum \alpha^2 \Omega^2)$$

Zdroj: $T^{\mu\nu} = (\rho + P)u^\mu u^\nu + P g^{\mu\nu}$
„kosmická ležetina“

$$\rho = \rho_{\text{materiá}} + \rho_{\text{záření}} \approx 10^{-4} \rho_{\text{materiá}}$$

$$P = \underbrace{P_{\text{materiá}}}_{\sim 0} + \underbrace{P_{\text{záření}}}_{\sim \frac{1}{3} \rho_{\text{záření}}}$$

$$\frac{P}{\rho c^2} \sim \frac{\frac{1}{3} \rho_{\text{záření}}}{\rho c^2} \sim 10^{-6}, \quad r \sim 10^{-3} c$$

Role ložty a záření:

(41-37)

rovnice kontinuity $\rightarrow T^{\mu\nu}_{;\nu} = 0$
Eulerova rovnice $\leftarrow$

Jura

$$\frac{d\rho}{dt} + (\rho + P)u^\nu_{;\nu} = 0$$

$$u^\nu_{;\nu} = \cancel{u^\nu_{;\nu}} + \Gamma^\nu_{\alpha\sigma} u^\sigma = \frac{1}{2} g^{\nu\alpha} (g_{\nu\sigma,\alpha} + g_{\alpha\sigma,\nu} - g_{\sigma\alpha,\nu}) u^\sigma =$$

$u^\sigma = (1, 0, 0, 0)$

$$= \frac{1}{2} g^{\nu\alpha} (g_{\nu\sigma,\alpha} + g_{\alpha\sigma,\nu} - g_{\sigma\alpha,\nu}) u^\sigma = \frac{1}{2} (g^{xx} g_{xx,t} + g^{yy} g_{yy,t} + g^{zz} g_{zz,t}) =$$
$$= \frac{1}{2} \left(\frac{g_{xx,t}}{g_{xx}} + \frac{g_{yy,t}}{g_{yy}} + \frac{g_{zz,t}}{g_{zz}} \right) = *$$

$$\textcircled{*} \frac{1}{2} (3a_{,t}^2)$$

$$\textcircled{*} = \frac{1}{2} (2 \cdot 3a_{,t})$$

$$\Rightarrow \rho_{,t} + 3(\rho + p) \frac{a_{,t}}{a} = 0$$

predpokladajme, že látka a záření je izotropní

$$\text{látka: } / a^3 \Rightarrow a^3 \rho_{,t} + 3a^2 a_{,t} \rho = 0$$

$$\rightarrow (\rho a^3)_{,t} = 0$$

$$\text{záření: } / a^4 \Rightarrow a^4 \rho_{,t} + 4a^3 a_{,t} \rho = 0$$

$$\rightarrow (\rho a^4)_{,t} = 0$$

Objem nespojitosti homogeneity:

$$V = \int_0^{2\pi} \int_0^\pi \int_0^{\chi_{\max}} \sqrt{g_{\chi\chi} g_{\theta\theta} g_{\varphi\varphi}} d\chi d\theta d\varphi = \textcircled{*}$$

$$k \leq 0 \quad \left\{ \begin{array}{l} \Sigma \leftarrow \begin{array}{l} \sin \chi \\ \chi \\ \sinh \chi \end{array} \quad \begin{array}{l} 0 \leq \chi \leq \pi \\ 0 \leq \chi < \infty \end{array} \end{array} \right.$$

$$\textcircled{*} = \int_0^{2\pi} \int_0^\pi \int_0^{\chi_{\max}} a^3(t) \Sigma^2 \sin \theta d\chi d\theta d\varphi =$$

$$= 2\pi a^3 \int_0^{\chi_{\max}} \Sigma^2 \sin \theta d\chi d\theta = 4\pi a^3 \int_0^{\chi_{\max}} \Sigma^2 d\chi =$$

$$= \begin{cases} k=+1 & \int_0^{\chi_{\max}} 4\pi a^3 \int_0^\pi \sin^2 \chi d\chi = 2\pi^2 a^3 \\ k=0, -1 & \int_0^{\chi_{\max}} 4\pi a^3 \int_0^\pi \sinh^2 \chi d\chi = \infty \end{cases}$$

13. přednáška

Minule: Kosmologický princip $\Rightarrow$ FLWR metrika

$$ds^2 = -dt^2 + a^2(t) (\frac{dr^2}{1-kr^2} + \sum_i^2 d\Omega_i^2)$$

$$\Sigma = \begin{cases} \sin \chi, k=1 \text{ (3-sféra)} \\ \chi, k=0 \text{ (}\mathbb{E}^3\text{)} \\ \sinh \chi, k=-1 \text{ (3-hyperboloid)} \end{cases}$$

$$T_{\mu\nu}^{\text{tot}} = (\rho + P) u_\mu u_\nu + P g_{\mu\nu}$$

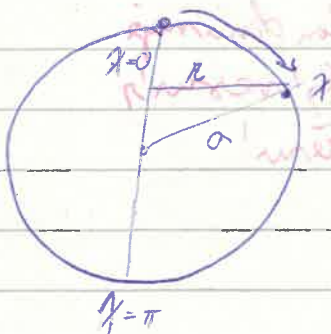
$$\rho = \rho_{\text{materi}} + \rho_{\text{záření}}$$

$$P = P_{\text{materi}} + P_{\text{záření}}$$

Einsteinovy rovnice:

$$\boxed{H^2 + \frac{kc^2}{a^2} = \frac{\Lambda c^2}{3} + \frac{8\pi}{3} G \rho} \quad \leftarrow \text{Friedmann}$$

$$H^2(1-2q) + \frac{kc^2}{a^2} = -\frac{\Lambda c^2}{3} - \frac{8\pi G}{3} \frac{P}{c^2}$$



$$r = \frac{dr}{dt} = \frac{d(a \sin \chi)}{dt} = a_{,t} \Delta \chi = \frac{a_{,t}}{a} \underbrace{a \Delta \chi}_L =$$

$$= H L$$

q ... deceleration parameter

$$q = -\frac{a a_{,tt}}{(a_{,t})^2}$$

Derivace 1. rovnice (Friedmannov):

$$\frac{2a_{,t} a_{,tt}}{a^2} - \frac{2(a_{,t})^3}{a^3} - \frac{2kc^2 a_{,t}}{a^3} = -\frac{8\pi G(\rho + \frac{P}{c^2})}{3} \frac{1}{H}$$

$$\frac{2a_{,tt}}{a} - 2\frac{(a_{,t})^2}{a^2} - \frac{2kc^2}{a^2} = -8\pi G(\rho + \frac{P}{c^2})$$

$$a_{,tt} = -\frac{(a_{,t})^2}{a} q$$

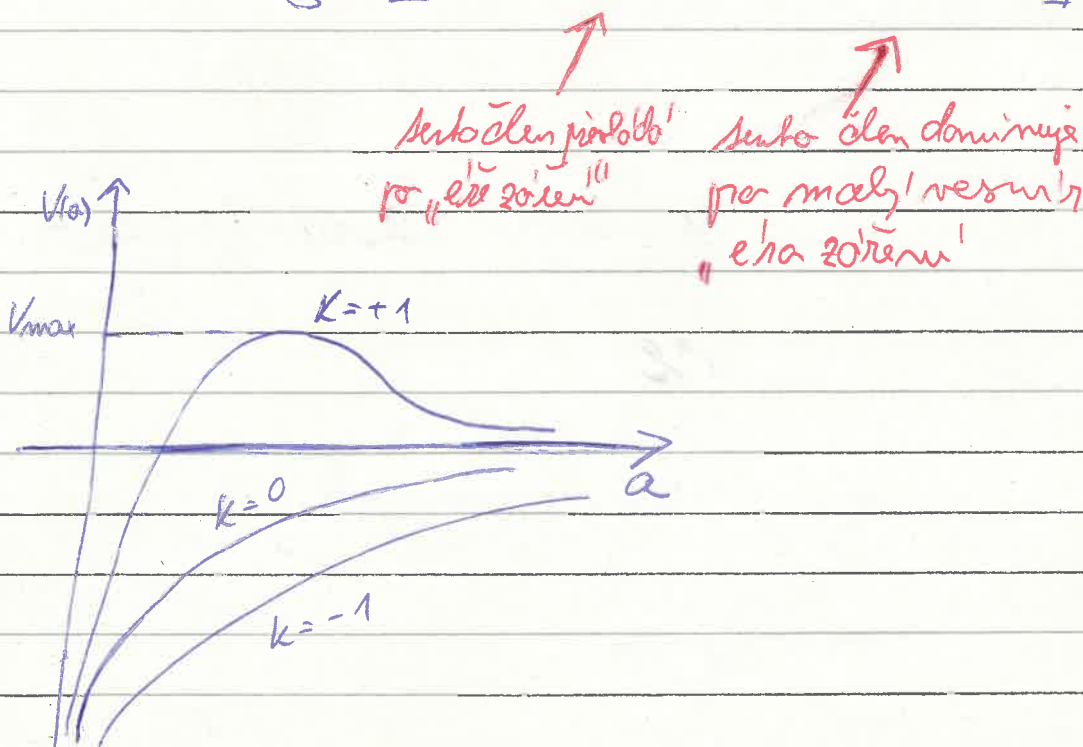
$$-2H^2 q - 2H^2 - \frac{2kc^2}{a^2} = -\Lambda c^2 - 3H^2 - \frac{3kc^2}{a^2} - 8\pi G \frac{P}{c^2}$$

$$H^2(1-2q) + \frac{kc^2}{a^2} = -\Lambda c^2 - 8\pi G \frac{P}{c^2}$$

Můžeme historie kosmického vývoje

$$H^2 = \frac{\Lambda c^2}{3} - V(a)$$

$$V(a) = \frac{kc^2}{a^2} - 8\pi G \left[\rho_{\text{materiálu}}(t_0) \left(\frac{a(t_0)}{a(t)} \right)^3 + \rho_{\text{záření}}(t_0) \left(\frac{a(t_0)}{a(t)} \right)^4 \right]$$

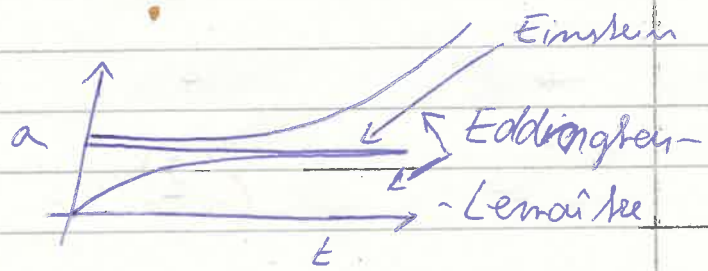


① $k = +1$

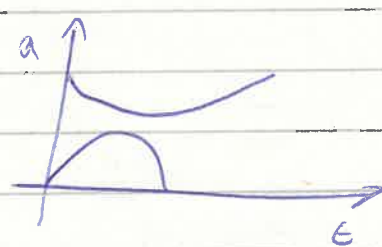
• $\frac{\Lambda c^2}{3} > V_{\max}(a)$



• $\frac{\Lambda c^2}{3} = V_{\max}(a)$



• $\frac{\Lambda c^2}{3} < V_{\max}(a)$

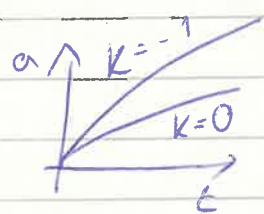


• $\frac{\Lambda c^2}{3} \leq 0$

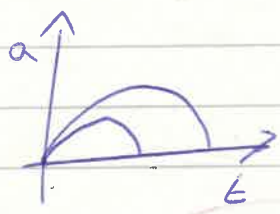


② $k = 0, -1$

• $\frac{\Lambda c^2}{3} \geq 0 \Rightarrow$



• $\frac{\Lambda c^2}{3} \leq 0 \Rightarrow$



Zatreni: $H^2 = \frac{8\pi G a_0^4}{3a^4} \rho_0$

$\rightarrow \sqrt{a} da = \sqrt{\frac{8\pi G}{3} a_0^4} dt$

$\rightarrow \frac{a}{a_0} = 2\sqrt{\frac{2\pi G}{3} \rho_0} t^{\frac{1}{2}}$

Latka: $H^2 = \frac{8\pi G a_0^3}{a^3} \rho_0$

$\rightarrow \sqrt{a} da = \sqrt{\frac{8\pi G}{3} a_0^3} dt$

$\rightarrow \frac{a}{a_0} = (6\pi G \rho_0)^{\frac{1}{3}} t^{\frac{2}{3}}$

Krivost: $H^2 = -\frac{kc^2}{a^2}$

$\rightarrow k = +1$ nebo

$k = 0 \quad a = \text{const}$

$k = -1 \quad a = ct$

$\perp: H^2 = \frac{1}{3} \frac{c^2}{a^2} \rightarrow$

$\rightarrow a = \text{const} \exp(\sqrt{\frac{1}{3}} ct)$

Friedmannov modely: $\Lambda = 0$

$$p_{\text{materi}} = 0 \quad (\Rightarrow P = 0)$$

$$cdt = a d\eta \Rightarrow ds^2 = a^2(\eta) [-d\eta^2 + dr^2 + \Sigma^2 (d\theta^2 + \sin^2\theta d\varphi^2)]$$

konformni čas

$$a(\eta) = KA [1 - C_k(\eta)]$$

$$t(\eta) = \frac{1}{c} \int a(\eta') d\eta' = \frac{KA}{c} [\eta - S_k(\eta)]$$

$$C_k \equiv \begin{cases} \cos \eta, & k = +1 \\ \cosh(\eta), & k = -1 \end{cases}$$

$$S_k(\eta) \equiv \begin{cases} \sin \eta, & k = +1 \\ \sinh \eta, & k = -1 \end{cases}$$

$$A = \frac{4\pi G}{3c^2} \rho_0 a_0^3$$

Reči o faktorih

Friedmannova rovnice $\cdot \frac{1}{H^2}$

$$1 + \Omega_k = \Omega_\Lambda + \Omega_L + \Omega_Z \quad (H, \rho, \Lambda, k)$$

$$(1 - 2q) + \Omega_k = 3\Omega_\Lambda - \Omega_Z \quad (\text{deceleracijská rovnice})$$

(H, q, Λ, k)

Dasen' der deceleration' n. 2 Fr. sowie:

$$q + \Omega_L = \frac{1}{2} \Omega_L + \Omega_2 (H, q, L, \rho) \quad (*)$$

~~1+q~~ $\swarrow$ $3(*) + \text{deceleration'}$

$$1+q + \Omega_k = \frac{3}{2} \Omega_L + 2\Omega_2 (H, q, \rho, k)$$

$$H = 70 \text{ km/s/Mpc} = 2,27 \cdot 10^{-18} / \text{s}$$

$$\Omega_L = \frac{8\pi G \rho_L}{3H^2} = \frac{\rho_L}{\rho_{krit}}$$

$$\Omega_2 = \frac{8\pi G \rho_2}{3H^2}, \quad \rho_{krit} = \frac{3H^2}{8\pi G} = 10^{-29} \text{ g/cm}^3$$

$$\Omega_L = \frac{\Lambda c^2}{3H^2} = \frac{\Lambda c^2}{8\pi G \rho_{krit}}$$

$$\Omega_k = \frac{kc^2}{H^2 a^2}$$

hauptsächlich "dies"

$$\Omega_L = 0,73 \quad (\Lambda = 1,3 \cdot 10^{-56} / \text{cm}^2)$$

$$\left. \begin{array}{l} \Omega_L = 0,27 \\ \Omega_2 = 5 \cdot 10^{-5} \end{array} \right\} \Rightarrow \Omega_k = 0$$

$$\Rightarrow q = -0.6$$

q je sukcintní akcelerační parametr

$$\Omega_L = 0.27 = \underbrace{\Omega_{\text{Fermiova'ho}}}_{0.23} + \underbrace{\Omega_{\text{Barionova'ho}}}_{0.04}$$

speciálně $\Omega_H = 0.03$
 $\Omega_{He} = 0.01$
 $\Omega_{\text{neutrinos}} < 10^{-3}$

Albersin paradox

dynamický vení → frekvencí poměr

