

2 přednáška: Klein-Gordon

Budeme uvažovat tzv. přirozené jednotky, tj.: $c = \hbar = 1$.

Značení: • čtyřvektory $x^\alpha = (x^0, \mathbf{x}) = (t, \mathbf{x})$

• čtyřhybnost $p^\alpha = (p^0, \mathbf{p}) = (E, \mathbf{p})$

• skalární součin: $x \cdot y = g_{\mu\nu} x^\mu y^\nu = x^\mu y_\mu = x_\mu y^\mu$

$$g_{\mu\nu} = g^{\mu\nu} = \text{diag}(1, -1, -1, -1)$$

Lorentzovské transformace jsou reprezentovány ~~na~~ prvky tzv. Lorentzovy grupy $SO(1,3)$.

$$x^\mu \xrightarrow{L} x'^\mu = L^\mu{}_\nu x^\nu, \quad x^\mu = L_\nu{}^\mu x'^\nu$$

Lorentzovy musejí zachovávat skalární součin; $x \cdot y = x' \cdot y'$,
odtud plynou podmínky:

$$g_{\mu\nu} L^\mu{}_\alpha L^\nu{}_\beta = g_{\alpha\beta}$$

$$g^{\mu\nu} L_\mu{}^\alpha L_\nu{}^\beta = g^{\alpha\beta}$$

$$\det(g_{\mu\nu} L^\mu{}_\alpha L^\nu{}_\beta) = \det(g_{\mu\nu}) \det^2(L^\mu{}_\alpha)$$

$$\rightarrow \det(L) = 1 \begin{cases} \det L = 1, \text{ vlastní Lorentzovy transformace} \\ \det L = -1, \text{ nevlátní Lorentzovy transformace} \end{cases}$$

• diferenciál $dx := dx^\mu \frac{\partial}{\partial x^\mu} \equiv dx^\mu \partial_\mu$

• 4-gradient $\partial_\mu := (\frac{\partial}{\partial x_0}, \nabla)$, $\partial^\mu := (\frac{\partial}{\partial x_0}, -\nabla)$

• d'Alembertian $\square := g^{\mu\nu} \partial_\mu \partial_\nu = \partial^\mu \partial_\mu = (\frac{\partial^2}{\partial x_0^2} - \nabla^2)$

Struktura Lorentzových transformací

Uvažujme infinitesimální transformace tvaru

$$\textcircled{*} L^{\mu}_{\nu} = \delta^{\mu}_{\nu} + \omega^{\mu}_{\nu}, \quad \|\omega^{\mu}_{\nu}\| \ll 1$$

Víme, že (obecně) platí $L^{\nu'}_{\mu'} L^{\mu}_{\alpha} = \delta^{\nu'}_{\alpha}$

$$\rightarrow (\delta^{\nu'}_{\mu'} + \omega^{\nu'}_{\mu'}) (\delta^{\mu}_{\alpha} + \omega^{\mu}_{\alpha}) = \delta^{\nu'}_{\alpha}$$

$\downarrow (\omega^2 \ll 1)$

$$\rightarrow \delta^{\nu'}_{\alpha} + \omega^{\nu'}_{\alpha} + \omega^{\mu}_{\alpha} \delta^{\nu'}_{\mu} = \delta^{\nu'}_{\alpha}$$

$$\rightarrow \omega_{\nu'\alpha} + \omega_{\alpha\nu'} = 0$$

$\rightarrow \omega$ je antisymetrická matice 4×4 s 6 reálnými parametry

(konkrétně) Lorentzovy transformace získáme pomocí generatorů Lorentzovy grupy:

$$L^{\rho}_{\sigma} = \exp\left(-\frac{i}{4} M^{\mu\nu} \omega_{\mu\nu}\right)^{\rho}_{\sigma}$$

$M^{\mu\nu}$ určuje 4 infinitesimální transformace porovnáme s $\oplus$

$$L^{\rho}_{\sigma} \sim \delta^{\rho}_{\sigma} - \frac{i}{4} (M^{\mu\nu})^{\rho}_{\sigma} \omega_{\mu\nu} \stackrel{!}{=} \delta^{\rho}_{\sigma} + \omega^{\rho}_{\sigma} =$$

$$= \delta^{\rho}_{\sigma} + \eta^{\rho\mu} \eta^{\nu}_{\sigma} \omega_{\mu\nu} = \delta^{\rho}_{\sigma} + \frac{1}{2} \eta^{\rho\mu} \delta^{\nu}_{\sigma} (\omega_{\mu\nu} - \omega_{\nu\mu}) =$$

$$= \delta^{\rho}_{\sigma} + \frac{1}{2} (\eta^{\rho\mu} \delta^{\nu}_{\sigma} - \eta^{\rho\nu} \delta^{\mu}_{\sigma}) \omega_{\mu\nu}$$

$$\rightarrow (M^{\mu\nu})^{\rho}_{\sigma} = 2i (\eta^{\rho\mu} \delta^{\nu}_{\sigma} - \eta^{\rho\nu} \delta^{\mu}_{\sigma})$$

Ukážeme nyní bezspinovou relativistickou částici,
popsanou vlnovou funkcí $\Phi(x, t)$.

Relativistická částice musí splňovat disperzní vztah

$$E = \sqrt{m^2 + p^2}$$

Pocítíme čtyřhybnost, le kterou elistuje relativistický
invariant:

$$p^\mu p_\mu = p_0^2 - p^2 = m^2,$$

lze psát:

$$(E^2 - p^2)\phi(x) = m^2\phi(x)$$

$$\text{QM: } E \leftrightarrow i \frac{\partial}{\partial t}, \quad p \leftrightarrow -i \nabla$$

$$\rightarrow \left(-\frac{\partial^2}{\partial t^2} - \nabla^2\right)\phi(x) = m^2\phi(x)$$

Pomocí 4 - gradientu $\partial_\mu = \left(\frac{\partial}{\partial t}, \nabla\right)$ lze přepsat rovnici jako

$$\partial^\mu \partial_\mu \phi = \square \phi = -m^2 \phi$$

$$\rightarrow (\square + m^2)\phi(x) = 0 \quad \text{Klein-Gordonova rovnice}$$

Její řešení pro volnou částici je:

$$\phi(x) = \int \frac{d^3p}{(2\pi)^3} \frac{1}{2\omega_p} \left(e^{-i\omega_p t + i\mathbf{p} \cdot \mathbf{x}} f(\mathbf{p}) + e^{i\omega_p t + i\mathbf{p} \cdot \mathbf{x}} g(\mathbf{p}) \right)$$

$$\omega_p = \sqrt{p^2 + m^2}$$

3. přednáška

Abychom mohli interpretovat ϕ jako vlnovou funkci, musíme mít normu $\|\cdot\|$, která se zachováá při časovém ústroji a je Lorentzovsky invariantní. Položíme

$$\|\phi\|^2 = (\phi, \phi) := i \int d^3x \left[\phi^*(x, t) \frac{\partial \phi}{\partial x^0}(x, t) - \frac{\partial \phi^*}{\partial x^0}(x, t) \phi(x, t) \right]$$

(Analogicky jako $\sim QM$: $J = i [\phi^* \nabla \phi - \phi \nabla \phi^*]$)

V duchu toho definujeme „4-moment“ jako:

$$J_{\mu} = \frac{i}{2m} [\phi^* \partial_{\mu} \phi - \phi \partial_{\mu} \phi^*]$$

(faktor $\frac{1}{2m}$ najistěji koulhe' nerekativistického limitu)

Tvrzení:

J_{μ} splňuje rovnici kontinuity, tj: $\partial^{\mu} J_{\mu} = 0$.

Důkaz:

$$\begin{aligned} \partial^{\mu} J_{\mu} &= \partial^{\mu} [\phi^* \partial_{\mu} \phi - \phi \partial_{\mu} \phi^*] = |\partial^{\mu} \phi|^2 + \phi^* \square \phi - |\partial^{\mu} \phi|^2 - \phi \square \phi^* = \\ &= \phi^* (-m^2 \phi) - \phi (-m^2 \phi^*) = 0 \end{aligned}$$

Nerekativistický limit

Předpokládejme: $\phi(x, t) = e^{-imt} \psi(x, t)$, kde ψ je nerekativistická vlnová funkce. Potom dosazením získáme NR limity jako:

$$J_{NR}(x) = \frac{i}{2m} [\psi^* \nabla \psi - \psi \nabla \psi^*], \quad \rho_{NR}(x) = \psi \psi^* = |\psi|^2$$

Tvrzení:

Norma $\|\phi\|^2 = i \int d^3x \rho(x, t)$ je časově nesolíska.

Důkaz:

$$\bullet \|\phi\|^2 = i \int d^3x \rho(x, t) = i \int d\Omega d\kappa \cdot \kappa^2 \rho(\eta, \Omega, t) < \infty$$

$$\rightarrow |\phi| \sim \frac{1}{\eta^{\frac{3}{2}+\varepsilon}} \quad (|\phi|^2 = |\psi|^2)$$

zovice kontinuity

$$\frac{d}{dt} \|\phi\|^2 = i \int d^3x \partial^0 J_0 \stackrel{\downarrow}{=} -i \int d^3x \nabla J = \lim_{\kappa \rightarrow +\infty} \int_{S^2(\eta)} d\Omega \cdot J \sim \lim_{\eta \rightarrow +\infty} \frac{1}{\eta^{2+\varepsilon}} = 0$$

Tvrzení:

Norma $\|\phi\|^2$ je Lorentzovsky skalar.

Důkaz:

$$\begin{aligned} \|\phi\|^2 &= \int d^3x \rho(x) = \int d^4x \delta(x_0) \rho(x) = \int d^4x \rho(x) \frac{\partial}{\partial x_0} \theta(x_0) = \\ &= \int d^4x J^{\mu 0} \partial_{\mu} \theta(m^a x_a), \quad m^a := (1, 0, 0, 0) \end{aligned}$$

Definujme nyní na obecný časově-podobný vektor m^a výraz

$$\|\tilde{\phi}\|^2 := \int d^4x J^{\mu \alpha} \partial_{\mu} \theta(m^a x_a).$$

$$\begin{aligned} \|\phi\|^2 - \|\tilde{\phi}\|^2 &= \int d^4x J^{\mu \alpha} \partial_{\mu} [\theta(m^a x_a) - \theta(m'^a x_a)] \stackrel{\partial_{\mu} J^{\mu \alpha} = 0}{=} \\ &= \int d^4x \partial_{\mu} [J^{\mu \alpha} (\theta(m^a x_a) - \theta(m'^a x_a))] \stackrel{\text{Gauss}}{=} \\ &= \int dS_{\mu} J^{\mu \alpha} (\theta(m^a x_a) - \theta(m'^a x_a)) \rightarrow 0 \end{aligned}$$

$J^{\mu \alpha} \rightarrow 0$ po $|x| \rightarrow \infty, t = \text{const}$

$\theta(m^a x_a) - \theta(m'^a x_a) \rightarrow 0$ po $|t| \rightarrow \infty, x = \text{const}$

Pomocí 4-věty lze zapsat řešení Klein-Gordonovy rovnice v následující kompaktní tvaru:

$$\phi(x) = \int \frac{d^3p}{(2\pi)^3 2\omega_p} (f(p) e^{-ip \cdot x} + g(p) e^{ip \cdot x})$$

Tvrzení:

Norma $\|\phi\|^2$ je semi-definitivní.

Důkaz:

$$\begin{aligned} \|\phi\|^2 &= i \int d^3x \left\{ \left[\int \frac{d^3p}{(2\pi)^3 2\omega_p} (f^*(p) e^{ip \cdot x} + g^*(p) e^{-ip \cdot x}) \right] \right. \\ &\quad \cdot \left[\int \frac{d^3q}{(2\pi)^3 2\omega_q} (f(q) (-i\omega_q) e^{-iq \cdot x} + g(q) (i\omega_q) e^{iq \cdot x}) \right] - \\ &\quad \left. - \left[\int \frac{d^3q}{(2\pi)^3 2\omega_q} (f^*(q) e^{-iq \cdot x} + g^*(q) e^{iq \cdot x}) \right] \cdot \right. \\ &\quad \left. \cdot \left[\int \frac{d^3p}{(2\pi)^3 2\omega_p} (f^*(p) (i\omega_p) e^{ip \cdot x} + g^*(p) (-i\omega_p) e^{-ip \cdot x}) \right] \right\} \end{aligned}$$

Norma je časově nezávislá, a proto členy typu $e^{\pm i(\omega_p + \omega_q)x}$ musí zmizet (odločou se).

$$\begin{aligned} \|\phi\|^2 &= i \int \frac{d^3x}{1} \int \frac{d^3p d^3q}{(2\pi)^6 2\omega_p 2\omega_q} \left[(f^*(p) f(q) (-i\omega_q) e^{ix(p-q)} + \right. \\ &\quad \left. + g^*(p) g(q) (-i\omega_q) e^{-ix(p-q)}) - (f^*(q) f^*(p) (i\omega_p) e^{ix(p-q)} + \right. \\ &\quad \left. + g(q) g^*(p) (-i\omega_p) e^{-ix(p-q)}) \right] = \\ &= \int \frac{d^3p}{(2\pi)^3} (|f(p)|^2 - |g(p)|^2) \end{aligned}$$

4. přednáška: Diracova rovnice

Hledáme alternativní relativistickou rovnici, která
inkluduje pozitivně definitní normu.

$$\rho = T_0 = i (\phi^* \overleftrightarrow{\partial} \phi - \phi \overleftrightarrow{\partial} \phi^*)$$

↑
vol'ným mínus

"mínus" reprezentuje dva způsoby, jak propagovat derivaci ∂

Dirac:

Mínus lze odstranit, pokud bude hledaná rovnice
Lorentzovsky kovariantní a lineární + časové derivaci
(tj.: obsahující pouze první časovou derivaci)

Zobovření musí platit:

- i) produkce $T_{\mu\nu}$: $\partial^\mu T_{\mu\nu} = 0$
- ii) $\rho = T_0$ je pozitivně definitní

Ansatz:

$$(i \gamma^0 \partial_0 + i \gamma^1 \partial_1 + i \gamma^2 \partial_2 + i \gamma^3 \partial_3) \psi = m \psi$$

$$\rightarrow (i \gamma^\mu \partial_\mu - m) \psi = 0$$

$$\cancel{\text{nebo}} (i \not{\partial} - m) \psi = 0 \quad (\text{Feynmanův slash})$$

$$\text{Navíc musí platit } (\square + m^2) \psi = 0$$

Jestliže ψ splňuje obě rovnice současně, musí existovat
nějaký vnitřní stupeň volnosti (extra podmínka pro ψ)

$$(\square + m^2)\Psi = 0, \quad (i\partial - m)\Psi = 0$$

$$\bullet (i\partial + m)(i\partial - m)\Psi = 0$$

$$\rightarrow (\gamma^\mu \gamma^\nu \partial_\mu \partial_\nu + m^2)\Psi = 0 \quad \text{přejmenování indexů} \quad [\partial_\nu, \partial_\mu] = 0$$

$$\begin{aligned} \gamma^\mu \gamma^\nu \partial_\mu \partial_\nu &= \frac{1}{2} \gamma^\mu \gamma^\nu \partial_\mu \partial_\nu + \frac{1}{2} \gamma^\nu \gamma^\mu \partial_\nu \partial_\mu = \\ &= \frac{1}{2} (\gamma^\mu \gamma^\nu + \gamma^\nu \gamma^\mu) \partial_\nu \partial_\mu = \frac{1}{2} \{\gamma^\mu, \gamma^\nu\} \partial_\mu \partial_\nu = \square \end{aligned}$$

$$\rightarrow \frac{1}{2} \{\gamma^\mu, \gamma^\nu\} = \gamma^{\mu\nu}$$

Diracovo odvození

$$i\partial_0 \Psi = \underbrace{\left[\frac{1}{2} \alpha \cdot \nabla + \beta m \right]}_{H_D - \text{Diracův Hamiltonian}} \Psi = H_D \Psi$$

$$\begin{aligned} i\partial_0 (i\partial_0 \Psi) &= -\partial_0^2 \Psi = H_D^2 \Psi \rightarrow \begin{cases} \{\alpha^i, \alpha^j\} = 0, & i \neq j \\ \{\alpha^i, \beta\} = 0, \\ \alpha^i{}^2 = \mathbb{I} \\ \beta^2 = \mathbb{I} \end{cases} \quad \left. \begin{matrix} \alpha(\alpha^i) = \alpha(\beta) = \{\pm 1\} \end{matrix} \right\} \end{aligned}$$

Porovnáním oba odvození získáme:

$$(i\gamma^0 \partial_0 + i\gamma^i \partial_i) \Psi = m \Psi$$

$$(\gamma^0)^{-1} (i\gamma^0 \partial_0 + i\gamma^i \partial_i) \Psi = (i\partial_0 + i(\gamma^0)^{-1} \gamma^i \partial_i) \Psi = m (\gamma^0)^{-1} \Psi$$

$$\begin{aligned} i\partial_0 \Psi &= \left[\frac{1}{2} (\gamma^0)^{-1} \gamma^i \partial_i + (\gamma^0)^{-1} m \right] \Psi \rightarrow \alpha^i = (\gamma^0)^{-1} \gamma^i, \beta = (\gamma^0)^{-1} \\ &\rightarrow (\gamma^0)^2 = \mathbb{I} \Rightarrow \gamma^0 = (\gamma^0)^{-1} \end{aligned}$$

Poznámka:

Algebra $\{\gamma^\mu, \gamma^\nu\} = 2\gamma^{\mu\nu}\mathbb{I}$ se nazývá Diracova algebra.
Clifordova algebra $CL_{1,3}(\mathbb{R})$

Minimální dimenze α^i, β matice v $(1+3)D$ je $d=4$.
 $\det(\alpha^i \alpha^i) = \det(-\alpha^i \alpha^i) = (-1)^d \det(\alpha^i \alpha^i) \rightarrow (-1)^d = 1$
 $\det(\alpha^i \beta) = \det(-\beta \alpha^i) = (-1)^d \det(\beta \alpha^i) \rightarrow (-1)^d = 1$

$\rightarrow d$ je sudé

pro $d=2$ existuje však jediná Clifordova algebra
Hermitovských matic 2×2 , které antikomutují a
to je algebra Pauliho matic, kterých jsou 3, my
však potřebujeme 4: α^i, β

Proto první kandidátem je $d=4$.

Tvrzení:

Pro $d=4$ existují netriviální 4×4 matice γ^μ .

Důkaz:

Diracova reprezentace γ -matic:

$$\gamma^0 = \begin{pmatrix} \mathbb{I} & 0 \\ 0 & -\mathbb{I} \end{pmatrix}, \quad \gamma^i = \begin{pmatrix} 0 & \alpha^i \\ -\alpha^i & 0 \end{pmatrix}$$

$$\gamma^0 = \alpha_3 \otimes \mathbb{I}, \quad \gamma^i = i\alpha_2 \otimes \alpha^i$$

Poznámka: $(A \otimes B) \cdot (C \otimes D) = (A \cdot C) \otimes (B \cdot D)$

$$\alpha^i \alpha^j = \delta^{ij} + i \epsilon^{ijk} \alpha^k$$

5. přednáška

Kovariance Diracovy rovnice (Lorentzova)

Poznámka:

Rotační a nerelativistické $\mathcal{SH}$ pro Weyler spinor $\Psi = \begin{pmatrix} \uparrow \\ \downarrow \end{pmatrix}$:

$$\Psi_a(x) \xrightarrow{R} \Psi_{R,a}(x) = D(R)_{ab} \Psi_b(R^{-1}x)$$

Podobně pro Lorentzovsky transformovanou vlnovou funkci předpokládáme

$$\Psi(x) \xrightarrow{L} \Psi_L(x) = S(L) \Psi(L^{-1}x)$$

Chceme ukázat, že pokud $\Psi(x)$ je řešením $(i\gamma^\mu \partial_\mu - m)\Psi(x) = 0$,
pak také $\Psi_L(x)$ je řešením $(i\gamma^\mu \partial_\mu - m)\Psi_L(x) = 0$.

$$0 \stackrel{?}{=} (i\gamma^\mu \partial_\mu - m)\Psi_L(x) = (i\gamma^\mu \partial_\mu - m)S(L)\Psi(L^{-1}x) =$$

$$= S(L)[iS^{-1}(L)\gamma^\mu \partial_\mu S(L) - m]\Psi(\underbrace{L^{-1}x}_{x'}) = 0$$

$$\text{Pokud } S^{-1}(L)\gamma^\mu \partial_\mu S(L) \stackrel{?}{=} \gamma^\mu \partial'_\mu = \gamma^\mu \frac{\partial}{\partial x'^\mu} \rightarrow S(L)[i\gamma^\mu \partial'_\mu - m]\Psi(x') = 0$$

Potomáme obě strany: $x'^\mu = (L^{-1})^\mu_\nu x^\nu \Leftrightarrow x^\nu = L^\nu_\mu x'^\mu$

$$\partial'_\mu = \frac{\partial}{\partial x'^\mu} = \underbrace{\frac{\partial x^\nu}{\partial x'^\mu}}_{L^\nu_\mu} \frac{\partial}{\partial x^\nu}$$

$$\rightarrow S^{-1}(L)\gamma^\mu \partial_\mu S(L) \stackrel{!}{=} \gamma^\mu L^\nu_\mu \frac{\partial}{\partial x^\nu}$$

$$\rightarrow S^{-1}(L)\gamma^\nu S(L) \stackrel{!}{=} \gamma^\mu L^\nu_\mu = L^\nu_\mu \gamma^\mu$$

Lorentzova grupa

i) vlasti Lorentzova grupa $\rightarrow \det L = 1$ $\left\{ \begin{array}{l} L^0_0 \geq 1, \text{Ortochronni} \\ L^0_0 < -1, \text{Neortochronni} \end{array} \right\}$ Kompletni Lorentzova grupa
 neortochroni Lorentzova grupa $\rightarrow \det L = -1$ $\left\{ \begin{array}{l} L^0_0 \geq 1, \text{Ortochronni} \\ L^0_0 < -1, \text{Neortochronni} \end{array} \right\}$

ii) $\eta^{\mu\nu} = L^\mu_\alpha L^\nu_\beta \eta^{\alpha\beta}$

$\rightarrow \eta^{00} = 1 = L^0_\alpha L^0_\beta \eta^{\alpha\beta} = (L^0_0)^2 - \sum_{i=1}^3 (L^0_i)^2 \rightarrow (L^0_0)^2 = 1 + \sum_{i=1}^3 (L^0_i)^2 \geq 1$

$\rightarrow |L^0_0| \geq 1$

iii) Lorentzova grupa je 6-parametrična ($\omega_{\alpha\beta} = -\omega_{\beta\alpha}$)

$L^\mu_\nu = \exp(-\frac{i}{4} \omega_{\alpha\beta} (M^{\alpha\beta})^\mu_\nu)$

$(M^{\alpha\beta})^\mu_\nu \neq 0 \iff \mu = \alpha, \nu = \beta \text{ or } \mu = \beta, \nu = \alpha$ $\left\{ \begin{array}{l} \text{Fundamentální (definující)} \\ \text{representace Lorentzovy grupy} \end{array} \right\}$

$[M^{\alpha\beta}, M^{\mu\nu}] = 2i (\eta^{\alpha\mu} M^{\beta\nu} - \eta^{\beta\mu} M^{\alpha\nu} - \eta^{\alpha\nu} M^{\beta\mu} + \eta^{\beta\nu} M^{\alpha\mu})$
 (Fundamentální algebra)

Poznámka: Rotací grupa

$R_{ij} = \exp(-i\theta_m \cdot J)_{ij}$, $[J_i, J_k] = i \epsilon_{ikl} J_l$ $\left\{ \begin{array}{l} \text{strukturální konstanty} \\ \text{Fundamentální} \\ \text{representace rotační grupy} \end{array} \right\}$

$J_1 = i \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}, J_2 = i \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix}, J_3 = i \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$(J_i)_{kl} = i \epsilon_{ikl}$ (Adjungované representace)

Poznamka: Vektorový operátor

$$U^\dagger(R) V_k(x) U(R) = R_{ki} V_i$$

$\uparrow$ Matrix rotací
Fundamentální reprezentace

$$(S^{-1}(L) \gamma^\mu S(L) = L^\nu{}_\mu \gamma^\mu)$$

→ Infinitesimální charakteristické rotace $\mathbb{I}$

$$R_{ij} = \exp(-i \theta \omega_k J_k)_{ij}$$

$$U(R) = \exp(-i \omega_k J_k)$$

$$(\mathbb{I} + i \omega_k J_k) V_k(x) (\mathbb{I} - i \omega_k J_k) = (\delta_{ki} - i \omega_k (J_k)_{ki}) V_i$$

$$\rightarrow i \omega_k [J_k, V_k] = -i \omega_k (J_k)_{ki} V_i \rightarrow [J_k, V_k] = - (J_k)_{ki} V_i = i \epsilon_{kik} V_i$$

$$\rightarrow [J_k, V_k] = i \epsilon_{kik} V_i$$

Triviální důsledek je, že J_m je vektorový operátor.

Alternativní (uvážlivě) reprezentace Lorentzovy grupy

$$i) M^{ij}, \quad i, j = 1, 2, 3$$

$$\textcircled{*} [M^{12}, M^{13}] = 2i M^{23}$$

$$\textcircled{\oplus} [M^{23}, M^{12}] = -2i M^{32}$$

$$\text{Definujeme } J_i := \frac{1}{4} \epsilon_{ijk} M^{jk} \Leftrightarrow M^{jk} = \frac{1}{2} \epsilon^{jki} J_i$$

$$\frac{1}{4} \epsilon_{ijk} M^{jk} = \frac{1}{2} \epsilon_{ijk} \epsilon^{jkl} J_l = \frac{1}{2} \cdot 2 \delta_i^l J_l = J_i \quad \checkmark$$

~~$$[2J_3, (-2)J_2] = 4iJ_1 \Leftrightarrow -[J_3, J_2] = iJ_1 = [J_2, J_3]$$~~

$$(*) [2J_3, (-2)J_2] = 4iJ_1 \Leftrightarrow -[J_3, J_2] = iJ_1 = [J_2, J_3]$$

$$(\#) [2J_1, 2J_3] = -4iJ_2 \Leftrightarrow [J_1, J_3] = -iJ_2$$

$$\rightarrow [J_i, J_k] = i\epsilon_{ijk} J_j$$

Lorentzova grupa obsahuje grupy rotací (3 parametry)

$$M_{10} = iK_1 = -M^{10} = M^{01}$$

$$[M^{01}, M^{02}] = -4iJ_3 \rightarrow [K_1, K_2] = -iJ_3$$

$$\rightarrow [K_i, K_j] = -i\epsilon_{ijk} J_k$$

Boosty nejsou urovňené (grupové)!

$$\rightarrow [J_i, K_j] = i\epsilon_{ijk} K_k$$

6. přednáška

Chceme uložit $\underbrace{S^{-1}(L)}_{S(L^{-1})} \gamma^\mu S(L) = L^\mu_\nu \gamma^\nu$

↗ Vjebo' representaci

Typy komutačních relací:

- i) $[M^{\mu\nu}, M^{\rho\sigma}] = 2i(\eta^{\mu\rho} M^{\nu\sigma} + \eta^{\nu\sigma} M^{\mu\rho} - \eta^{\mu\sigma} M^{\nu\rho} - \eta^{\nu\rho} M^{\mu\sigma})$ Definiční representace
- ii) $[J_i, J_j] = i\epsilon_{ijk} J_k$, $M^{ij} = 2\epsilon^{ijk} J_k$
 $[K_i, K_j] = -i\epsilon_{ijk} J_k$, $M^{0i} = 2K_i$
 $[J_i, K_j] = i\epsilon_{ijk} K_k$ } Fyzikální representace

iii) Matematická representace:

$$N_k := \frac{1}{2} [J_k + iK_k], \quad N_k^\dagger = \frac{1}{2} [J_k - iK_k] \quad (n, m)$$

$$\underbrace{\mathfrak{su}(2) \oplus \mathfrak{su}(2)}_{\hookrightarrow \Sigma N_i^2 = n(n+1)\mathbb{I}} \rightarrow \Sigma (N_i^\dagger)^2 = m(m+1)\mathbb{I}$$

Tvrzení:

$$[N_i, N_j^\dagger] = 0, \quad [N_i, N_j] = i\epsilon_{ijk} N_k, \quad [N_i^\dagger, N_j^\dagger] = i\epsilon_{ijk} N_k^\dagger$$

Důkaz:

Dosazení

Casimirův operátor = operátor, který komutuje se všemi prvky algebry

Poznámka:

$$J_k = N_k + N_k^\dagger \rightarrow J = m + m : \text{spin } 0 : (0, 0)$$

↗ Left-handed
↘ Right-handed

$$\text{spin } \frac{1}{2} : (\frac{1}{2}, 0), (0, \frac{1}{2})$$

↑
Allas' moment hybridy

Kovariance Diracovy rovnice

$$S^{-1}(L) \gamma^\mu S(L) = L^\mu_\nu \gamma^\nu$$

Pořadujeme:

i) $S(L_1 L_2) = S(L_1) S(L_2)$

Je kompatibilní s grupou m. sklopním

$$\begin{aligned} [S(L_1 L_2)]^{-1} \gamma^\mu S(L_1 L_2) &= S^{-1}(L_2) S^{-1}(L_1) \gamma^\mu S(L_1) S(L_2) = L_1^\mu_\nu S^{-1}(L_2) \gamma^\nu S(L_2) = \\ &= L_1^\mu_\nu L_2^\nu_\alpha \gamma^\alpha = (L_1 L_2)^\mu_\alpha \gamma^\alpha \end{aligned}$$

• Infinitesimalní verze $\rightarrow$ generátory

$$L = \exp(-\frac{i}{4} \omega_{\alpha\beta} M^{\alpha\beta})$$

lze kalorou podléhat splnit?

$$S(L) = \exp(-\frac{i}{4} \omega_{\alpha\beta} \sigma^{\alpha\beta})$$

existuje kaloro a?

$$(\mathbb{I} + \frac{i}{4} \omega_{\alpha\beta} \sigma^{\alpha\beta}) \gamma^\mu (\mathbb{I} - \frac{i}{4} \omega_{\alpha\beta} \sigma^{\alpha\beta}) = (\delta^\mu_\nu + \frac{i}{2} \omega^\mu_\nu) \gamma^\nu$$

$$\rightarrow \frac{i}{4} [\omega_{\alpha\beta} \sigma^{\alpha\beta}, \gamma^\mu] = \omega^\mu_\nu \gamma^\nu$$

valisej se pouze anti-symetricko část

$$\rightarrow \frac{i}{4} \omega_{\alpha\beta} [\sigma^{\alpha\beta}, \gamma^\mu] = \omega_{\alpha\beta} \gamma^{\alpha\mu} \gamma^\beta = \omega_{\alpha\beta} \frac{1}{2} [\gamma^{\alpha\mu} \gamma^\beta - \gamma^{\beta\mu} \gamma^\alpha]$$

$$\rightarrow \frac{i}{4} [\sigma^{\alpha\beta}, \gamma^\mu] = \frac{1}{2} [\gamma^{\alpha\mu} \gamma^\beta - \gamma^{\beta\mu} \gamma^\alpha]$$

Tvrzení:

$$\sigma^{\alpha\beta} = \frac{i}{2} [\gamma^\alpha, \gamma^\beta] \leftarrow \text{nová mjetonová reprezentace}$$

Důkaz:

$$[AB, C] = A[B, C] - [A, C]B$$

$$\begin{aligned} \frac{i}{4} \{ \frac{i}{2} [\gamma^\alpha \gamma^\beta, \gamma^\mu] - \frac{i}{2} [\gamma^\beta \gamma^\alpha, \gamma^\mu] \} &= -\frac{1}{8} [\gamma^\alpha \gamma^\beta \gamma^\mu - \gamma^\beta \gamma^\alpha \gamma^\mu - \gamma^\beta \gamma^\alpha \gamma^\mu + \gamma^\alpha \gamma^\beta \gamma^\mu] = \\ &= \dots = \frac{1}{2} [\gamma^\beta \gamma^\alpha \gamma^\mu - \gamma^\alpha \gamma^\beta \gamma^\mu] \end{aligned}$$

Tím je dokázána kovariance Diracovy rovnice.

7. přednáška

Diracovy bi-linearity

$$\Psi(x) = \begin{pmatrix} \psi_1(x) \\ \psi_2(x) \\ \psi_3(x) \\ \psi_4(x) \end{pmatrix} \mapsto \Psi^{*+}(x) = (\psi_1^*(x), \psi_2^*(x), \psi_3^*(x), \psi_4^*(x))$$

$$\text{Spinor adjoint stav: } \bar{\Psi}(x) := \Psi^{*+} \cdot \gamma^0$$

• Jak se transformuje $\bar{\Psi}(x)$ vzhledem k Lorentzově grupě?

$$\begin{aligned} \Psi(x) &\mapsto \Psi_L(x) = S(L) \Psi(L^{-1}x) \\ \Psi^\dagger(x) &\mapsto \Psi_L^\dagger(x) = \Psi^\dagger(L^{-1}x) S^{*+}(L) \end{aligned}$$

$$\bar{\Psi}(x) \mapsto \bar{\Psi}_L(x) = ?$$

Poznámka:

$$\bullet S(L) = \exp(-i\omega_{\alpha\beta} \sigma^{\alpha\beta}) \rightarrow S^\dagger(L) = \exp(i\omega_{\alpha\beta} [\sigma^{\alpha\beta}]^\dagger)$$

$$\rightarrow \sigma^{\alpha\beta} = \frac{i}{2} [\gamma^\alpha, \gamma^\beta] \rightarrow (\sigma^{\alpha\beta})^\dagger = -\frac{i}{2} [\gamma^{\alpha\dagger}, \gamma^{\beta\dagger}] = \frac{i}{2} [\gamma^{\alpha\dagger}, \gamma^{\beta\dagger}]$$

$$\bullet i\partial_0 \Psi = -i\gamma^0 \gamma^i \partial_i \Psi - m\gamma^0 \Psi = H_D \Psi \rightarrow$$

$$H_D = H_D^\dagger \Rightarrow \gamma^0 = \gamma^{0\dagger}, \gamma^{i\dagger} = \gamma^i = -\mathbb{I} \gamma^i = -\gamma^0 \gamma^0 \gamma^i = \gamma^0 \gamma^i \gamma^0$$

$$\rightarrow \gamma^0 \gamma^0 \gamma^0 = \gamma^{0\dagger}$$

$$\rightarrow \gamma^0 \gamma^{\alpha\dagger} \gamma^0 = (\gamma^\alpha)^\dagger$$

$$\begin{aligned} \rightarrow \gamma^0 S^\dagger(L) \gamma^0 &= \exp(i\omega_{\alpha\beta} \gamma^0 (\sigma^{\alpha\beta})^\dagger \gamma^0) = \exp(i\omega_{\alpha\beta} \sigma^{\alpha\beta}) = \\ &= S^{-1}(L) = S(L^{-1}) \end{aligned}$$

$$\rightarrow \boxed{S^{-1}(L) = \gamma^0 S^\dagger(L) \gamma^0}$$

Transformace $\bar{\Psi}$:

$$\bar{\Psi}(x) \xrightarrow{L} \bar{\Psi}_L(x) = \bar{\Psi}^\dagger(L^{-1}x) \overset{\gamma^0}{S^\dagger(L)} \gamma^0 = \bar{\Psi}(L^{-1}x) S(L^{-1}) = \bar{\Psi}(L^{-1}x) S^{-1}(L)$$

Skalární pole

$$S(x) := \bar{\Psi}(x) \Psi(x) \xrightarrow{L} \bar{\Psi}_L(x) \Psi_L(x) = \bar{\Psi}(L^{-1}x) \underbrace{S^{-1}(L) S(L)}^{\mathbb{I}} \Psi(L^{-1}x) = S(L^{-1}x)$$

$$\rightarrow S(x) \xrightarrow{L} S_L(x) = S(L^{-1}x)$$

(transformační vlastnost skalárního pole)

Vektorové pole (nektorové pole)

$$J^\mu(x) := \bar{\Psi}(x) \gamma^\mu \Psi(x) \xrightarrow{L} \bar{\Psi}_L(x) \gamma^\mu \Psi_L(x) = \bar{\Psi}(L^{-1}x) \overset{S(L)}{S^{-1}(L)} \gamma^\mu \Psi(L^{-1}x) = L^\mu_\nu J^\nu(L^{-1}x)$$

$$\rightarrow J^\mu(x) \xrightarrow{L} J_L^\mu(x) = L^\mu_\nu J^\nu(L^{-1}x)$$

(transformační vlastnost vektorového pole)

Pseudoskalár

- Skalár vzhledem k rotačním, otáčivým transformacím.
- Změní se měří při paritních transformacích.

$$\gamma^5 := i \gamma^0 \gamma^1 \gamma^2 \gamma^3 : i) \gamma^5 = \begin{pmatrix} 0 & \mathbb{I} \\ \mathbb{I} & 0 \end{pmatrix} = \sigma^1 \otimes \mathbb{I} \text{ (Diracově reprezentaci)}$$

$$ii) (\gamma^5)^2 = \mathbb{I}$$

$$iii) \gamma^5 = (\gamma^5)^\dagger$$

$$iv) \{\gamma^5, \gamma^\mu\} = 0$$

$$v) \gamma^5 = \frac{i}{4!} \epsilon_{\mu\nu\alpha\beta} \gamma^\mu \gamma^\nu \gamma^\alpha \gamma^\beta$$

$$\begin{aligned}
 P(x) &:= \bar{\Psi}(x) \gamma^5 \Psi(x) \xrightarrow{L} \bar{\Psi}_L(x) \gamma^5 \Psi_L(x) = \bar{\Psi}(L^{-1}x) S^{-1}(L) \gamma^5 S(L) \Psi(L^{-1}x) = \\
 &= \frac{1}{4!} \epsilon_{\alpha\beta\gamma\delta} \bar{\Psi}(L^{-1}x) L_{\alpha'}^{\alpha} L_{\beta'}^{\beta} L_{\gamma'}^{\gamma} L_{\delta'}^{\delta} \gamma^{\alpha'} \gamma^{\beta'} \gamma^{\gamma'} \gamma^{\delta'} \Psi(L^{-1}x) = \\
 &= \frac{1}{4!} \epsilon_{\alpha\beta\gamma\delta} \underbrace{\epsilon^{\alpha'\beta'\gamma'\delta'} L_{\alpha'}^{\alpha} L_{\beta'}^{\beta} L_{\gamma'}^{\gamma} L_{\delta'}^{\delta}}_{\det L} \bar{\Psi}(L^{-1}x) \gamma^5 \Psi(L^{-1}x) = \\
 &= (\det L) P(L^{-1}x)
 \end{aligned}$$

$$\epsilon^{\alpha\beta\gamma\delta} \gamma^5 = i \gamma^{\alpha} \gamma^{\beta} \gamma^{\gamma} \gamma^{\delta} \text{ (pořadí jsou } \alpha, \beta, \gamma, \delta \text{ různé)}$$

$P(x)$ je pseudo skalární pole

Podobným způsobem lze vytvořit pseudoskalar $J_5^P = J_5^P = \bar{\Psi} \gamma^5 \Psi$

Typické leusore' reličiny mají strukturu $\bar{\Psi} \Gamma^A \Psi$,

$$\Gamma^A := \underbrace{\{ \mathbb{I}, \gamma^5, \gamma^{\mu}, [\gamma^{\mu}, \gamma^{\nu}], \gamma^{\mu} \gamma^5 \}}_{16 \text{ matric}}$$

Vlastnosti Γ^A matric:

- i) $\text{Tr}(\Gamma) = 0$, kromě $\mathbb{I}$
- ii) $\text{Tr}(\Gamma_1 \Gamma_2) = 0$, $\Gamma_1 \neq \Gamma_2$
- iii) $\text{Tr}((\Gamma^A)^2) = \pm 4$
- iv) $\Gamma_1 \Gamma_2 = -\Gamma_2 \Gamma_1$, kromě $\mathbb{I}$
- v) $\sum_{i=1}^6 a_i \Gamma_i = 0 \Leftrightarrow a_i = 0, \forall i \in \{1, \dots, 16\}$
 $\rightarrow \Gamma^A$ tvoří bázi $\mathbb{C}^{4,4}$

Semam bilineari:

$\bar{\psi}\psi$	Skalar
$\bar{\psi}\gamma^5\psi$	Pseudoskalar
$\bar{\psi}\gamma^\mu\psi$	Vektor
$\bar{\psi}\gamma^\mu\gamma^5\psi$	Pseudovektor
$\bar{\psi}[\gamma^\mu, \gamma^\nu]\psi$	Antisymmetrisch' tensor 2. rade

8. přednáška

(Proraděpodobnosti) proudy po Diracovu částece

Přirození kandidáti: $\bar{\Psi} \gamma^\mu \Psi$, $\bar{\Psi} \gamma^\mu \gamma^5 \Psi$

$$\rightarrow (\Psi, \Psi) = \|\Psi\|^2 = \int d^3x J^0(x) = \int dV \underbrace{m_\mu}_{d\Sigma_\mu} J^\mu(x)$$

$$\rightarrow = \int d^3x \bar{\Psi} \gamma^0 \Psi = \int d^3x \Psi^\dagger(x) \gamma^0 \gamma^0 \Psi = \int d^3x |\Psi|^2 = 0$$

a navíc $J^0 = \rho \geq 0$

Zachováno se norma v čase?

$$\frac{d}{dt} \|\Psi\| = 0 \Leftarrow \partial_\mu J^\mu = 0 \quad \leftarrow \text{rovnice kontinuity}$$

$$\partial_\mu J^\mu = \partial_\mu (\bar{\Psi} \gamma^\mu \Psi) = (\partial_\mu \bar{\Psi}) \gamma^\mu \Psi + (\bar{\Psi} \gamma^\mu \partial_\mu \Psi) =$$

$$= (\partial_\mu \bar{\Psi}) \gamma^\mu \Psi + \bar{\Psi} \underbrace{\partial_\mu \gamma^\mu \Psi}_{-im\Psi} \stackrel{(*)}{=} (i\gamma^\mu \partial_\mu - m) \Psi = 0$$

$$(i\gamma^\mu \partial_\mu - m) \Psi = 0 \rightarrow (-i\partial_\mu (\Psi^\dagger \gamma^\mu)^\dagger - m \Psi^\dagger) = 0 \quad / \gamma^0$$

$$\rightarrow (-i\partial_\mu \Psi^\dagger \gamma^0 \gamma^0 \gamma^\mu \gamma^0 - m \Psi^\dagger \gamma^0) = 0$$

$$\rightarrow (i\partial_\mu \bar{\Psi} \gamma^\mu + \bar{\Psi} m) = 0 \rightarrow \partial_\mu \bar{\Psi} \gamma^\mu = m \bar{\Psi}$$

$$(*) = im \bar{\Psi} \bar{\Psi} - \Psi im \Psi = 0$$

Lorentzovská invariance normy $\|\cdot\|$:

$$\begin{aligned} \|\Psi\|^2 &= \int d^3x J^0(x) = \int d^4x J^0(x) \delta(x_0) = \int d^4x J^0(x) \frac{d}{dx_0} \theta(x_0) = \\ &= \int d^4x J^{\mu}(x) \partial_{\mu} \theta(m^a x_a) \end{aligned}$$

$m^a = (1, 0, 0, 0)$

Podob $\|\tilde{\Psi}\|^2$ je Lorentzovsky invariantní, pokud musí být

$$\int d^4x J^{\mu}(x) \partial_{\mu} \theta(m^a x_a)$$

po libovolném ^{času} prostoru podobnosti (jednotkovém) vektoru.

$$\begin{aligned} \|\tilde{\Psi}\|^2 - \|\Psi\|^2 &= \int d^4x J^{\mu}(x) \partial_{\mu} [\theta(m'^a x_a) - \theta(m^a x_a)] = \int d^4x \partial_{\mu} J^{\mu} [\theta(m'^a x_a) - \theta(m^a x_a)] = \\ &= \int d^4x \partial_{\mu} J^{\mu} [\theta(m'^a x_a) - \theta(m^a x_a)] = \\ &= \int d^4x \partial_{\mu} J^{\mu} [\theta(m'^a x_a) - \theta(m^a x_a)] \end{aligned}$$

$\partial_{\mu} J^{\mu} = 0$

• $\in \text{fixu}$, $|x| \sim \infty$: čtyřproud $J^{\mu} \sim \frac{1}{x^4}$

• $\times \text{fixu}$, $|x| \sim \infty$: $\theta(m'^a x_a) - \theta(m^a x_a) = 0$

Skalární součin:

$$(\Psi_1, \Psi_2) = \int d^4x \bar{\Psi}_1 \gamma^{\mu} \Psi_2 = \int d^4x J_{12}^{\mu}(x) = \int d^3x J_{12}^0(x)$$

Řešení Diracovy rovnice - Rovinné vlny

Proložte Ψ , řešení Diracovy rovnice, splňuje také Klein-Gordonovu rovnici, rovinné vlny (tj. vlnové funkce s fixní hodnotou E a p) jsou řešeními Diracovy rovnice.

$$\Psi_p^+(x) = u(p) e^{-i\omega_p t + i p x}$$

$$\Psi_p^-(x) = v(p) e^{i\omega_p t + i p x}$$

$$(i\gamma^\mu \partial_\mu - m) \Psi_p^+(x) \stackrel{!}{=} 0 \rightarrow (\gamma^\mu p_\mu - m \mathbb{I}) u(p) = 0 \quad \oplus$$

$$(i\gamma^\mu \partial_\mu - m) \Psi_p^-(x) \stackrel{!}{=} 0 \rightarrow (\gamma^\mu p_\mu + m \mathbb{I}) v(p) = 0 \quad \oplus$$

Ne-triviale řešení $\oplus, \oplus$ na v existují právě tehdy, když

Feynmanův slash

$$\det(\not{p} \mp m) = 0.$$

$$\begin{aligned} \bullet \det(\not{p} \mp m) &= \det(\gamma^5 \gamma^5 (\not{p} \mp m)) = \det(\gamma^5 \gamma^5 (\gamma^\mu p_\mu \mp m)) = \\ &= \det(\gamma^5 (\gamma^\mu p_\mu \mp m) \gamma^5) = \det(-\gamma^5 \gamma^5 (\gamma^\mu p_\mu \pm m)) = \\ &= \det(\not{p} \pm m) \end{aligned}$$

Tj.: determinanty (podle jsou nulové), jsou nulové ve stejné m. okamžiku

$$\begin{aligned} \bullet \det(\gamma^\mu p_\mu + m) \cdot \det(\gamma^\mu p_\mu - m) &= \det((\gamma^\mu p_\mu + m)(\gamma^\mu p_\mu - m)) = \\ &= \det(\gamma^\mu \gamma^\nu p_\mu p_\nu - m^2) = \det\left(\frac{1}{2} \epsilon^{\mu\nu} \gamma^\mu \gamma^\nu p_\mu p_\nu - m^2\right) = \\ &= \det(\gamma^{\mu\nu} p_\mu p_\nu - m^2) = \det(p^2 - m^2) = 0 \end{aligned}$$

Positivní energie

$$(\gamma^\mu p_\mu - m) u(p) = 0$$

$$\begin{pmatrix} (E-m)\mathbb{I} & -\alpha \cdot p \\ \alpha \cdot p & -(E+m)\mathbb{I} \end{pmatrix} \begin{pmatrix} \psi \\ \varphi \end{pmatrix} = 0 \rightarrow \begin{cases} (E-m)\psi - \alpha \cdot p \varphi = 0 \\ \alpha \cdot p \psi - (E+m)\varphi = 0 \end{cases}$$

Poznámka:

Ve skutečnosti jsou rovnice ekvivalentní.
Efektivně se tedy jedná o 2 rovnice.

$$\rightarrow \varphi = \frac{\alpha \cdot p}{E-m} \psi \rightarrow u(p) \sim \begin{pmatrix} \sqrt{E+m} \psi \\ \frac{\alpha \cdot p}{\sqrt{E+m}} \psi \end{pmatrix}$$

Poznámka:

Často se používá normalizace $\sqrt{\frac{E+m}{2m}}$ místo $\sqrt{E+m}$.
($\bar{u}u$ a $\bar{v}v$ jsou kesč)

• Řešení pro $u(p)$ se dá najít fyzikálněji:
Necht' jsem v klidové soustavě: $u(p) = u(m, 0)$.

$$(\gamma^\mu p_\mu - m) u(p) = 0 \rightarrow (\gamma^0 m - m) u(m, 0) = 0$$

$$\rightarrow (\gamma^0 - \mathbb{I}) u(m, 0) = 0 \rightarrow \begin{pmatrix} 0 & 0 \\ 0 & -2\mathbb{I} \end{pmatrix} \begin{pmatrix} u^0 \\ u^1 \\ u^2 \\ u^3 \end{pmatrix} = 0$$

$$\rightarrow u \in \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\} = \text{span} \{ \sqrt{2m} e_1, \sqrt{2m} e_2 \}$$

$$\text{Analogicky: } v \in \text{span} \{ \sqrt{2m} e_3, \sqrt{2m} e_4 \}$$

9. přednáška

Jak přejít zpět k referenční soustavě?

Trik:

$$\text{Hledáme } U^{(A)}(p) : (p - m)U^{(A)}(p) = 0$$

$$(p - m)(p + m) = p^2 - m^2 = 0$$

$$\rightarrow (p - m)(p + m) \underbrace{U^{(A)}(m, 0)}_{U^{(A)}(p)} = 0$$

$$\rightarrow U^{(A)}(p) = \frac{p + m}{\sqrt{E + m}} U^{(A)}(m, 0)$$

$$U^{(A)}(p) = \frac{-p + m}{\sqrt{E + m}} V^{(A)}(m, 0)$$

Úvaha:

Pro $|p| \ll m$ řeší Diracova rovnice na Schrödingrově

Důkaz:

Necht $|p| \ll m$

$$U_S = \frac{\alpha \cdot p}{E + m} U_L \Rightarrow |U_S| \ll |U_L|$$

$$(p - m)U^{(A)}(p) = 0 \stackrel{\text{Diracova rovnice}}{\Leftrightarrow} \begin{pmatrix} E - m & -\alpha \cdot p \\ \alpha \cdot p & -(E + m) \end{pmatrix} U^{(A)}(p) = 0 \Leftrightarrow$$

$$\Leftrightarrow \begin{pmatrix} m - E & \alpha \cdot p \\ \alpha \cdot p & -(E + m) \end{pmatrix} \begin{pmatrix} U_L \\ U_S \end{pmatrix} = 0 \Leftrightarrow \begin{aligned} \alpha \cdot p U_S &= (E - m) U_L \\ \alpha \cdot p U_L &= (E + m) U_S \end{aligned}$$

$$U_S = \frac{\alpha \cdot p}{E + m} U_L$$

$$\rightarrow \frac{(a \cdot p)(a \cdot p)}{E+m} u_L = (E-m) u_L \quad (*)$$

Poznamka:

$$(a \cdot p)(a \cdot p) = a^\mu p_\mu a^\nu p_\nu = a^\mu a^\nu p_\mu p_\nu = \underbrace{2a^\mu a_\mu}_{2a^\mu a_\mu} p^\mu p_\mu = p^2$$

$$(*) = \frac{p^2}{E+m} u_L = (E-m) u_L = |p| \ll m \rightarrow E+m \approx 2m$$

$$\rightarrow \frac{p^2}{2m} u_L = E_{NR} u_L$$

Aplikace Lorentzovy grupy na vlnové funkce Diracovy rovnice

• Rotace

Grupa rotací je podgrupou Lorentzovy grupy $SO(1,3)$
 $SU(2) \sim SO(3)$

Element Lorentzovy grupy má (obecně) tvar:

$$L = \exp\left(-\frac{i}{4} \omega_{\mu\nu} M^{\mu\nu}\right)$$

↳ Generátory grupy

$$\cdot J_i = \frac{1}{4} \epsilon_{ijk} M^{jk} \rightarrow [J_i, J_j] = i \epsilon_{ijk} J_k$$

$$\cdot (M^{\mu\nu})^\rho_\sigma = 2i (\eta^{\mu\rho} \eta^\nu_\sigma - \eta^{\nu\rho} \eta^\mu_\sigma) \quad (\eta^\mu_\nu = \delta^\mu_\nu)$$

$$(J_i)^\rho_\sigma = \frac{1}{2} \epsilon_{ijk} (M^{jk})^\rho_\sigma =$$

↑
rotace

$$(J_3)^\rho_\sigma = \frac{1}{2} \epsilon_{3jk} (\eta^{j\rho} \eta^k_\sigma - \eta^{k\rho} \eta^j_\sigma) \rightarrow (J_3)_2^1 = \frac{1}{2} [\epsilon_{312} \eta^1_2 \eta^2_1 - \epsilon_{321} \eta^2_1 \eta^1_2] = -i$$

Obecně: $(J_i)^d = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$ (Adjoint representation)

Jak vypadá explicitně $L = \exp(-\frac{i}{4} \omega_{ab} M^{ab})$ při rotacích?

$$R = \exp(-\frac{i}{4} \omega_{ij} M^{ij}) = \exp(-\frac{i}{2} (\omega_{ij} \varepsilon^{ijk} J_k)) = \exp(-i \theta_n J_n)$$

$2\theta^k = \theta_n \varepsilon^{njk}$

$$\rightarrow \theta^k = \frac{1}{2} \varepsilon^{kij} \omega_{ij}$$

$$J_i = i \frac{\partial R}{\partial \theta^i} \Big|_{\theta=0}$$

10. přednáška

Práce na Diracových vlnových funkcích

$$L = \exp(-\frac{i}{4} \omega_{\alpha\beta} M^{\alpha\beta}) \mapsto S(L) = \exp(-\frac{i}{4} \omega_{\alpha\beta} \sigma^{\alpha\beta}), \quad \sigma^{\alpha\beta} = \frac{i}{2} [\gamma^\alpha, \gamma^\beta]$$

$$R = \exp(-\frac{i}{4} \omega_{ij} M^{ij}) \mapsto S(R) = \exp(-\frac{i}{4} \omega_{ij} \sigma^{ij})$$

$\underbrace{\quad}_{-i\theta_k J^k} \qquad \underbrace{\quad}_{-i\theta_k \hat{a}^k}$

$$\bullet \theta^k = \frac{1}{2} \varepsilon^{kij} \omega_{ij}$$

$$\rightarrow \hat{a}_k = \frac{1}{4} \varepsilon_{k\ell m} \sigma^{\ell m} \quad (\text{Chceme explicitně})$$

$$\begin{aligned} \hat{a}^i &= \frac{i}{2} [\gamma^i, \gamma^j] = i \gamma^i \gamma^j = i \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix} \begin{pmatrix} 0 & \sigma^j \\ -\sigma^j & 0 \end{pmatrix} = -i \begin{pmatrix} -\sigma^i \sigma^j & 0 \\ 0 & -\sigma^i \sigma^j \end{pmatrix} \\ &= \{ \sigma^i \sigma^j = i \varepsilon^{ijk} \sigma_k \} = \varepsilon^{ijk} \begin{pmatrix} \sigma_k & 0 \\ 0 & \sigma_k \end{pmatrix} = \varepsilon^{ijk} \mathbb{I} \otimes \sigma_k \end{aligned}$$

$$\rightarrow \hat{a}_k = \frac{1}{4} \varepsilon_{k\ell m} \varepsilon^{\ell m n} \mathbb{I} \otimes \sigma_n = \frac{1}{4} (\delta_k^n \mathbb{I} \otimes \sigma_n) = \frac{1}{2} \mathbb{I} \otimes \sigma_k$$

$$\rightarrow [\hat{a}_k, \hat{a}_\ell] = i \varepsilon_{k\ell m} \hat{a}^m$$

$$\rightarrow \exp(-i\theta_k \hat{a}^k) = \frac{1}{2} \mathbb{I} \otimes \exp(-\frac{i}{2} \theta_k \sigma^k) = S(R)$$

$$S(R)u(p) = \sqrt{E+m} (\mathbb{I} \otimes \exp(-\frac{i}{2} \theta_k \sigma^k)) u(p) =$$

$$= \sqrt{E+m} \mathbb{I} \otimes \exp(-\frac{i}{2} \theta_k \sigma^k) u(p)$$

$$\exp(-\frac{i}{2} \theta_k \sigma^k) u(p) = \begin{pmatrix} \exp(-\frac{i}{2} \theta_k \sigma^k) \psi \\ \exp(-\frac{i}{2} \theta_k \sigma^k) \frac{a \cdot p}{E+m} \psi \end{pmatrix}$$

$$\mathbb{I} = \exp(+\frac{i}{2} \theta_k \sigma^k) \exp(-\frac{i}{2} \theta_k \sigma^k)$$

$$\exp(-\frac{i}{2} \theta_k \sigma^k) (a \cdot p) \exp(\frac{i}{2} \theta_k \sigma^k) = a \exp(-i\theta_k J^k) p \quad (\text{onien'})$$

$$\rightarrow S(\gamma) = \sqrt{E+m} \begin{pmatrix} \psi_R \\ \frac{\vec{\alpha} \cdot \vec{p}}{E+m} \psi_R \end{pmatrix} = \sqrt{E+m} \begin{pmatrix} \psi_R \\ \frac{\vec{\alpha} \cdot \vec{p}}{E+m} \psi_R \end{pmatrix}$$

Poznámka:

Vlnové funkce, které se vzhledem k rotačním transformují jako $\psi \mapsto \psi_R = \exp(-\frac{i}{2} \theta_k \sigma^k) \psi$ se nazývají Pauliho spinory. (Weylov)

Spin Diracovy částice

V klidové souřadné soustavě můžeme psát:

$$\psi_1^{(+)}(x) = \sqrt{2m} \begin{pmatrix} \psi(x) \\ 0 \end{pmatrix} \frac{e^{-iEt + i\vec{p} \cdot \vec{x}}}{\sqrt{m^3}} = \sqrt{2m} \begin{pmatrix} \psi(x) \\ 0 \end{pmatrix} \frac{e^{imx}}{\sqrt{m^3}}$$

$$\psi_1^{(-)}(x) = \sqrt{2m} \begin{pmatrix} 0 \\ \psi(x) \end{pmatrix} \frac{e^{imx}}{\sqrt{m^3}}$$

$$\hat{\sigma}_3 \psi_{\frac{1}{2}}^{(+)}(x) = \frac{1}{2} \psi_{\frac{1}{2}}^{(+)}(x), \quad \hat{\sigma}_3 \psi_{-\frac{1}{2}}^{(+)}(x) = -\frac{1}{2} \psi_{-\frac{1}{2}}^{(+)}(x)$$

$$\hat{\sigma}_3 \psi_{\frac{1}{2}}^{(-)}(x) = \frac{1}{2} \psi_{\frac{1}{2}}^{(-)}(x), \quad \hat{\sigma}_3 \psi_{-\frac{1}{2}}^{(-)}(x) = -\frac{1}{2} \psi_{-\frac{1}{2}}^{(-)}(x)$$

Laurentzovské boosty

Pro posuv kvadranty: izochrony

$$\begin{aligned} \text{i) } x\text{-komponenta: } \begin{aligned} t' &= \gamma(t - vx) & x_0' &= \gamma(x_0 - \beta x) \\ x' &= \gamma(x - vt) & x_1' &= \gamma(x_1 - \beta x_0) \\ y' &= y & x_2' &= x_2 \\ z' &= z & x_3' &= x_3 \end{aligned} \end{aligned}$$

$$\beta \in (-1, 1)$$

$$\text{Využijeme se analogie s rotací: } \gamma^2 - (\gamma\beta)^2 = \gamma^2(1 - \beta^2) = 1$$

$$\rightarrow \gamma = \cosh \eta, \quad \gamma\beta = \sinh \eta$$

$$\eta := \text{rapidity} : \tanh \eta = \beta \rightarrow \eta = \tanh^{-1}(\beta) \in (-\infty, +\infty)$$

Poznámka:

• Rapidity pro různé rychlosti se sčítají.

• Boostová část Lorentzovy grupy je nekompatní.

$\rightarrow$ neexistuje unitární transformace reprezentace

$$\rightarrow (L_x)^\mu{}_\nu = \begin{pmatrix} \cosh \eta_x & -\sinh \eta_x & 0 & 0 \\ -\sinh \eta_x & \cosh \eta_x & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

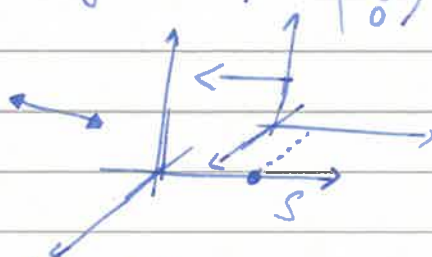
$$(L_y)^\mu{}_\nu = \begin{pmatrix} \cosh \eta_y & 0 & -\sinh \eta_y & 0 \\ 0 & 1 & 0 & 0 \\ -\sinh \eta_y & 0 & \cosh \eta_y & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$(L_z)^\mu{}_\nu = \begin{pmatrix} \cosh \eta_z & 0 & 0 & -\sinh \eta_z \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ -\sinh \eta_z & 0 & 0 & \cosh \eta_z \end{pmatrix}$$

Poznámka:

Klidová částice a soustava S má 4-hybnost: $p^\mu = \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix}$

$$\rightarrow \begin{pmatrix} \cosh \eta & 0 & 0 & \sinh \eta \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \sinh \eta & 0 & 0 & \cosh \eta \end{pmatrix}$$



$$(L_z) \begin{pmatrix} m \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} m \cosh \eta \\ 0 \\ 0 \\ m \sinh \eta \end{pmatrix} = \begin{pmatrix} E \\ 0 \\ 0 \\ \frac{m\gamma\beta}{\gamma} \end{pmatrix} = \begin{pmatrix} E \\ 0 \\ 0 \\ p \end{pmatrix}$$

$$(*) : \gamma = \cosh \eta \\ \gamma\beta = \sinh \eta$$

• Infinitesimal transform ($|q| \ll 1$)

$$(L_z) = \mathbb{I} + \underbrace{q \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}}_{\sim M^{03}},$$

a súčasne $L_z = \exp(-\frac{i}{4} \omega_{03} M^{03}) = \exp(-\frac{i}{4} \omega_{03} M^{03} + \frac{i}{4} \omega_{30} M^{30}) =$

$$= \exp(-\frac{i}{2} \omega_{03} M^{03}) = \mathbb{I} - \underbrace{\frac{i}{2} \omega_{03} M^{03}}_{K_3} = \mathbb{I} - i \omega_{03} K_3$$

$$(M^{03})^\mu{}_\nu = 2i \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$\rightarrow L_z = \mathbb{I} + \omega_{03} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \rightarrow q = \omega_{03}$$

$$\begin{aligned} \rightarrow L_z &= \exp\left(q \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}\right) = \mathbb{I} + \sum_{n=1}^{\infty} \frac{q^n}{n!} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}^n = \mathbb{I} + \sum_{n=1}^{\infty} \frac{q^{2n}}{2n!} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} + \sum_{n=0}^{\infty} \frac{q^{2n+1}}{(2n+1)!} \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \\ &= \begin{pmatrix} \cosh q & 0 & 0 & \sinh q \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \sinh q & 0 & 0 & \cosh q \end{pmatrix} \end{aligned}$$

Bi-spinorove' representace Lorentzovych boostu

$$L = \exp(-\frac{i}{2} \omega_{ij} M^{ij}) = \exp(-i \mathbf{q} \cdot \mathbf{k}_i) \quad (\text{Fundamentální representace})$$

$$S(L) = \exp(-\frac{i}{2} \mathbf{q} \cdot \mathbf{a}^{0i}) \quad , \quad a^{0i} = \frac{i}{2} [\gamma^0, \gamma^i]$$

$$S(L_z) = \exp(-\frac{i}{2} q_3 a^{03}) = \exp(\frac{1}{2} q_3 \gamma^0 \gamma^3)$$

$$\cdot (\gamma^0 \gamma^3)^2 = \gamma^0 \gamma^3 \gamma^0 \gamma^3 = - \underbrace{\gamma^0 \gamma^0}_{\mathbb{I}} \underbrace{\gamma^3 \gamma^3}_{-\mathbb{I}} = \mathbb{I} \rightarrow (\gamma^0 \gamma^3)^{2n} = \mathbb{I} \quad , \quad (\gamma^0 \gamma^3)^{2n+1} = \gamma^0 \gamma^3$$

Involutive!

Poznámka:

$$\exp(tA) = \{ A^{2n} = \mathbb{I}, A^{2n+1} = A \} = \cosh(t) + A \sinh(t)$$

$$\rightarrow S(L_z) = \cosh\left(\frac{q}{2}\right) + \gamma^0 \gamma^3 \sinh\left(\frac{q}{2}\right)$$

$$\left. \begin{aligned} \cosh^2 \theta - \sinh^2 \theta &= 1 \\ \cosh^2 \theta + \sinh^2 \theta &= \cosh(2\theta) \end{aligned} \right\} \begin{aligned} 2 \cosh^2 \theta &= 1 + \cosh(2\theta) \\ 2 \sinh^2 \theta &= \cosh(2\theta) - 1 \end{aligned}$$

$$\rightarrow \cosh\left(\frac{1}{2} q\right) = \sqrt{\frac{\cosh q + 1}{2}} = \sqrt{\frac{E+m}{2m}}$$

$$\sinh\left(\frac{1}{2} q\right) = \sqrt{\frac{\cosh q - 1}{2}} = \sqrt{\frac{E-m}{2m}} = \sqrt{\frac{E^2 - m^2}{2m(E+m)}} = \sqrt{\frac{q^2}{2m(E+m)}}$$

$$S(L_z) = \sqrt{\frac{E+m}{2m}} + \sqrt{\frac{q^2}{2m(E+m)}} = \sqrt{\frac{E+m}{2m}} \left(\mathbb{I} + \frac{q}{E+m} \gamma^0 \gamma^3 \right) = (*)$$

$$\gamma^0 \gamma^3 = (\alpha_3 \otimes \mathbb{I})(i\alpha_2 \otimes \alpha_3) = (i\alpha_2 \alpha_3 \otimes \alpha_3) = \alpha_1 \otimes \alpha_3 = \begin{pmatrix} 0 & \alpha_3 \\ \alpha_3 & 0 \end{pmatrix}$$

$$(*) = \sqrt{\frac{E+m}{2m}} \begin{pmatrix} \mathbb{I} & \frac{q \alpha_3}{E+m} \\ \frac{q \alpha_3}{E+m} & \mathbb{I} \end{pmatrix} \rightarrow \sqrt{\frac{E+m}{2m}} \begin{pmatrix} \mathbb{I} & \frac{q \cdot \mathbf{a}}{E+m} \\ \frac{q \cdot \mathbf{a}}{E+m} & \mathbb{I} \end{pmatrix} = S(L)$$

Diracova representace

11. přednáška

Působení na klidovou Diracovu částici:

$$u_{\frac{1}{2}} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \sqrt{2m}, \quad u_{-\frac{1}{2}} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \sqrt{2m} \rightarrow u_2 = \begin{pmatrix} x_2 \\ 0 \end{pmatrix} \sqrt{2m}$$

$$S(L) u_2 = \sqrt{E+m} \begin{pmatrix} x_2 \\ \frac{\vec{\alpha} \cdot \vec{p}}{E+m} x_2 \end{pmatrix}$$

Spinové stavy a projekční operátory

Připomenutí:

Negativní energetická řešení $\psi_2^{(-)}(x) = u_2^{(-)}(p) \exp(iu_p x_0 - ix \cdot p)$

Pozitivní energetická řešení $\psi_2^{(+)}(x) = u_2^{(+)}(p) \exp(-iu_p x_0 + ix \cdot p)$

$$u_1(p) = \begin{pmatrix} x_1 \\ \frac{\vec{\alpha} \cdot \vec{p}}{E+m} x_1 \end{pmatrix} \sqrt{E+m}, \quad \bar{u}_1 = u_1^* \gamma^0$$

$$v_2(p) = \begin{pmatrix} \frac{\vec{\alpha} \cdot \vec{p}}{E+m} x_2 \\ x_2 \end{pmatrix} \sqrt{E+m}, \quad \bar{v}_2 = v_2^* \gamma^0$$

Teoremy:

$$i) \bar{u}_1(p) u_1(p) = 2m \delta_{11}$$

$$ii) \bar{v}_2(p) v_2(p) = -2m \delta_{22}$$

$$iii) \bar{u}_2(p) v_2(p) = \bar{v}_2(p) u_1(p) = 0$$

Poznámka:

$$\psi_2^{(+)}(x) \psi_2^{(+)}(x) = \text{skalár}$$

$$\begin{aligned} \xrightarrow{L} \bar{\psi}_{L_2}^{(+)}(x) \psi_{L_2}^{(+)}(x) &= \bar{\psi}_1^{(+)}(L^{-1}x) \underbrace{S(L^{-1})S(L)}_{\mathbb{I}} \psi_1^{(+)}(L^{-1}x) = \bar{\psi}_1^{(+)}(L^{-1}x) \psi_1^{(+)}(L^{-1}x) = \\ &= \bar{u}_1(p) u_1(p) = \bar{u}_1(L^{-1}p) u_1(L^{-1}p) \end{aligned}$$

V klidové souřadné soustavě:

$$u_{\frac{1}{2}}(m,0) = \sqrt{2m} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} \chi_{\frac{1}{2}}, \quad u_{-\frac{1}{2}}(m,0) = \sqrt{2m} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \chi_{-\frac{1}{2}}$$

$$v_{\frac{1}{2}}(m,0) = \sqrt{2m} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \chi_{\frac{1}{2}}, \quad v_{-\frac{1}{2}}(m,0) = \sqrt{2m} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \chi_{-\frac{1}{2}}$$

$$\rightarrow \overline{u}_\lambda(p) u_{\lambda'}(p) = 2m \delta_{\lambda\lambda'} = -\overline{v}_\lambda(p) v_{\lambda'}(p)$$

$$\overline{u}_\lambda(p) v_{\lambda'}(p) = \overline{v}_{\lambda'}(p) u_\lambda(p) = 0$$

Projekční operátory

$$(\not{p} - m) u_\lambda(p) = 0, \quad (\not{p} + m) v_\lambda(p) = 0$$

$$(\not{p} + m) u_\lambda(p) = (\not{p} - m + 2m) u_\lambda(p) = 2m u_\lambda(p)$$

$$(\not{p} - m) v_\lambda(p) = (\not{p} + m - 2m) v_\lambda(p) = -2m v_\lambda(p)$$

$$\tilde{\Lambda}^+(p) := \sum_\lambda u_\lambda(p) \overline{u}_\lambda(p)$$

$$\tilde{\Lambda}^-(p) := \sum_\lambda v_\lambda(p) \overline{v}_\lambda(p)$$

> Spinore' sumy

$$\rightarrow \tilde{\Lambda}^+(p) u_{\lambda'}(p) = \sum_\lambda u_\lambda(p) \overline{u}_\lambda(p) u_{\lambda'}(p) = \sum_\lambda u_\lambda 2m \delta_{\lambda\lambda'} = 2m u_{\lambda'}(p)$$

$$\tilde{\Lambda}^+(p) v_{\lambda'}(p) = 0 \Leftrightarrow$$

$$\rightarrow \tilde{\Lambda}^+(p) = (\not{p} + m), \quad \tilde{\Lambda}^-(p) = (\not{p} - m)$$

Operátory $\Lambda^+(\mathbf{p}) := \frac{\tilde{\Lambda}^+(\mathbf{p})}{2m}$, $\Lambda^-(\mathbf{p}) = -\frac{\tilde{\Lambda}^-(\mathbf{p})}{2m}$ jsou projekční
operátory na pozitivní (Λ^+), resp. negativní (Λ^-) energetická
bi-spinorová řešení

Diracova rovnice - Aplikace I.

Elektromagnetický coupling elektronu

I) Nereativistická malá částice

$$H = \frac{(\mathbf{p} - \frac{q}{c}\mathbf{A})^2}{2m} + q\phi$$

↑
Vektorový kalibrační potenciál

← Skalární kalibrační potenciál

$\mathbf{p} \mapsto \mathbf{p} - \frac{q}{c}\mathbf{A}$ (Minimální substituce)

Interakční člen se narytí minimální coupling.
Minimalní coupling je například $\mathbf{p} \mapsto \mathbf{p} - \frac{q}{c}\mathbf{A}$

$$H = \frac{\mathbf{p}^2}{2m} - \frac{q}{c}(\mathbf{p}\mathbf{A} + \mathbf{A}\mathbf{p}) + O(q^2) = \textcircled{*}$$

$$\mathbf{p}\mathbf{A} = A_i p_i + [p_i, A_i] = A_i p_i - i [\nabla_i, A_i] = A_i p_i - i \nabla_i A_i$$

0 (Coulombův kalibrační)

$$\mathbf{A} = \frac{1}{2\mathbf{B}}(x\mathbf{p}_y - y\mathbf{p}_x, 0) \leftrightarrow \mathbf{B} = (0, 0, B)$$

$$\textcircled{*} = \frac{1}{2m}(\mathbf{p}^2 - 2\frac{q}{c}\mathbf{A}\cdot\mathbf{p}) + O(q^2) = \frac{\mathbf{p}^2}{2m} - \frac{q}{2mc} B(x\mathbf{p}_y - y\mathbf{p}_x) + H_B$$

$$\frac{q\hbar}{2mc} = \mu_B \text{ (Bohrův magneton)}$$

12. jednotka

Experimenty:

- i) elektron má spin $\frac{1}{2}$
- ii) pro elektron (a pro všechny částice se spinem $\frac{1}{2}$) g -foton související se spinem je 2

I) Relativistická nabitá částice

• Minimální substituce:

$$p_\mu \rightarrow p_\mu - q A_\mu \rightarrow i\partial_\mu \rightarrow i\partial_\mu - q A_\mu$$
$$\partial_\mu \rightarrow \partial_\mu - iq A_\mu$$

$$\rightarrow (i\gamma^\mu \partial_\mu - m)\Psi = 0 \rightarrow [i\gamma^\mu (\partial_\mu + iq A_\mu) - m]\Psi = 0$$

$$\rightarrow [i\gamma^0 \partial_0 + i\gamma^i \partial_i - \gamma^0 q A_0 - \underbrace{\gamma^i q A_i}_{\leftarrow \Phi} - m]\Psi = 0$$

$$\rightarrow i\partial_0 \Psi = \left[-i \underbrace{\gamma^0 \gamma^i}_{\alpha^i} \partial_i + \underbrace{\gamma^0 \gamma^i q A_i}_{\alpha^i} + \beta m + q\Phi \right] \Psi$$

$$\rightarrow i\partial_0 \Psi = [\alpha(i\nabla - qA) + q\Phi \mathbb{I} + \beta m] \Psi$$

Pro $\Psi = \begin{pmatrix} \Psi \\ \chi \end{pmatrix}$ máme:

$$i\partial_0 \Psi = \tilde{\alpha}(-i\nabla - qA)\chi + (q\Phi)\Psi + m\Psi$$

$$i\partial_0 \chi = \tilde{\sigma}(-i\nabla - qA)\Psi + (q\Phi)\chi - m\chi$$

Nonrelativisticko' limita: $\Psi \rightarrow e^{-iEt} \tilde{\Psi} = e^{-iEt} \begin{pmatrix} \tilde{\Psi} \\ \tilde{\chi} \end{pmatrix}$

$$i\partial_0 \tilde{\Psi} + m \tilde{\Psi} = \tilde{\alpha} (-i\nabla - qA) \tilde{\chi} + (q\phi) \tilde{\Psi} + m \tilde{\Psi}$$

$$\rightarrow i\partial_0 \tilde{\Psi} = \tilde{\alpha} (-i\nabla - qA) \tilde{\chi} + (q\phi) \tilde{\Psi} \quad (*)$$

$$i\partial_0 \tilde{\chi} = \tilde{\alpha} \underbrace{(-i\nabla - qA) \tilde{\Psi}}_{\pi\text{-kineticko' hybnost}} + (q\phi) \tilde{\chi} - \underline{2m \tilde{\chi}} \quad (\#)$$

$$|m \tilde{\chi}| \gg |\partial_0 \tilde{\chi}|$$

$$\rightarrow 0 = \alpha \pi \tilde{\Psi} + (q\phi) \tilde{\chi} - 2m \tilde{\chi} \rightarrow \tilde{\chi} = \frac{\alpha \pi}{2m} \tilde{\Psi} + \underbrace{\frac{(q\phi)}{2m} \tilde{\chi}}_{\ll 1}$$

$$\rightarrow \tilde{\chi} = \frac{\alpha \pi}{2m} \tilde{\Psi} \rightarrow (*)$$

$$i\partial_0 \tilde{\Psi} = \frac{(\alpha \pi)(\alpha \pi)}{2m} \tilde{\Psi} + (q\phi) \tilde{\Psi}$$

$$(a \cdot a)(a \cdot b) = a^i a^j a^i b^j = (\delta^{ij} + i \epsilon^{ijk} a^k) = a \cdot b + i a^k (a + b)^k$$

platí pouze pro komutující a & b .

$$(a \cdot \pi)(a \cdot \pi) = a^i a^j \pi^i \pi^j = \frac{1}{4} \underbrace{\{a^i, a^j\}}_{\frac{1}{2} \delta^{ij}} \underbrace{\{\pi^i, \pi^j\}}_{\frac{1}{2} \delta^{ij}} + \frac{1}{4} \underbrace{[a^i, a^j]}_{2i \epsilon^{ijk} a^k} \underbrace{[\pi^i, \pi^j]}_{2i \epsilon^{ijk} a^k} =$$

$$= \pi^2 + \frac{i}{2} \epsilon^{ijk} a^k [(-i\nabla_i - qA^i)_i, (-i\nabla_j - qA^j)_j] =$$

$$= \pi^2 + \frac{i}{2} \epsilon^{ijk} a^k ([i\nabla_i, qA^j] + [qA^i, i\nabla_j]) =$$

$$= \pi^2 + \frac{i}{2} \epsilon^{ijk} a^k q (i\nabla_i A^j - i\nabla_j A^i) =$$

$$= \pi^2 - q a^k (\nabla_0 + A)^k = \pi^2 - q a \cdot \mathbf{B}$$

$$\rightarrow i\partial_0 \tilde{\Psi} = \left[\frac{(\mathbf{p} - q\mathbf{A})^2}{2m} - \frac{q\mathbf{A} \cdot \mathbf{B}}{2m} + q\phi \right] \tilde{\Psi} =$$

$$\stackrel{q\hbar+1}{=} \left[\frac{\mathbf{p}}{2m} - \frac{q\hbar}{2mc} \frac{\mathbf{L}}{\hbar} \mathbf{B} - \frac{q\hbar}{2mc} \frac{\mathbf{S}}{\hbar} \mathbf{B} + H_{EM} \right] \tilde{\Psi} =$$

$$= [H_0 + H_{EM} + H_I] \tilde{\Psi} \quad (\text{Pauliho rovnice})$$

$$H_I = -g_L \mu_B \frac{\mathbf{L}}{\hbar} \mathbf{B} - g_S \mu_B \frac{\mathbf{S}}{\hbar} \mathbf{B} = \tilde{\boldsymbol{\mu}} \cdot \tilde{\mathbf{B}}$$

$$\boldsymbol{\mu} = -\frac{e\hbar}{4m} (g_L \cdot \tilde{\mathbf{L}} + g_S \cdot \tilde{\mathbf{S}}) \neq \tilde{\mathbf{J}}$$

Poznámka: Reprezentace γ -matice

Fundamentální teorem Cliffordovy algebry (Pauli, 1936)

Existují 2 množiny γ -matice, splňující

Cliffordův součin $\{\gamma^\mu, \gamma^\nu\} = 2\eta^{\mu\nu} \mathbb{I}$, potom existuje $S \in GL(4, \mathbb{C})$, která poskytuje podobnostní transformaci:

$$S \gamma^\mu S^{-1} = \gamma'^\mu$$

Nové podobné γ -matice jsou (anti)hermitovské, je podobnostní transformace unitární.

Díky unitární transformaci je jednoznačné až na multiplikační faktor nelikost 1.

13. přednáška

Representace γ -matic

i) Diracova reprezentace

$$\gamma^0 = \alpha^3 \otimes \mathbb{I}, \quad \gamma^i = i\alpha^2 \otimes \sigma^i, \quad \gamma^5 = 0' \otimes \mathbb{I}$$

Výhody:

- snadno nerelativistický limit ($\Psi^{(+)}$ $\mapsto$ Weylov spinor)
- platí i pro částice v elmag. poli

Nevýhody:

- nelze snadno přejít po částice s $m=0$
- reprezentace Lorentzovy grupy $L_+^\uparrow$ (vlastní ortochronní transformace)
 - $\hookrightarrow$ Diracův spinor je reducibilní vzhledem k $L_+^\uparrow$ (nemůžeme $\sim$ Diracovu reprezentaci)

Poznámka:

$$S(\mathcal{D}) = \exp(-\frac{i}{2} \omega_{ij} \alpha^{ij}) \oplus \alpha^{ij} = \frac{i}{2} [\gamma^i, \gamma^j] = i \gamma^i \gamma^j$$

$$\oplus = \exp(-i\theta_i \hat{\alpha}^i) = \begin{pmatrix} \exp(-\frac{i}{2}\theta_i \frac{\sigma^i}{2}) & 0 \\ 0 & \exp(-\frac{i}{2}\theta_i \frac{\sigma^i}{2}) \end{pmatrix}$$

$$S_0(\mathcal{B}) = \exp(-\frac{i}{2} \omega_{0i} \alpha^{0i}) \oplus \alpha^{0i} = \frac{i}{2} [\gamma^0, \gamma^i] = i \gamma^0 \gamma^i$$

$$\oplus = \exp(\frac{1}{2} \zeta_i \gamma^0 \gamma^i) = \sqrt{\frac{E+m}{2m}} \begin{pmatrix} \mathbb{I} & \frac{\mathbf{a} \cdot \mathbf{p}}{E+m} \\ \frac{\mathbf{a} \cdot \mathbf{p}}{E+m} & \mathbb{I} \end{pmatrix}$$

ii) Chiralu' (Weylora) representation

$$T_W^0 = 0_3 \otimes \mathbb{I}, T_W^1 = T_0^1, T_W^5 = -0_3 \otimes \mathbb{I}$$

Výhody:

- pro $m=0$ se Diracova rovnice „rozpadne“ na 2 nezávislé rovnice
- reducibilita $L_+^\uparrow$ je explicitní

Poznámka:

$$S_W(R) = \exp\left(-\frac{i}{2} \omega_{ij} a^{ij}\right), a^{ij} = \frac{i}{2} [T_W^i, T_W^j] = \frac{i}{2} [T_0^i, T_0^j] \\ = S_0(R)$$

$$S_W(B) = \exp\left(-\frac{i}{2} \omega_{ab} a^{ab}\right), a^{ab} = \frac{i}{2} [T_W^a, T_W^b] = \frac{i}{2} [T_0^a, T_0^b]$$

$$= \exp\left(\frac{1}{2} G_1 T_0^5 T_0^3\right) = \begin{pmatrix} \exp\left(-\frac{G_1}{2} a^1\right) & 0 \\ 0 & \exp\left(\frac{G_1}{2} a^1\right) \end{pmatrix} \Rightarrow \text{Reducibilita } L_+^\uparrow \text{ je transparentní}$$

Parita P:

$$P: x^\mu \xrightarrow{P} x_P^\mu = (x_0, \mathbf{x})$$

$$\det P = -1, P^0_0 = 1 \rightarrow P \in L_-^\uparrow \text{ (neortochroní ortochroní transformace)}$$

Časová inverze T:

$$T: x^\mu \xrightarrow{T} x_T^\mu = (-x_0, \mathbf{x})$$

$$\det T = -1, T^0_0 = -1 \rightarrow T \in L_-^\downarrow \text{ (neortochroní neortochroní transformace)}$$

Poznámka:

T a K je T anti-lineární.

14. přednáška

Poslední z diskrétních symetrií je tzv. C - symetrie (Charge Conjugation)

$$e \xrightarrow{C} -e$$

Uvažujme elektromagnetické pole s minimálním couplingem:

$$(i\partial - eA - m)\psi(x) = 0 \quad (*)$$

$$\text{tj: } [i\gamma^\mu(\partial_\mu + ieA) - m]\psi(x) = 0$$

Požadujeme-li C-symetrii, musí konjugovaná rovnice splňovat

$$[i\gamma^\mu(\partial_\mu - ieA) - m]\psi_c(x) = 0$$

$$(*)^+ : \psi_c^\dagger(x) [-i\overleftarrow{\gamma}^\mu \partial_\mu - e(\gamma^\mu)^\dagger A_\mu - m] = 0$$

$$\rightarrow \bar{\psi}(x) \gamma^0 [-i(\gamma^\mu)^\dagger \overleftarrow{\partial}_\mu - e(\gamma^\mu)^\dagger A_\mu - m] \gamma^0 = 0$$

$$\rightarrow \bar{\psi}(x) [-i\gamma^\mu \overleftarrow{\partial}_\mu - e\gamma^\mu A_\mu - m] = 0$$

$$\rightarrow [-i\gamma^\mu \overleftarrow{\partial}_\mu - e\gamma^\mu A_\mu - m] \bar{\psi}^T(x) = 0$$

$$\text{Tip: } \psi_c(x) = C \bar{\psi}^T(x)$$

Paž by muselo platit:

$$(-iC(\gamma^\mu)^T C^{-1} \partial_\mu - eC(\gamma^\mu)^T C^{-1} A_\mu - m)\psi_c(x) = 0$$

Nechť platí $C(\gamma^\mu)^T C^{-1} = -\gamma^\mu$, pak máme:

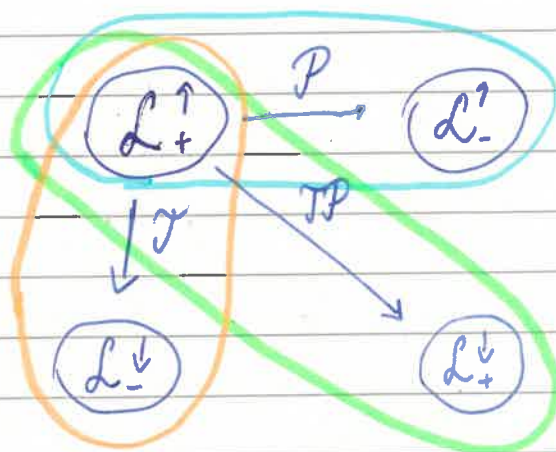
$$(i\gamma^\mu \partial_\mu + e\gamma^\mu A_\mu - m)\psi_0(x) = 0$$

V Diracově reprezentaci pak platí:

$$C = \begin{matrix} \eta_c \\ \end{matrix} i\gamma_0\gamma^2 = \begin{matrix} \eta_c \\ \end{matrix} \alpha_1 \otimes i\sigma_2$$

V Chiralní reprezentaci:

$$C = -\mathbb{D}_3 \otimes i\sigma_2$$



Vlastnosti matice C:

- i) $C = -C^{-1}$
- ii) $C = C^+$ ~~and~~
- iii) $C = -C^T$

Diskrétní kvantová čísla:

$$\begin{aligned} \text{spin } S &= \pm \frac{1}{2} \\ \eta_P &= \pm 1 \\ \eta_T &= \pm 1 \\ \eta_C &= \pm 1 \end{aligned}$$

Fyzikální význam záporných energií Diracova operátoru

Uvažme následující myšlenkový experiment:

Bředtstomne si, že „skutečné“ elektrony jsou popsány pouze kladnými energetickými stavy, tj.: $E = \sqrt{p^2 + m^2}$ a všechny záporné energetické stavy jsou obsazeny elektrony.

Takto je „skutečný“ elektron chová, před popodem do záporných energií postupnou emisí!

Pri lestitorné ršal mšre negativí elétron absorbat falon a energie $\hbar\omega > 2mc^2$ a jstóat do kladného energetického sfery.

Dúsledkem tohoto jevu j vyhraení „díry“ v záporném „Diracově moři“. Pomocí této energie Diracovo moře j patřím

$$E_{\text{obs}} = E_{\text{vac}} - (-|E_e|) = E_{\text{vac}} + |E_e| \quad a$$

$$q = q_{\text{vac}} + (-|e|) = q_{\text{vac}} + |e|.$$

To ^umožná ...

Pořád takom' proces pijmeme jako pijestím, ziskóháme rúdnířdí částice s nábojem $|e|$ a pozitiví energií.

Takové částice nazýváme pozitron.

Antičástice

Každá nabitá částice má antičástici, tj. částici se stejnou hmotností a opačným nábojem.

Feynman-Stueckelberg interpretation:

Antičástice j částice s negativí energií, hmotností, nábojem a spínem, pohybující se zpět v čase

	náboj	energie	hybnost	spin	helicita
electron	$- e $	$- E $	p	$\hat{\sigma}$	$\hat{\sigma} \cdot \frac{p}{ p } = \hat{h}$
positron	$ e $	$ E $	$-p$	$-\hat{\sigma}$	$\hat{\sigma} \cdot \frac{p}{ p } = \hat{h}$

15. přednáška

Jemno' struktura atomového spektra

Uvažujeme Diracův Hamiltonián popisující částici v centrálním stabilním potenciálu:

$$H_D \Psi = [\alpha \cdot p + \beta \cdot m + V(r)] \Psi = E \Psi$$

$$\alpha := \alpha_i \otimes \tilde{\alpha}, \quad \beta := \alpha_3 \otimes \mathbb{I} \quad (\text{Diracova reprezentace})$$

Celkový moment hybnosti J :

$$J := r \times p + \tilde{\alpha} = L + \tilde{\alpha}$$

$$\tilde{\alpha} = \frac{1}{2} \epsilon_{ijk} \gamma_i^\dagger \gamma_j^\dagger = \frac{2}{4} \epsilon_{ijk} [\gamma_i^\dagger \gamma_j^\dagger] = \frac{i}{4} \epsilon_{ijk} \alpha^{ik}$$

Teorema:

$\{H_D, J^2, J_z\}$ lze současně diagonalizovat, tj. komutují

Důkaz:

$$[H_D, J] = 0 \Rightarrow [H_D, J^2] = 0 \Rightarrow [H_D, J_z]$$

$$J = \begin{pmatrix} L + \frac{1}{2}\alpha & 0 \\ 0 & L + \frac{1}{2}\alpha \end{pmatrix}$$

$$\text{Dobře platí: } [H_D, \beta \tilde{\alpha} \cdot J] = \frac{1}{4} [H_D, \beta J]$$

$$[H_D, \beta \Sigma \cdot J] = \frac{1}{2} [H_D, \beta J]$$

$$\rightarrow K := \beta \Sigma \cdot J - \frac{1}{2} \beta J \text{ se zachová, tj.: } [H_D, K] = 0$$

$$K = \beta (\Sigma \cdot L + 1) \rightarrow [K, J^2] = 0$$

→ $\{H_0, J_z, J^2, K\}$ je úplná množina komutujících

• K, J nejsou hermitovské

$$K^2 = \beta(\Sigma L + 1)\beta(\Sigma L + 1) = \beta^2(\Sigma L + 1)^2 = (\Sigma L)(\Sigma L) + 2\Sigma L + 1 =$$

$$= L^2 - \Sigma L$$

→ ~~$K^2 = L^2 - \Sigma L$~~ → $K^2 = J^2 + \frac{1}{4}$

spin-sférické (normalizované) funkce

$$\Psi = \begin{pmatrix} \psi_+ \\ \psi_- \end{pmatrix} = \begin{pmatrix} g(r) y_{j, l^+}^m \\ i f(r) y_{j, l^-}^m \end{pmatrix}$$

Rovnice pro $g(r)$ a $f(r)$

$$\text{I. } \left[-i \frac{d}{dr} - i \frac{(k+1)}{r} \right] i f(r) = [E - V(r) - m] g(r)$$

$$\text{II. } \left[-i \frac{d}{dr} + i \frac{(k-1)}{r} \right] g(r) = [E - V(r) + m] i f(r)$$

Kvantová teorie pole 2

Globalní symetrie

Metoda Emmy Noetherové (1918)

$$\phi \mapsto (\phi + (\epsilon \delta \phi)) = \phi + \epsilon^\alpha T^\alpha_{\beta\gamma} \phi_\beta$$

$$\boxed{\epsilon \delta \bar{\phi} = \epsilon^\alpha T^\alpha_{\beta\gamma} \bar{\phi}_\beta}$$

$$[T^\alpha, T^\beta] = i f^{\alpha\beta\gamma} T^\gamma$$

Předpokládáme, že Lagrangian $\mathcal{L}$ je invariantní vůči nějaké
množině symetrií $\Rightarrow \delta \mathcal{L} = 0$

Poznámka:

Zachovávací proud $J^\alpha_\mu = i \frac{\partial \mathcal{L}}{\partial (\partial_\mu \phi)} T^\alpha_{\beta\gamma} \phi_\beta$

$$\partial_\mu J^\alpha_\mu = 0 \Rightarrow \exists \theta^\alpha = \int d^3x J^\alpha_0 : \frac{d\theta^\alpha}{dt} = 0$$

Přip: $\epsilon = \text{konst} \rightarrow \epsilon(x)$

$$\phi \mapsto \phi' = \phi + \epsilon(x) \delta \phi \Rightarrow \delta \mathcal{L} = 0$$

$$\delta \mathcal{S} = \int d^4x [\mathcal{L}(\phi + \epsilon \delta \phi, \partial_\mu(\phi + \epsilon \delta \phi)) - \mathcal{L}(\phi, \partial_\mu \phi)]$$

Poznámka:

$$\delta \mathcal{L} = 0 = \int d^4x \frac{\partial \mathcal{L}}{\partial \phi} \frac{\delta \phi}{\epsilon \delta \phi} \Rightarrow \text{lineární v } \epsilon$$

$$= \int d^4x \left[\textcircled{\alpha} \epsilon^\alpha(x) + \textcircled{\alpha, \mu} \partial^\mu \epsilon^\alpha(x) \right] = \int d^4x \textcircled{\alpha, \mu} \partial^\mu \epsilon^\alpha(x) =$$

" $\delta \mathcal{L} = 0$ "

$$= \int d^4x [\Xi^\alpha_{, \mu}] \partial^\mu \epsilon^\alpha(x)$$

$$\delta S = \int d^4x [-J^\alpha_\mu] \partial^\mu \varepsilon^\alpha(x)$$

Pro řešení polynomických rovníc máme $\delta S = 0$:

$$0 = \int d^4x [-J^\alpha_\mu] \partial^\mu \varepsilon^\alpha(x) \stackrel{\text{p.p.}}{=} \int d^4x (\partial^\mu J^\alpha_\mu) \varepsilon^\alpha(x)$$

$$\Rightarrow \partial^\mu J^\alpha_\mu = 0$$

Příklad $U(1) \sim SO(2)$:

Symetrie pro skalární pole

$$\mathcal{L} = \frac{1}{2} \sum_{i=1}^2 (\partial_\mu \phi_i \partial^\mu \phi_i + m^2 \phi_i^2)$$

$$\vec{\phi} = \frac{1}{\sqrt{2}} (\phi_1 + i\phi_2)$$

$$\mathcal{L} = \partial_\mu \phi^* \partial^\mu \phi - m^2 \phi \phi^* = \phi^* [\square + m^2] \phi$$

→ Invariantní vzhledem k transformaci $\phi \rightarrow \phi' = e^{i\alpha} \phi$, $\alpha \in \mathbb{R}$
 $\phi^* \rightarrow \phi'^* = e^{-i\alpha} \phi^*$

$$\phi \xrightarrow{\text{inf}} \phi' = \phi + i\alpha \phi$$

$$\phi^* \xrightarrow{\text{inf}} \phi'^* = \phi^* - i\alpha \phi^*$$

$$\alpha \sim \alpha(x)$$

$$\delta S = \int d^4x (\mathcal{L}(\phi + i\alpha \phi, \phi^* - i\alpha \phi^*, \partial_\mu(\phi + i\alpha \phi), \partial_\mu(\phi^* - i\alpha \phi^*)) - \mathcal{L}(\phi, \phi^*, \partial_\mu \phi, \partial_\mu \phi^*))$$

$$= - \int d^4x ((\phi^* - i\alpha \phi^*)(\square + m^2)(\phi + i\alpha \phi) - \phi^*(\square + m^2)\phi) =$$

$$= - \int d^4x [\phi^*(\square + m^2)(i\alpha \phi)] = -i \int d^4x \phi^* \square(\alpha \phi) =$$

$$= -i \int d^4x [\phi^* (\square \alpha) \phi + 2 \phi^* \partial_\mu \alpha \partial^\mu \phi + \cancel{\phi^* \alpha \square \phi}] =$$

Průběh je

čtený zleva doprava

čtené!

$$= \int d^4x \underbrace{\partial_\mu \alpha}_{-J_\mu}$$

$$= -i \int d^4x [2\phi^* \partial^\mu \phi - \partial(\phi^* \phi)] \partial_\mu \alpha =$$

$$= -i \int d^4x [\phi^* \partial_\mu \phi - \phi \partial_\mu \phi^*] \partial^\mu \alpha =$$

$$\Rightarrow T_\mu = i(\phi^* \partial_\mu \phi - \phi \partial_\mu \phi^*)$$

Príklad 2: Diracova pole

$$\mathcal{L} = \bar{\Psi} (\gamma^\mu \partial_\mu - m) \Psi$$

$$\begin{aligned} \Psi &\rightarrow \Psi' = e^{i\alpha} \Psi \\ \bar{\Psi} &\rightarrow \bar{\Psi}' = e^{-i\alpha} \bar{\Psi} \quad (U(1) \text{ symetrie}) \end{aligned}$$

• Noetherova metóda $\alpha \rightarrow \alpha(x)$

$$\delta \mathcal{L} = \mathcal{L}(\bar{\Psi} - i\alpha \bar{\Psi}, \Psi + i\alpha \Psi, \partial_\mu(\Psi + i\alpha \Psi)) - \mathcal{L}(\bar{\Psi}, \Psi, \partial_\mu \Psi) =$$

$$= (\bar{\Psi} - i\alpha \bar{\Psi})(i\gamma^\mu \partial_\mu - m)(\Psi + i\alpha \Psi) - \bar{\Psi}(i\gamma^\mu \partial_\mu - m)\Psi =$$

$$= i\bar{\Psi}(i\gamma^\mu \partial_\mu - m)(\alpha \Psi) = i\bar{\Psi}(i\gamma^\mu \partial_\mu)(\alpha \Psi) =$$

$$= i\bar{\Psi}(\gamma^\mu \partial_\mu \alpha) \Psi = i\bar{\Psi} \gamma^\mu \Psi \partial_\mu \alpha$$

$$\Rightarrow \delta S = -i \int d^4x (\bar{\Psi} \gamma^\mu \Psi) \partial_\mu \alpha$$

$$\text{ON-SHELL } \delta S = 0 \Rightarrow \gamma^\mu = +\bar{\Psi} \gamma^\mu \Psi$$

Kvantova' uróven'

$$Q \mapsto \hat{Q} = \int d^3x \hat{\Psi}^\dagger \hat{Q} \hat{\Psi} \mapsto : \hat{Q} : = \hat{Q} + \text{kont}$$

$$\cdot [\hat{Q}, \hat{\Psi}(y)]_c = \int d^3x \left[\underbrace{\hat{\Psi}_\alpha^\dagger}_{A} \underbrace{\hat{Q}_{\alpha\beta}}_{B}, \underbrace{\hat{\Psi}_\beta}_{C}(y) \right]_c = \textcircled{*}$$

$$\boxed{[AB, C] = A[B, C] + [A, C]B}$$

$$\textcircled{*} = - \int d^3x \left\{ \underbrace{\hat{\Psi}_\alpha^\dagger(x)}_{\hat{a}^\dagger} \underbrace{\hat{\Psi}_\beta(y)}_{\hat{a}} \underbrace{\hat{Q}_{\alpha\beta}}_{\hat{a}^\dagger \hat{a}} \hat{\Psi}_\beta(x) \right\}$$

$$= - \int d^3x \hat{a}^\dagger \hat{a} \delta(x-y) \hat{\Psi}_\beta(x) = - \hat{\Psi}_\beta(y)$$

$$\Rightarrow \hat{Q} \hat{\Psi} = \hat{\Psi} (\hat{Q} - 1)$$

$$\Rightarrow \hat{Q} \hat{\Psi}^\dagger = \hat{\Psi}^\dagger (\hat{Q} + 1)$$

$$\hat{Q} \hat{a} = \hat{a} (\hat{Q} - 1)$$

$$\hat{Q} \hat{b} = \hat{b} (\hat{Q} - 1)$$

$$\hat{Q} \hat{a}^\dagger = \hat{a}^\dagger (\hat{Q} + 1)$$

$$\hat{Q} \hat{b}^\dagger = \hat{b}^\dagger (\hat{Q} + 1)$$

Noether method for internal symmetries (global symmetries)

$$[T^i, T^j] = i\gamma^{jk} T^k \mapsto J^{\mu} \rightarrow \partial_{\mu} J^{\mu} = 0 \rightarrow \exists \theta_i: \frac{d}{dt} \theta_i = 0 \quad (*)$$

$$\otimes [\theta^i, \theta^j] = i\gamma^{jk} \theta^k$$

$$\phi_x \mapsto \phi'_x = (e^{i\alpha^i \hat{T}_i} \phi)_x = (e^{-i\alpha^i \hat{T}_i} \phi_x e^{i\alpha^i \hat{T}_i})_x$$

Noether method for space-time symmetries

1) Translation invariance

i.e.: Invariance of Lagrangian $\mathcal{L}$ (modulo 4-divergence)
under transformation $\varphi(x) \mapsto \varphi(x+a)$

$$\varphi(x) \mapsto \varphi'(x) = \varphi(x) + a^{\mu} \partial_{\mu} \varphi(x)$$

$$a^{\mu} \mapsto a^{\mu}(x) \text{ (Noether method).}$$

$$\begin{aligned} \delta S &= \int d^4x \left[\mathcal{L}(\phi + a^{\mu} \partial_{\mu} \phi, \partial \phi + \partial(a^{\mu} \partial_{\mu} \phi)) - \mathcal{L}(\phi, \partial \phi) \right] = \\ &= \int d^4x \left[\frac{\partial \mathcal{L}}{\partial \phi} (a^{\mu} \partial_{\mu} \phi) + \frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} (\partial_{\nu} (a^{\mu} \partial_{\mu} \phi)) \right] = \\ &= \int d^4x \left[\left(\frac{\partial \mathcal{L}}{\partial \phi} \partial_{\mu} \phi + \frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} \partial_{\nu} (\partial_{\mu} \phi) \right) a^{\mu} + \left(\frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} \partial_{\mu} \phi \right) \partial_{\nu} a^{\mu} \right] = \\ &= \int d^4x \left[(\partial_{\mu} \mathcal{L}(\phi, \partial \phi)) a^{\mu} + \left(\frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} \partial_{\mu} \phi \right) \partial_{\nu} a^{\mu} \right] = \\ &= \int d^4x \left[\underbrace{\partial_{\mu} (a^{\mu} \mathcal{L})}_{=0} - \mathcal{L} \partial_{\mu} a^{\mu} + \left(\frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} \partial_{\mu} \phi \right) \partial_{\nu} a^{\mu} \right] = \end{aligned}$$

$$\text{Note: } \min a^{\mu} \underbrace{\int d^4x \partial_{\mu} \mathcal{L}}_{=0} \leq \int d^4x \partial_{\mu} a^{\mu} \mathcal{L} \leq \max a^{\mu} \underbrace{\int d^4x \partial_{\mu} \mathcal{L}}_{=0}$$

$$= \int d^4x \textcircled{\mu}^{\nu} \partial_{\nu} \phi^{\mu} \leftarrow \int d^4x \underbrace{\textcircled{i}^{\nu}}_{-J_i^{\nu}} \partial_{\nu} \xi^i$$

$$= \int d^4x \underbrace{\left[\frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} \partial_{\mu} \phi - \textcircled{\mu\nu} \mathcal{L} \right]}_{\textcircled{\mu\nu}} \partial^{\nu} \phi^{\mu} \stackrel{!}{=} 0 \stackrel{(\#)}{=} \delta S$$

In that case we have (on-shell):

$$0 \stackrel{\text{D.P.}}{=} - \int d^4x \left(\partial_{\alpha}^{\nu} \left[\frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} \partial_{\mu} \phi - \textcircled{\mu\nu} \mathcal{L} \right] \right) \phi^{\mu}(x), \text{ for every } \phi^{\mu}(x)$$

$$\Rightarrow \partial^{\nu} (\textcircled{\mu\nu}) = 0$$

$$\boxed{T_{\mu\nu} = \partial_{\mu} \phi \frac{\partial \mathcal{L}}{\partial (\partial_{\nu} \phi)} - \textcircled{\mu\nu} \mathcal{L}}$$

↓ $\textcircled{\mu\nu} \sim \Theta_i = \int d^3x J_i^0$

• $P_{\mu}^{\alpha} = + \int d^3x T^{0\alpha} = Q^{\alpha}$

ii) Lorentz transformation

$$\phi(x) \mapsto \phi'(x) = S(L) \phi(L^{-1}x)$$

$$\rightarrow 0 = \dots = \int d^4x \textcircled{\mu\nu}^{\alpha\beta} \partial_{\nu} \phi^{\mu}$$

$$\rightarrow \textcircled{\mu\nu}^{\alpha\beta} = x^{\alpha} T^{\mu\beta} - x^{\beta} T^{\mu\alpha}$$

$$\rightarrow \Theta^{\alpha\beta} = M^{\alpha\beta} = \int d^3x (x^{\alpha} T^{0\beta} - x^{\beta} T^{0\alpha})$$

Angular momentum density

Recap: Internal symmetries

$$\psi \sim \psi' = e^{i\alpha T^a} \psi, \quad [T^a, T^b] = i f^{abc} T^c$$
$$[Q^a, Q^b] = i f^{abc} Q^c$$

$$\psi' = e^{-i\alpha^a Q^a} \psi e^{i\alpha^a T^a}$$

Space-time symmetries

$$\psi \sim \psi'(x) = \psi(x+a)$$

Free propagator

- Causality issue

Relativistically invariant commutation relations

$$i\Delta(x) = [\varphi(x), \varphi(0)]$$

$$i\Delta(t, x) = [\varphi(t, x), \varphi(0)]$$

$$\left. \begin{aligned} \frac{\partial}{\partial t} \Delta(t, x) &= i[\pi(t, x), \varphi(0)] \\ i\Delta(0, x) &= 0 \end{aligned} \right\} \frac{\partial}{\partial t} \Delta(t, x) \Big|_{t=0} = -i(-i\delta(x)) = -\delta(x)$$

$$(\square + m^2) \varphi(x) = 0 \quad (\text{every quantum relativ. particle does})$$

$$\downarrow$$

$$(\square + m^2) \Delta(x) = 0$$

$$\rightarrow \Delta(x) = -i \int d^4p \frac{1}{(2\pi)^4 2\omega_p} (f(p) e^{-ip \cdot x} + h(p) e^{ip \cdot x})$$

$$\Delta(0, x) = -i \int d^4p \frac{1}{(2\pi)^4 2\omega_p} (f(p) e^{ipx} + h(p) e^{-ipx}) =$$

$$= -i \int d^4p \frac{1}{(2\pi)^4 2\omega_p} [f(p) + h(p_p)] e^{ipx} = 0$$

$$\downarrow$$

$$p_p^0 = (\omega_p, -\mathbf{p})$$

$$\rightarrow f(p) + h(p_p) = 0$$

$$\frac{\partial}{\partial t} \Delta(t, x) \Big|_{t=0} = -i \int d^4p \frac{1}{(2\pi)^4 2\omega_p} (-i\omega_p f(p) e^{ipx} + i\omega_p h(p) e^{-ipx}) =$$

$$= - \int d^4p \frac{1}{(2\pi)^4 2\omega_p} (f(p) - h(p_p)) e^{ipx} = -\delta(x)$$

$$\rightarrow f(p) - h(p_p) = 2 \Rightarrow \boxed{f(p) = 1, h(p_p) = -1 = h(p)}$$

$$\Delta(x) = i \int d^4p \frac{1}{(2\pi)^4 2m} (e^{-ipx} - e^{ipx}) = \Delta(L^{-1}x)$$

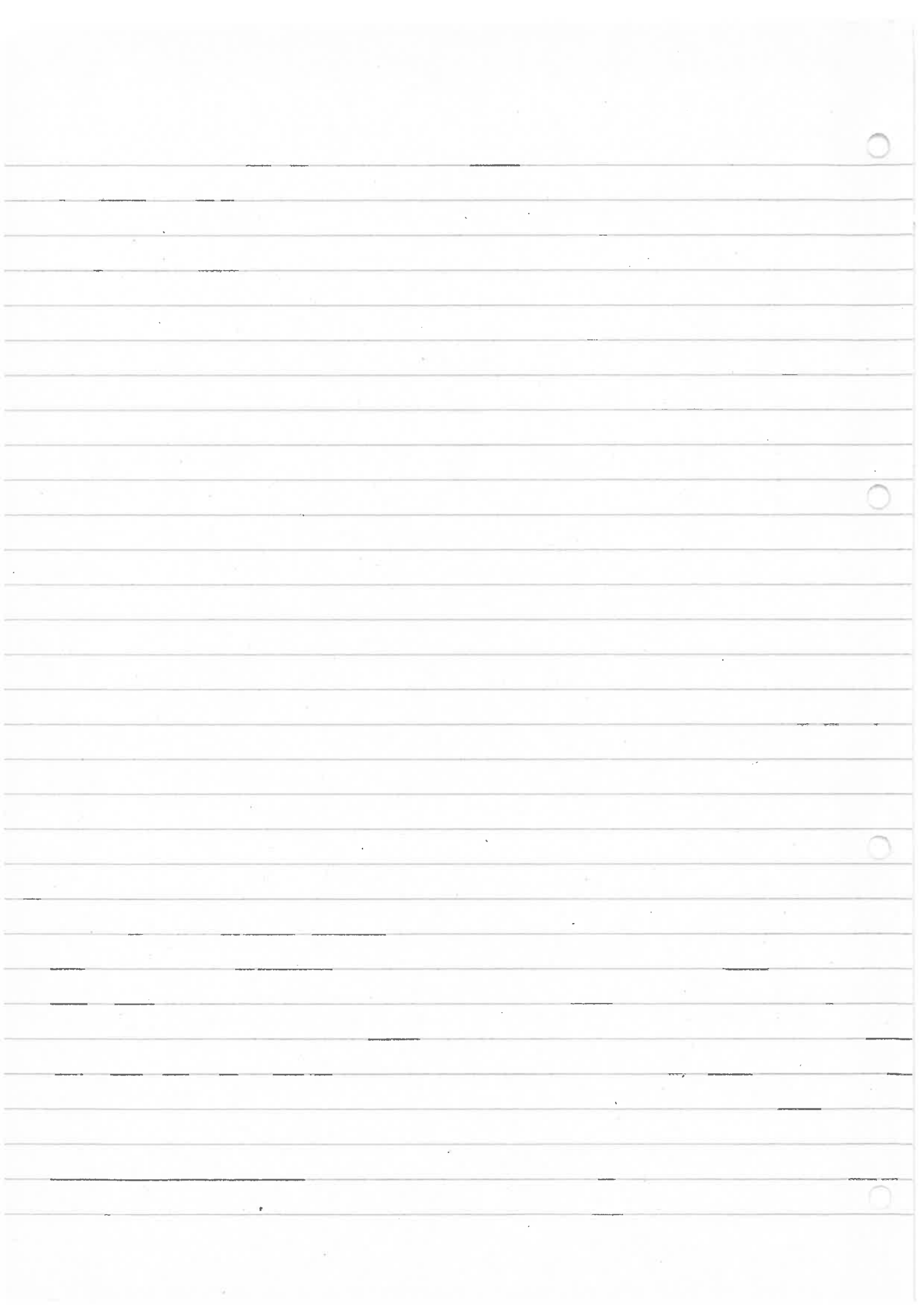
$$d^4p' = d^4p \underbrace{|\det L|}_1$$

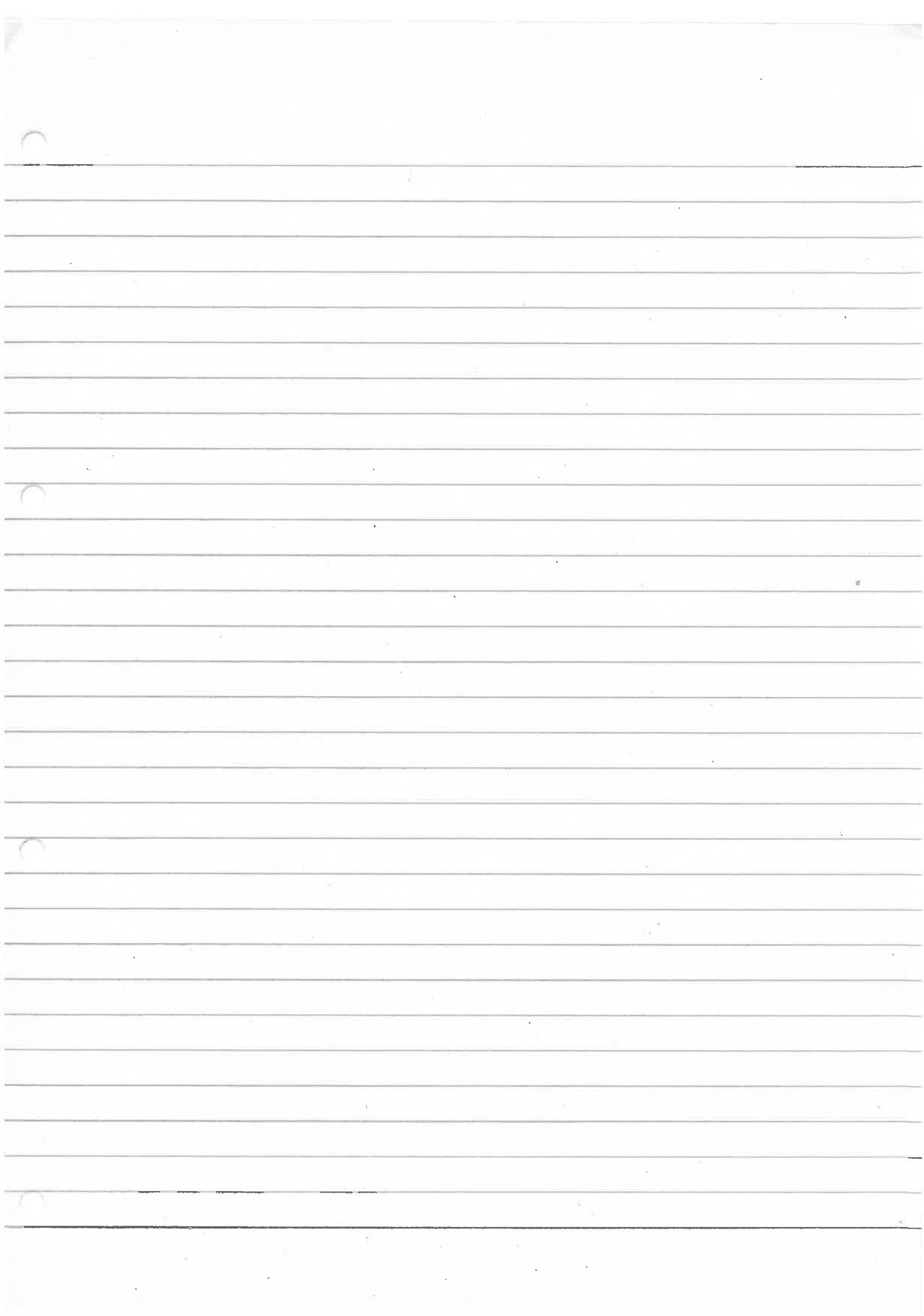
$$\delta(p^2 - m^2) = \delta(p'^2 - m^2)$$

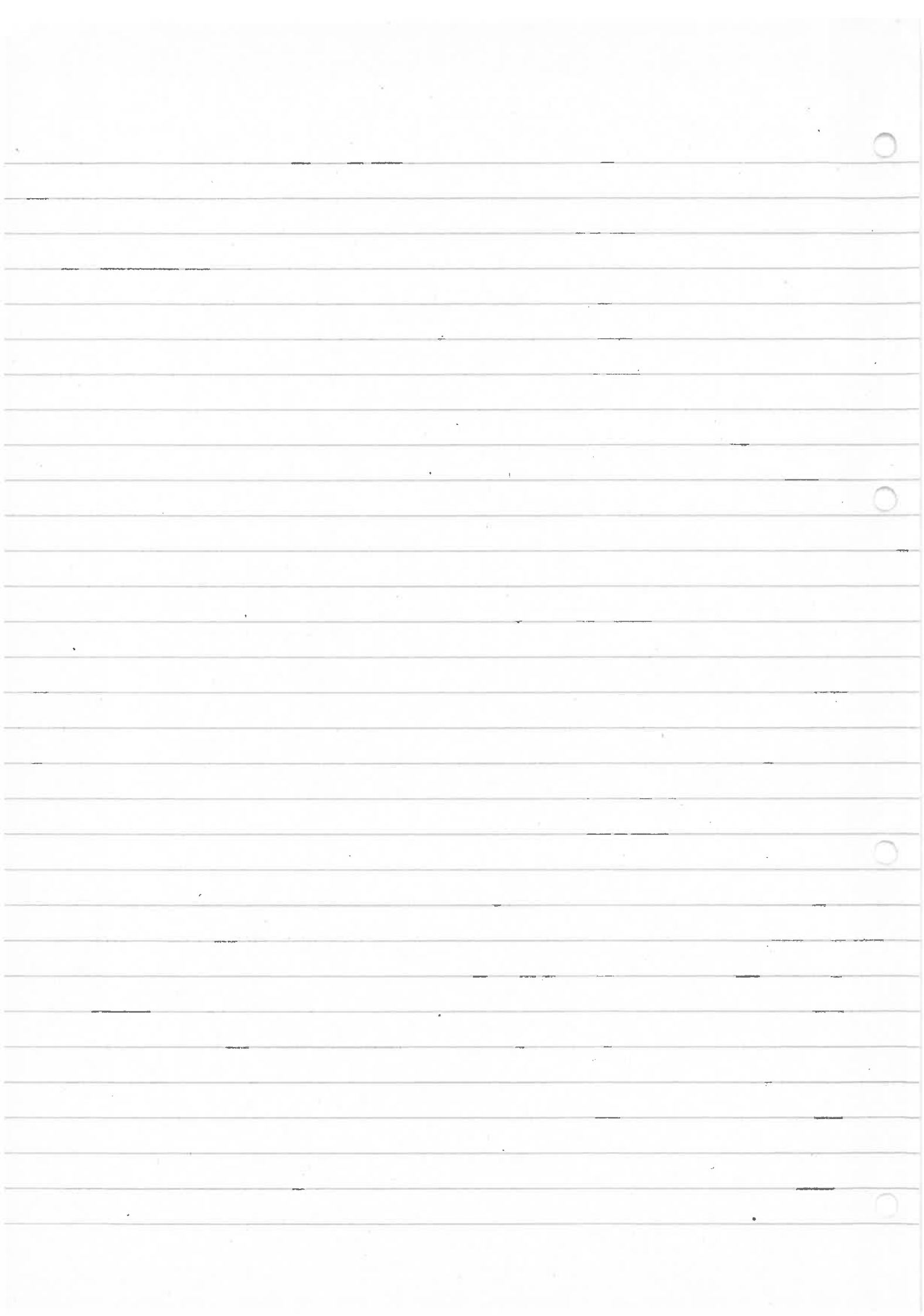
$$\varepsilon(p^0) = \begin{cases} 1, & p^0 > 0 \\ -1, & p^0 < 0 \end{cases}$$

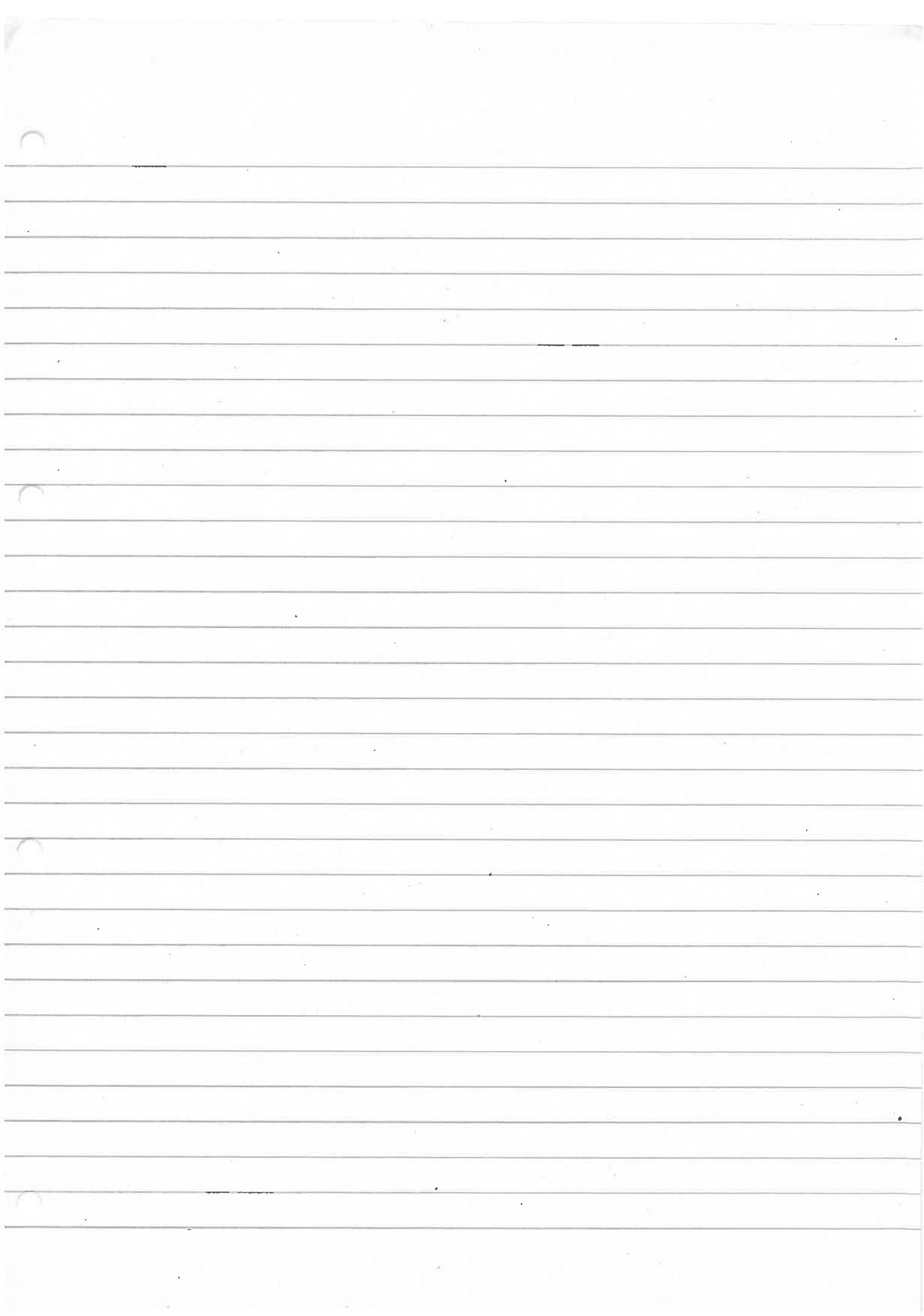
$$\parallel$$

$$\varepsilon(p^0)$$









4. přednáška

$$i\Delta_F = \langle 0 | T[\psi(x) \bar{\psi}(0)] | 0 \rangle = i \int \frac{d^4 p}{(2\pi)^4} \frac{e^{-ipx}}{p^2 - m^2 + i\epsilon}$$

$$\downarrow$$

$$(\Box + m^2)\Delta_F(x) = -\delta(x)$$

Feynman-Stueckelberg

Propagator = 2-bodová greenova funkce (volná) = amplituda přechodu = 2-bodová 'každou' funkce
= kačlaton

$$x^2 = 0 \rightarrow \delta(x^2) \frac{1}{4\pi}$$

$$x^2 > 0 \rightarrow K_1 \Theta(-x^2)$$

$$x^2 < 0 \rightarrow (J_1 + Y_1) \Theta(x^2)$$

$$\left. \begin{array}{l} x^2 = 0 \rightarrow \delta(x^2) \frac{1}{4\pi} \\ x^2 > 0 \rightarrow K_1 \Theta(-x^2) \\ x^2 < 0 \rightarrow (J_1 + Y_1) \Theta(x^2) \end{array} \right\} \text{Pro } |x| \ll 1 \approx \frac{1}{4\pi} \delta(x^2) \cdot \frac{1}{4\pi^2 x^2} + \frac{im^2}{8\pi^2} \ln|x| - \frac{m^2}{16\pi} \Theta(x^2)$$

$$x^2 < 0 \sim \Delta_F(x) = \frac{im}{4\pi^2} \frac{K_1(m\sqrt{-x^2})}{\sqrt{-x^2}}$$

$$|x| \gg 1: \frac{1}{4} \sqrt{\frac{m}{2(|x|m)^3}} e^{-im|x|} [1 + O(\frac{1}{|x|})] = \frac{1}{4} \sqrt{\frac{mc}{\hbar 2(|x|m)^3}} e^{-\frac{mc}{\hbar}|x|} [1 + O(\frac{1}{|x|})]$$

Propagation po Diracovské a' pole

$$T[\psi_a(x)\bar{\psi}_b(y)] = \theta(x_0 - y_0)\psi_a(x)\bar{\psi}_b(y) - \theta(y_0 - x_0)\bar{\psi}_b(y)\psi_a(x)$$

$$\rightarrow i(S_F(x+y))_{ab} = \langle 0 | T[\psi_a(x)\bar{\psi}_b(y)] | 0 \rangle$$

$$\text{Le uvažat, že } (S_F(x))_{ab} = -i \langle 0 | T[\psi_a(x)\bar{\psi}_b(0)] | 0 \rangle =$$

$$= \int \frac{d^4 p}{(2\pi)^4} \frac{e^{-ipx}}{p^2 - m^2 + i\epsilon} (p + m)_{ab}$$

$$\cdot x_0 > 0: -i \langle 0 | \sum_{p,p'} \sum_{\lambda,\lambda'} [a(p,\lambda) u_\alpha(p,\lambda) e^{-ipx} + b^\dagger(p,\lambda) v_\alpha(p,\lambda) e^{ipx}] \cdot$$

$$\cdot [b(p',\lambda) \bar{v}_\beta(p',\lambda) e^{ip'0} + a^\dagger(p',\lambda') \bar{u}_\beta(p',\lambda') e^{ip'0}] | 0 \rangle =$$

$$\text{op. upravu a' } = -i \sum_{p,p'} \sum_{\lambda,\lambda'} \langle 0 | a(p,\lambda) a^\dagger(p',\lambda') | 0 \rangle u_\alpha(p,\lambda) \bar{u}_\beta(p',\lambda') e^{-ipx} =$$

$$\text{anulace! op. nula}$$

$$= -i \sum_{p,p'} \sum_{\lambda,\lambda'} \underbrace{\langle 0 | a(p,\lambda) a^\dagger(p',\lambda') | 0 \rangle}_{\delta_{pp'} \delta_{\lambda\lambda'}} u_\alpha(p,\lambda) \bar{u}_\beta(p',\lambda') e^{-ipx} =$$

$$= -i \sum_{p,\lambda} u_\alpha(p,\lambda) u_\beta(p,\lambda) e^{-ipx} = -i \sum_p (p + m)_{ab} e^{-ipx}$$

$$\cdot x_0 < 0: \dots = -i \sum_p (p - m)_{ab} e^{ipx} \xrightarrow{\text{Cauchyho integrální křivka}} \textcircled{2}$$

$$\textcircled{2} (S_F(x))_{ab} = \int \frac{d^4 p}{(2\pi)^4} \frac{e^{-ipx} (p + m)}{p^2 - m^2 + i\epsilon}$$

Tworu:

$$(i \not{\partial} - m)(S_F(x))_{ab} = \delta(x) \mathbb{I}_{ab}$$

$$\begin{aligned}
(i \not{\partial} - m) (S_F(x))_{\alpha\beta} &= (i \not{\partial} - m)_{\alpha\gamma} \int \frac{d^4 p}{(2\pi)^4} \frac{e^{-ipx} (\not{p} + m)_{\gamma\beta}}{p^2 - m^2 + i\epsilon} \\
&= \int \frac{d^4 p}{(2\pi)^4} \frac{(\not{p} - m)_{\alpha\gamma} e^{-ipx} (\not{p} + m)_{\gamma\beta}}{p^2 - m^2 + i\epsilon} \\
&= \int \frac{d^4 p}{(2\pi)^4} \frac{(p^2 - m^2) e^{-ipx} \mathbb{I}_{\alpha\beta}}{p^2 - m^2 + i\epsilon} = \\
&= \int \frac{d^4 p}{(2\pi)^4} \frac{(p^2 - m^2 + i\epsilon) e^{-ipx}}{p^2 - m^2 + i\epsilon} \int \frac{d^4 p}{(2\pi)^4} \frac{i\epsilon e^{-ipx}}{p^2 - m^2 + i\epsilon} = \\
&= \int \frac{d^4 p}{(2\pi)^4} \not{\partial} e^{-ipx} - i\epsilon \Delta_F(x) = \not{\partial} \delta(x)
\end{aligned}$$

Poznámka:

$$[\not{p} - (m \pm i\epsilon)][\not{p} + (m \pm i\epsilon)] = p^2 - m^2 \mp 2i\epsilon m + \epsilon^2 \approx p^2 - m^2 \mp i\epsilon'$$

$$[\not{p} + (m \pm i\epsilon)]^{-1} [\not{p} - (m \pm i\epsilon)]^{-1} = \frac{1}{p^2 - m^2 \pm i\epsilon}$$

$$\rightarrow [\not{p} + (m - i\epsilon)]^{-1} [\not{p} - (m - i\epsilon)]^{-1} = \frac{1}{p^2 - m^2 + i\epsilon}$$

$$\begin{aligned}
\rightarrow \frac{\not{p} + m}{p^2 - m^2 + i\epsilon} &= (\not{p} + m) [\not{p} + (m - i\epsilon)]^{-1} [\not{p} - (m - i\epsilon)]^{-1} = \\
&= [\not{p} - (m - i\epsilon)]^{-1} + \frac{i\epsilon}{p^2 - m^2 + i\epsilon}
\end{aligned}$$

$$\rightarrow (S_F(x))_{\alpha\beta} = \int \frac{d^4 p}{(2\pi)^4} \frac{e^{-ipx}}{(\not{p} - m + i\epsilon)_{\alpha\beta}}$$

Interakční pole - rovněž počít (hermitovsky skalární pole)

Do posed: $\mathcal{L}_0 = \frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2$

Kupříklad: $\mathcal{L}_I = -V_I = -\frac{g}{3!} \phi^3 - \frac{\lambda}{4!} \phi^4$

$$\mathcal{L} = \mathcal{L}_0 + \mathcal{L}_I = \mathcal{L}_0 - V_I = \frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 - \frac{g}{3!} \phi^3 - \frac{\lambda}{4!} \phi^4 =$$

$$= \frac{1}{2} (\dot{\phi})^2 - \frac{1}{2} (\nabla \phi)^2 - \frac{1}{2} m^2 \phi^2 - \frac{g}{3!} \phi^3 - \frac{\lambda}{4!} \phi^4$$

$$\pi = \frac{\partial \mathcal{L}}{\partial \dot{\phi}} = \dot{\phi}$$

$$\mathcal{H} = \pi \dot{\phi} - \mathcal{L} = \pi^2 - \left(\frac{1}{2} \pi^2 - \frac{1}{2} (\nabla \phi)^2 - \frac{1}{2} m^2 \phi^2 \right) + V_I =$$

$$= \frac{1}{2} \pi^2 + (\nabla \phi)^2 + \frac{1}{2} m^2 \phi^2 + \frac{g}{3!} \phi^3 + \frac{\lambda}{4!} \phi^4$$

5. Půchova'ska (Ponchova' teorie)

$$\mathcal{L} = \frac{1}{2} \partial_\mu \phi \partial^\mu \phi - \frac{1}{2} m^2 \phi^2 - \underbrace{\frac{g}{3!} \phi^3 + \frac{1}{4!} \phi^4}_{-V(\phi)}$$

$$\begin{aligned} \rightarrow \mathcal{H} &= \frac{\partial \mathcal{L}}{\partial \dot{\phi}} \dot{\phi} - \mathcal{L} = \frac{1}{2} \dot{\phi}^2 + \frac{1}{2} (\nabla \phi)^2 + \frac{1}{2} m^2 \phi^2 + \frac{g}{3!} \phi^3 + \frac{1}{4!} \phi^4 = \\ &= \frac{1}{2} \pi^2 + \frac{1}{2} (\nabla \phi)^2 + \frac{1}{2} m^2 \phi^2 + \frac{g}{3!} \phi^3 + \frac{1}{4!} \phi^4 \end{aligned}$$

$$\rightarrow H = \int d^3x \mathcal{H} = H_0 + H_I =$$

$$H_0 = \int d^3x \mathcal{H}_0, \quad H_I = \int d^3x \mathcal{H}_I = V(\phi)$$

$$\mathcal{H}_I = -\mathcal{L}_I \Rightarrow H_I = -L_I$$

$$\rightarrow \text{Ponchova' rovnice} : \partial_\mu \left(\frac{\partial \mathcal{L}}{\partial \partial_\mu \phi} \right) - \frac{\partial \mathcal{L}}{\partial \phi} \stackrel{!}{=} 0$$

$$\square \phi + m^2 \phi + \underbrace{\frac{g}{3!} \phi^2 + \frac{1}{4!} \phi^3}_{\frac{dV}{d\phi}} = 0 \quad \Leftarrow \text{Heisenbergovy rovnice}$$

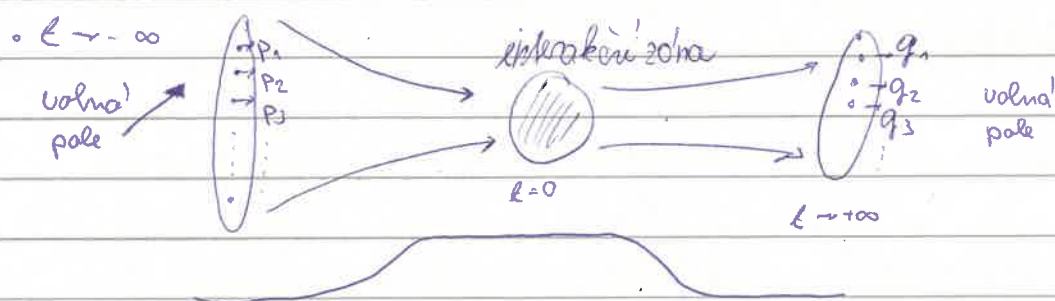
• Ponchova' teorie (intro)

Časujeme se Schrödingerovou rovnici:

$$H = \int d^3x \left(\frac{1}{2} \pi^2(0, x) + \frac{1}{2} (\nabla \phi(0, x))^2 + \frac{1}{2} m^2 \phi^2(0, x) \right) + \int d^3x \left(\frac{g}{3!} \phi^3(0, x) + \frac{1}{4!} \phi^4(0, x) \right)$$

Diracova (interakčijná) reprezentácia

↳ "Cluster-decomposition property"



i) Schrödingerova obraz

$$i \frac{d}{dt} |\Psi(t)\rangle_S = H^S |\Psi(t)\rangle_S \Rightarrow |\Psi(t)\rangle_S = e^{iH^S t} |\Psi(0)\rangle_S$$

ii) Diracova (interakčijná) obraz

$$|\Phi(t)\rangle_S = e^{iH_0^S t} |\phi(t)\rangle_S \Leftrightarrow |\phi(t)\rangle_S = e^{-iH_0^S t} |\Phi(t)\rangle_S$$

$\Leftrightarrow$ oddelenie voľnej evolúcie z dynamickým stavom $|\phi(t)\rangle_S$

$$\begin{aligned} i \frac{d}{dt} |\Phi(t)\rangle_S &= H^S |\Phi(t)\rangle_S = H_0^S |\Phi(t)\rangle_S + e^{iH_0^S t} \underbrace{i \frac{d}{dt} |\phi(t)\rangle_S}_{H^S |\phi(t)\rangle_S} \\ &= e^{iH_0^S t} H_+^S e^{-iH_0^S t} |\phi(t)\rangle_S \end{aligned}$$

Definícia:

Operátor $\hat{A}$ v interakčijnej obraz je definovaný vzťahom

$$\hat{A}_D = e^{iH_0^S t} \hat{A}_S e^{-iH_0^S t}$$

→ Vždy sloví je dle iterací interakční části hamiltoniánu

Dynamická rovnice pro operátor:

$$i \frac{d}{dt} \hat{A}_D = \cancel{[H_0, \hat{A}_D]} e^{+iH_0^S t} [\hat{A}_S, H_0^S] e^{-iH_0^S t} = [\hat{A}_D, H_0^S]$$

Rovnice pro stavy

$$i \frac{d}{dt} |\phi(t)\rangle_D = H_D(t) |\phi(t)\rangle_D, \text{ pro } t=t_i: |\phi(t_i)\rangle_D = |\phi_i\rangle$$

Řešení se obvykle hledá v tvaru: $|\phi(t)\rangle_D = |\phi_i\rangle + \int_{t_i}^t dt' H_D(t') |\phi(t')\rangle_D$

(Volterra rovnice 2. druhu)

iterativně:

1) $|\phi(t)\rangle_D = |\phi_i\rangle$

2) $|\phi(t)\rangle_D = |\phi_i\rangle + \int_{t_i}^t dt' H_D(t') |\phi_i\rangle$

3) $|\phi(t)\rangle_D = |\phi_i\rangle + \int_{t_i}^t dt' H_D(t') |\phi_i\rangle + \left(\frac{1}{i}\right)^2 \int_{t_i}^t dt' \int_{t_i}^{t'} dt'' H_D(t') H_D(t'') |\phi_i\rangle$

!

$$|\phi(t)\rangle_D = |\phi_i\rangle + \sum_{n=1}^{\infty} (-i)^n \int_{t_i}^t dt' \int_{t_i}^{t'} dt'' \dots \int_{t_i}^{t^{n-1}} dt^{n-1} H_D(t') H_D(t'') \dots H_D(t^{n-1}) |\phi_i\rangle =$$

$$= U(t, t_i) |\phi_i\rangle$$

$$U(t, t_i) = 1 + \sum_{n=1}^{\infty} (-i)^n \int_{t_i}^t dt' \int_{t_i}^{t'} dt'' \dots \int_{t_i}^{t^{n-1}} dt^{n-1} H_D(t') \dots H_D(t^{n-1})$$

Cauchy's formula for ordered integrals

$F(t_1, \dots, t_n)$ ← symmetric function

Tracy:

$$(-i)^n \int_{t_1}^t dt^1 \int_{t_1}^{t^1} dt^2 \dots \int_{t_1}^{t^{n-1}} dt^n f(t^1) f(t^2) \dots f(t^n) = \frac{(-i)^n}{n!} \int_{t_1}^t dt^1 \int_{t_1}^{t^1} dt^2 \dots \int_{t_1}^{t^{n-1}} dt^n F(t^1, \dots, t^n)$$

Dyson

or: chronological exponential

$$(-i)^n \int_{t_1}^t dt^1 \dots \int_{t_1}^{t^{n-1}} dt^n T[H_{\frac{1}{2}}(t^1) \dots H_{\frac{1}{2}}(t^n)] = \frac{(-i)^n}{n!} \int_{t_1}^t dt^1 \dots \int_{t_1}^{t^{n-1}} dt^n T[H_{\frac{1}{2}}(t^1) \dots H_{\frac{1}{2}}(t^n)] =$$

$$U(t, t_1) = 1 + \sum_{n=1}^{\infty} \frac{(-i)^n}{n!} \int_{t_1}^t dt^1 \dots \int_{t_1}^{t^{n-1}} dt^n T[H_{\frac{1}{2}}(t^1) \dots H_{\frac{1}{2}}(t^n)] =$$

$$= T(\exp(-i \int_{t_1}^t H_{\frac{1}{2}}(x) dx))$$

6. přednáška

$$U(t, t_i) = T \left[\exp(-i \int_{t_i}^t d\tau \bar{H}_I) \right] = T \left[\exp(+i \int_{t_i}^t d\tau \bar{L}_I) \right]$$

↑
evoluční operátor v interakčním oboru

Interakce

$$U(+\infty, -\infty) = T \left[\exp(+i \int_{-\infty}^{+\infty} d\tau \bar{L}_I) \right] = T \left[\exp(i \int d^4x \bar{\mathcal{L}}_I) \right]$$

$$\bar{H}_I = \int d^3x \bar{\mathcal{H}}_I$$

$$\text{Klarický } \bar{\mathcal{H}}_I = \frac{g}{3!} \phi^3 + \frac{\lambda}{4!} \phi^4$$

Schro'dingerův obor $\rightarrow$ Interakční obor:

$$\phi_I(t, x) = e^{iH_0^I t} \phi_S(q, x) e^{-iH_0^I t} = e^{+iH_0^I t} \phi_I(q, x) e^{-iH_0^I t}$$

$$\rightarrow \mathcal{H}_I^S = \bar{\mathcal{H}}_I(0) = \int d^3x \left(\frac{g}{3!} \phi_I^3(q, x) + \frac{\lambda}{4!} \phi_I^4(q, x) \right)$$

$$\rightarrow \bar{\mathcal{H}}_I(t) = e^{-iH_0^I t} \bar{\mathcal{H}}_I(0) e^{+iH_0^I t} = \int d^3x \left(\frac{g}{3!} \phi_I^3(t, x) + \frac{\lambda}{4!} \phi_I^4(t, x) \right)$$

Obecněji:

$$\Theta_I(t) = e^{+iH_0^I(t-t')} \Theta_I(t') e^{-iH_0^I(t-t')}$$

$$i \frac{d}{dt} \Theta_I(t) = [\Theta_I(t), H_0^I]$$

$$\pi_I(t, x) = e^{+iH_0^I t} \pi_S(x) e^{-iH_0^I t} = e^{+iH_0^I t} \pi_I(q, x) e^{-iH_0^I t}$$

$$[\phi_S(x), \pi_S(y)] = i\delta(x-y) \rightarrow e^{iH_0 t} \underbrace{[\phi_S(x), \pi_S(y)]}_{\substack{(\underline{t}, x) \quad (\underline{t}, y) \\ [\phi_I(\underline{x}), \pi_I(\underline{y})]}} e^{iH_0 t} = i\delta(x-y)$$

Heisenbergův a interakční obar

předpokládá se čísel L_D se obar obar, rovnice

$$\phi_I(t, x) = e^{iH_0^I(t-t_0)} \phi_I(t_0, x) e^{-iH_0^I(t-t_0)}$$

$$\phi_H(t, x) = e^{iH(t-t_0)} \phi_H(t_0, x) e^{-iH(t-t_0)}$$

$$\rightarrow \phi_H(t_0, x) = \phi_I(t_0, x) = e^{-iH(t-t_0)} \phi_H(t, x) e^{iH(t-t_0)}$$

$$\rightarrow \phi_I(t, x) = \underbrace{e^{iH_0^I(t-t_0)} e^{iH(t-t_0)}}_{\Lambda(t, t_0)} \phi_H(t, x) \underbrace{e^{iH(t-t_0)} e^{-iH_0(t-t_0)}}_{\Lambda'(t, t_0) = \Lambda^*(t, t_0)}$$

Že se může najít $\Lambda(t, t_0)$ a interakčním obar

Λ : Ano!

$$\dot{\phi}_I(t, x) = i[H_0^I(\phi_I, \pi_I), \phi_I(t, x)]$$

$$\dot{\phi}_H(t, x) = i[H(\phi_H, \pi_H), \phi_H(t, x)]$$

$$\dot{\phi}_I(t, x) = H(t, t_0) \phi_H(t, x) \Lambda'(t, t_0)$$

$$\frac{d}{dt}(\Lambda \Lambda') = 0 \Leftrightarrow \Lambda \frac{d}{dt} \Lambda' + \left(\frac{d}{dt} \Lambda \right) \Lambda' = 0 \Leftrightarrow \Lambda \dot{\Lambda}' = -\dot{\Lambda} \Lambda'$$

$$\frac{d}{dt} \Phi_I = \dot{\Lambda} \Phi_I \Lambda^{-1} + \Lambda \dot{\Phi}_I \Lambda^{-1} + \Lambda \Phi_I (\dot{\Lambda}^{-1})$$

$$\rightarrow i \frac{d\Lambda}{dt} = (H_I + ic) \Lambda$$

$$\begin{aligned} \Lambda(t, t_0) &= T \left[\exp \left(-i \int_{t_0}^t dt' (H_I + ic) \right) \right] = \\ &= \exp \left(\int_{t_0}^t dt' c(t') \right) \cdot T \left[\exp \left(-i \int_{t_0}^t dt' H_I \right) \right] \end{aligned}$$

Pro normalne' matricne' elementy $\Lambda(t, t_0) = U(t, t_0)$

↓
Dysonov body

↓
Dysonova reprezentacija

Trazenje:

$$\begin{aligned} \Lambda(t, t') &= T \left[\exp \left(-i \int_{t'}^t dt'' H_I \right) \right] = T \left[\exp \left(i \int_{t_0}^t dt'' H_I \right) \right] = T \left[\exp \left(i \int_{t_0}^t dt'' \int d^3x \mathcal{L}_I(\dots) \right) \right] \\ \Lambda(t', t') &= \mathbb{I} \end{aligned}$$

$$\text{Naci } i \dot{\Lambda}(t, t') = H_I(t) \Lambda(t, t')$$

Polazimka:

$$t^3 \geq t^2 \geq t^1$$

$$\begin{aligned} \Lambda(t^3, t^2) \Lambda(t^2, t^1) &= \Lambda(t^3, t^0) \Lambda^{-1}(t^2, t^0) \Lambda(t^2, t^0) \Lambda^{-1}(t^1, t^0) = \\ &= \Lambda(t^3, t^0) \Lambda^{-1}(t^1, t^0) = \Lambda(t^3, t^1) \end{aligned}$$

$$(\Lambda(t^2, t^1))^* = \Lambda^{-1}(t^2, t^1) = \Lambda(t^1, t^2)$$

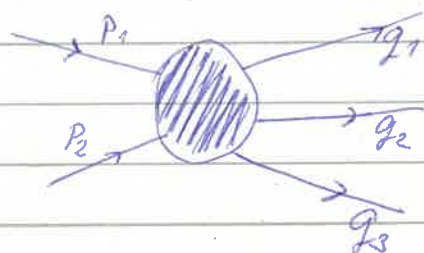
7. přednáška + 8. přednáška

Rozptyl částic

Předpoklad:

$$\forall t \sim -\infty : \phi_I(t, x) = \phi_H(t, x) = \phi_{in}(t, x)$$

$$t \sim +\infty : \phi_H(t, x) = \phi_{out}(t, x)$$



Čím je amplituda přechodu při této interakci?
(tj. dvě částice s p_1, p_2 do dvou částic q_1, q_2, q_3)

- počáteční stav ($t \sim -\infty$) (In-state)
- konečný stav ($t \sim +\infty$) (Out-state)

$$\text{Cíl: } |i\rangle_{in} = |\{p_i\}\rangle_{in}$$

$$|f\rangle_{out} = |\{q_i\}\rangle_{out}$$

$$\boxed{\langle f | S | i \rangle_{in}}$$

$$\bullet L_I \rightarrow \int dt L_I, \quad \int dt =$$



Definieren: $t \sim -\infty : \phi_{in}(E, x) := \phi_I(E, x) = \phi_H(E, x)$

$t \sim +\infty : \phi_{out}(E, x) := \phi_H(E, x)$

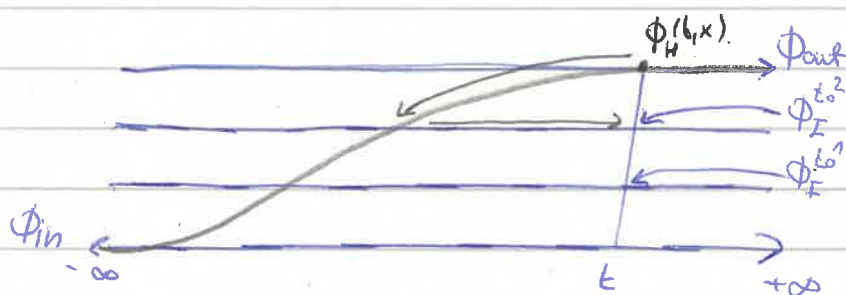
(Cluster decomposition)

$$\phi_{in}(E, x) = \phi_I(E, x) = \lim_{t_0 \sim -\infty} \exp(iH_0^I(t-t_0)) \phi_{in}(E, t_0) \exp(-iH_0^I(t-t_0))$$

Poshoden ko:

$$E_0^1 \& E_0^2 : \phi_I^{E_0^1}(E, x) = \Lambda(E, E_0^1) \phi_H(E, x) \Lambda^{-1}(E, E_0^1)$$

$$\phi_I^{E_0^2}(E, x) = \Lambda(E, E_0^2) \phi_H(E, x) \Lambda^{-1}(E, E_0^2)$$



$$\rightarrow \phi_I^{E_0^2}(E, x) = \Lambda(E, E_0^2) \phi_H(E, x) \Lambda^{-1}(E, E_0^2)$$

$$\rightarrow \underbrace{\phi_I^{-\infty}(E, x)}_{\phi_{in}(E, x)} = \Lambda(E, -\infty) \phi_H(E, x) \Lambda^{-1}(E, -\infty)$$

$$\rightarrow \phi_{in}(+\infty, x) = \underbrace{\Lambda(+\infty, -\infty)}_S \underbrace{\phi_H(+\infty, x)}_{\phi_{out}(x)} \underbrace{\Lambda^{-1}(+\infty, -\infty)}_{S^+}$$

$$\downarrow$$

$$a_{in} = S a_{out} S^+$$

$$a_{in}^+ = S a_{out}^+ S^+$$

$$\rightarrow \langle 0 | \phi_{in}^2 | 0 \rangle_{in} = \langle 0 | \phi_{out}^2 | 0 \rangle_{out} = \langle 0 | S \phi_{in}^2 S^\dagger | 0 \rangle_{in}$$

$$\rightarrow |0\rangle_{out} = S^\dagger |0\rangle_{in} \Leftrightarrow |0\rangle_{in} = S |0\rangle_{out}$$

$$a_{in}^\dagger(p) |0\rangle_{in} = |p\rangle_{in}$$

$$S a_{out}^\dagger S^\dagger S |0\rangle_{out} = S |p\rangle_{out}$$

$$\boxed{\rightarrow |i\rangle_{in} = S |i\rangle_{out}}$$

$$C_{fi} = \text{out} \langle f | i \rangle_{in}$$

$$|i\rangle_{in} = S |i\rangle_{out}, |f\rangle_{in} = S |f\rangle_{out} \Rightarrow \text{out} \langle f | S^\dagger = \text{out} \langle f | = \text{in} \langle f |$$

$$|i\rangle_{in} = |Si\rangle_{out}$$

$$\rightarrow \text{out} \langle f | i \rangle_{in} = \text{out} \langle f | S^\dagger S | i \rangle_{in} = \text{in} \langle f | S | i \rangle_{in} = \text{out} \langle f | S S^\dagger | i \rangle_{in} = \text{out} \langle f | S | i \rangle_{out} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{S-matrix}$$

$$S = \Lambda(\infty, -\infty) = T \left[\exp \left(i \int_{-\infty}^{\infty} d\tau \int_{\mathbb{R}^3} d^3x \mathcal{L}_I \right) \right] =$$

$$= T \left[\exp \left(i \int d^4x \mathcal{L}_I \right) \right]$$

Časově uspořádaný součin a Wickův teorém

Cílem je konvertovat časově uspořádaný součin polí,
 $T[\phi(x_1), \dots]$ na normální součin, $T[\phi(x_1), \dots] = \text{normal order}$

Příklad:

$$T[\phi(x_1)\phi(x_2)] = \theta(x_0^1 - x_0^2)\phi(x_1)\phi(x_2) + \theta(x_0^2 - x_0^1)\phi(x_2)\phi(x_1)$$

$$\phi(x_1) = \sum_p (\alpha(p)e^{-ipx} + \alpha^\dagger(p)e^{ipx}) = \phi^{(+)}(x) + \phi^{(-)}(x)$$

Předpokládáme, že $x_0^1 > x_0^2$

$$\begin{aligned}\phi(x_1)\phi(x_2) &= (\phi^{(+)}(x_1) + \phi^{(-)}(x_1))(\phi^{(+)}(x_2) + \phi^{(-)}(x_2)) = \\&= \phi^{(+)}(x_1)\phi^{(+)}(x_2) + \phi^{(+)}(x_1)\phi^{(-)}(x_2) + \phi^{(-)}(x_1)\phi^{(+)}(x_2) + \phi^{(-)}(x_1)\phi^{(-)}(x_2) = \\&= \phi^{(+)}(x_1)\phi^{(+)}(x_2) + \phi^{(-)}(x_1)\phi^{(+)}(x_2) + \phi^{(-)}(x_1)\phi^{(-)}(x_2) + \\&+ \phi^{(-)}(x_2)\phi^{(+)}(x_1) + (\phi^{(-)}(x_1)\phi^{(-)}(x_2) - \phi^{(-)}(x_2)\phi^{(+)}(x_1)) = \\&= :\phi(x_1)\phi(x_2): + [\phi^{(+)}(x_1), \phi^{(-)}(x_2)] = \\&= :\phi(x_1)\phi(x_2): + \sum_{p,p'} [\alpha(p)e^{-ipx}, \alpha^\dagger(p')e^{ip'x}] = \\&= :\phi(x_1)\phi(x_2): + \sum_p e^{-ip(x_1-x_2)}\end{aligned}$$

$$\text{pro } x_0^2 > x_0^1: \phi(x_2)\phi(x_1) = :\phi(x_1)\phi(x_2): + \sum_p e^{ip(x_1-x_2)}$$

$$\begin{aligned}\rightarrow T[\phi(x_1)\phi(x_2)] &= :\phi(x_1)\phi(x_2): + \theta(x_0^1 - x_0^2) \sum_p e^{-ip(x_1-x_2)} + \theta(x_0^2 - x_0^1) \sum_p e^{ip(x_1-x_2)} = \\&= :\phi(x_1)\phi(x_2): + i\Delta_F(x_1-x_2)\end{aligned}$$

$$\rightarrow \langle 0 | T [\phi(x_1) \phi(x_2)] | 0 \rangle = i \Delta_F(x_1 - x_2)$$

Vice versa!

$$T[\phi(x_1) \phi(x_2) \phi(x_3)] = :\phi(x_1) \phi(x_2) \phi(x_3): + \phi(x_1) i \Delta_F(x_2 - x_3) + \\ + \phi(x_2) i \Delta_F(x_3 - x_1) + \phi(x_3) i \Delta_F(x_1 - x_2)$$

$$T[\phi(x_1) \dots \phi(x_n)] = :\phi(x_1) \dots \phi(x_n): + i \Delta_F(x_1 - x_2) i \Delta_F(x_3 - x_4) + \\ + i \Delta_F(x_1 - x_3) i \Delta_F(x_2 - x_4) + \dots + \\ + i \Delta_F(x_1 - x_2) i \Delta_F(x_3 - x_4) + i \Delta_F(x_1 - x_3) i \Delta_F(x_2 - x_4) + \\ + i \Delta_F(x_1 - x_4) i \Delta_F(x_2 - x_3)$$

$$\text{«начин»: } \phi(x_1) \dots \phi(x_n) \equiv 12 \dots n$$

$$T[12 \dots n] = :12 \dots n:$$

9. přednáška

Recap: S-matrix

$$S = T \left[\exp \left(i \int_{-\infty}^{\infty} d^4x \mathcal{L}_I(\phi_I, \partial_\mu \phi_I) \right) \right]$$

$$out \langle f | i \rangle_{in} = {}_{in} \langle f | S | i \rangle_{in}$$

↳ Wick's theorem

$$\langle 0 | T \left[\exp \left(-i \int d^4x J(x) \phi(x) \right) \right] | 0 \rangle = \langle 0 | T \left[\exp \left(-i \int d^4x d^4y J(x) \Delta_F(x-y) J(y) \right) \right] | 0 \rangle$$

$$S \leftrightarrow out \langle f | i \rangle_{in} = \langle 0 | T [\phi_H(x_1) \dots \phi_H(x_n)] | 0 \rangle \quad \text{— the Green's function}$$

↳ nice duality
↳ zvládání stavů H

$$unw'we_{in} \langle 0 | T [\phi_{in}(x_1) \dots \phi_{in}(x_n)] | 0 \rangle_{in}$$

↳ zvládání stavů H₀

$$T [\phi_H(x_1) \dots \phi_H(x_n)] = \Lambda^{-1}(t) T [\phi_{in}(x_1) \dots \phi_{in}(x_n) \exp \left(i \int_{-\infty}^t d^4x \mathcal{L}_I(\phi_{in}, \partial_\mu \phi_{in}) \right) \Lambda(-t)]$$

$$\phi_H(x, t) = \Lambda^{-1}(t, -\infty) \phi_{in}(t) \Lambda(t, -\infty)$$

$$|0\rangle \sim |\Omega\rangle$$

$$Q: \langle \Omega | T [\phi_H(x_1) \dots \phi_H(x_n)] | \Omega \rangle =$$

$$= \lim_{t \rightarrow -\infty} \langle \Omega | \Lambda^{-1}(t, t_0) T [\phi_{in}(x_1) \dots \phi_{in}(x_n) \exp \left(i \int_{-\infty}^t d^4x \mathcal{L}_I \right) \Lambda(-t) | \Omega \rangle$$

Poznámka :

$$|\Psi_H\rangle = \lambda(t, -\infty) \Lambda^{-1}(t, -\infty) |\Psi_{in}(t)\rangle, \quad |\lambda| = 1$$

$$\Rightarrow |\Omega\rangle = \lambda(t, -\infty) \Lambda^{-1}(t, -\infty) |0\rangle_{in}$$

10. přednáška

$$\langle \Omega | T[\phi_{in}(x_1) \dots \phi_{in}(x_n)] | \Omega \rangle = \frac{i^n \langle 0 | T[\phi_{in}(x_1) \dots \phi_{in}(x_n) \exp(i \int d^4x \bar{\mathcal{L}}_I(\phi_{in}))] | 0 \rangle_{in}}{i^n \langle 0 | T[\exp(i \int d^4x \bar{\mathcal{L}}_I(\phi_{in}))] | 0 \rangle_{in}} = \langle x_1 \dots x_n \rangle$$

Funkcionální integrál pro skalární pole

Generující funkcionál pro plus' Greenovy funkce

$$Z[J] = Z[0] \sum_{n=0}^{\infty} \frac{(i)^n}{n!} \int_{\mathbb{R}^4} \left(\prod_{i=1}^n d^4x_i \right) J(x_1) \dots J(x_n) \langle x_1 \dots x_n \rangle$$

$$\langle y_1 \dots y_n \rangle = \frac{1}{Z[0]} (-i)^n \frac{\delta^n Z[J]}{\delta J(y_1) \dots \delta J(y_n)} \Big|_{J=0}$$

$$\frac{Z[J]}{Z[0]} = \langle \Omega | T[\exp(i \int d^4x J(x) \phi_{in}(x))] | \Omega \rangle = \oplus$$

$$\otimes = \frac{i^n \langle 0 | T[\exp(i \int d^4x J(x) \phi_{in}(x)) \exp(i \int d^4x \bar{\mathcal{L}}_I(\phi_{in}))] | 0 \rangle_{in}}{i^n \langle 0 | T[\exp(i \int d^4x \bar{\mathcal{L}}_I(\phi_{in}))] | 0 \rangle_{in}}$$

$$\frac{i^n \langle 0 | T[\exp(i \int d^4x (\bar{\mathcal{L}}_I + J\phi))] | 0 \rangle_{in}}{i^n \langle 0 | T[\exp(i \int d^4x \bar{\mathcal{L}}_I)] | 0 \rangle_{in}}$$

$$\text{Výběr } Z[0] = i^n \langle 0 | T[\exp(i \int d^4x \bar{\mathcal{L}}_I)] | 0 \rangle_{in}$$

$$\rightarrow Z[J] = i^n \langle 0 | T[\exp(i \int d^4x (\bar{\mathcal{L}}_I + J\phi))] | 0 \rangle_{in} =$$

$$= \exp(i \int d^4x \bar{\mathcal{L}}_I(-i \frac{\delta}{\delta J(x)})) i^n \langle 0 | T[\exp(i \int d^4x J(x) \phi_{in}(x))] | 0 \rangle_{in} =$$

$$\text{Wickův teorém} : = \exp(i \int d^4x \bar{\mathcal{L}}_I(-i \frac{\delta}{\delta J(x)})) \exp(-\frac{i}{2} \int d^4x d^4y J(x) \Delta_F(x-y) J(y))$$

$$\int \prod_{i=1}^n dc_i \exp\left(\frac{i}{2} c_i A_{ij} c_j\right) \xrightarrow{A_{ij} \text{ symmetric!}} \frac{1}{\prod_{i=1}^n \sqrt{|\lambda_i|}} e^{\frac{i}{2} \sum_{i=1}^n \text{sgn}(\lambda_i)} = \frac{1}{\prod_{i=1}^n \sqrt{\frac{2\pi i}{|\lambda_i|}}} = \left(\det \frac{A}{2\pi i}\right)^{-\frac{1}{2}}$$

$$= |\det\left(\frac{A}{2\pi}\right)|^{-\frac{1}{2}} \exp(i\eta \frac{F}{4})$$

$$\xrightarrow{\sum_{i=1}^n \text{sgn}(\lambda_i)} \text{ (Morse index / Maslov index)}$$

$$\phi \xrightarrow{\sum u_n^2 \text{ basis}} \phi(x) = \sum_n c_n u_n(x) \sim \sum_{j=1}^n c_j u_j(x_i)$$

$$\int d^4x d^4y \phi(x) A(x,y) \phi(y) = \sum_{n,m} c_n A_{nm} c_m$$

$$A_{nm} = \int d^4x d^4y u_n(x) A(x,y) u_m(y)$$

Feynmanova miera

$$\xrightarrow{\det} \begin{pmatrix} u_1(x_1) & u_1(x_2) & \dots & u_1(x_n) \\ u_2(x_1) & & & \\ \vdots & & & \\ u_n(x_1) & \dots & \dots & u_n(x_n) \end{pmatrix}$$

$$\mathcal{D}\phi \equiv [\mathcal{D}\phi] = \lim_{n \rightarrow \infty} \prod_{i=1}^n d\phi(x_i) = \lim_{n \rightarrow \infty} \prod_{i=1}^n dc_i / J =$$

Chiceme:

$$\int \mathcal{D}\phi \exp\left(\frac{i}{2} \int d^4x d^4y \phi(x) A(x,y) \phi(y)\right) = \lim_{n \rightarrow \infty} \int \prod_{i=1}^n dc_i \exp\left(\frac{i}{2} \sum_{n,m} c_n A_{nm} c_m\right) / J_n =$$

$$= c |\det A|^{-\frac{1}{2}} = c |\det(A)|^{-\frac{1}{2}}$$

$$c |\det(\Delta(x-y))|^{-\frac{1}{2}} \exp\left(-\frac{i}{2} \int d^4x d^4y J(x) \Delta_F(x,y) J(y)\right)$$

12. přednáška

Poučková

$$Z[J] \rightarrow \langle x_1 \dots x_n \rangle = \frac{(-i)^n \delta^n Z[J]}{\delta J(x_1) \dots \delta J(x_n)} \Big|_{J=0}$$

$$\tilde{Z}[J] = \frac{Z[J]}{Z[0]}, \quad \mathcal{L}_I(\phi) = -\frac{1}{4!} \phi^4$$

$$\tilde{Z}[J] = \exp(i \int d^4x \mathcal{L}_I(i \frac{\delta}{\delta J(x)})) \exp(-\frac{i}{2} \int d^4x d^4y J(x) \Delta_F(x-y) J(y))$$

- // - $J=0$

$$\rightarrow \tilde{Z}[J]^{(1)} = [1 - \frac{i}{4!} \lambda \int d^4x (-i \frac{\delta}{\delta J(x)})^4 + O(\lambda^2)] \exp(-\frac{i}{2} \int J \Delta_F J)$$

$$\cdot (-i \frac{\delta}{\delta J(x)}) \exp(-\frac{i}{2} \int J \Delta_F J) = (- \int d^4x \Delta_F(x-z) J(x)) \exp(-\frac{i}{2} \int J \Delta_F J)$$

$$\cdot (-i \frac{\delta}{\delta J(x)})^2 \exp(-\frac{i}{2} \int J \Delta_F J) = (-i \frac{\delta}{\delta J(x)}) [(- \int d^4x \Delta_F(x-z) J(x)) \exp(-\frac{i}{2} \int J \Delta_F J)] =$$

$$-i \Delta_F(z-z) \exp(-\frac{i}{2} \int J \Delta_F J) + (- \int d^4x \Delta_F(x-z) J(x))^2 \exp(-\frac{i}{2} \int J \Delta_F J)$$

$$\cdot (-i \frac{\delta}{\delta J(x)})^3 (-i \frac{\delta}{\delta J(x)}) [i \Delta_F(0) + (- \int d^4x \Delta_F(x-z) J(x))] \exp(-\frac{i}{2} \int J \Delta_F J) =$$

$$= [-2i \Delta_F(0) (- \int d^4x \Delta_F(x-z) J(x))] \exp(-\frac{i}{2} \int J \Delta_F J) +$$

$$+ [(-i \Delta_F(0) + (- \int d^4x \Delta_F(x-z) J(x))^2] (- \int d^4x \Delta_F(x-z) J(x)) \exp(-\frac{i}{2} \int J \Delta_F J)$$

$$\cdot (-i \frac{\delta}{\delta J(x)})^4 (-i \frac{\delta}{\delta J(x)}) [-3i \Delta_F(0) (- \int d^4x \Delta_F(x-z) J(x)) - (- \int d^4x \Delta_F(x-z) J(x))^3] \exp(-\frac{i}{2} \int J \Delta_F J) =$$

$$= [-3 (\Delta_F(0))^2 + 6i \Delta_F(0) (- \int d^4x \Delta_F(x-z) J(x))^2 + (- \int d^4x \Delta_F(x-z) J(x))^4] \exp(-\frac{i}{2} \int J \Delta_F J)$$

$$i\Delta_F(x-y) \longleftrightarrow \text{diagram: line from } x \text{ to } y, \quad i\Delta_F(z-z) = \Delta_F(0) \longleftrightarrow \text{diagram: circle with a dot at } z$$

$$\int d^4x \Delta_F(x-z) J(x) \longleftrightarrow \text{diagram: line from } x \text{ to } z \text{ with an arrow pointing to } x$$

$$\rightarrow \exp\left(-i \frac{1}{4!} \int d^4x \left(-i \frac{\delta}{\delta J(x)}\right)^4\right) \exp\left(-\frac{i}{2} \int J \Delta_F J\right) \cdot \mathcal{O}(1^2) (*)$$

$$(*) = \left[1 - \frac{i^4}{4!} \int d^4z \left(-3 \text{diagram: circle with a dot} + 6i \times \text{diagram: line from } z \text{ to } x \text{ with a dot at } z + \text{diagram: line from } x \text{ to } z \text{ with a dot at } x\right) dz\right] \exp\left(-\frac{i}{2} \int J \Delta_F J\right)$$

$$\Rightarrow Z[0] = \left[1 - \frac{i^4}{4!} \int d^4z (-3 \text{diagram: circle with a dot})\right]$$

$$\rightarrow \tilde{Z}[J]^{(1)} = \frac{\left[1 - \frac{i^4}{4!} \int d^4z \left(-3 \text{diagram: circle with a dot} + 6i \times \text{diagram: line from } z \text{ to } x \text{ with a dot at } z + \text{diagram: line from } x \text{ to } z \text{ with a dot at } x\right) dz\right] \exp\left(-\frac{i}{2} \int J \Delta_F J\right)}{\left[1 - \frac{i^4}{4!} \int d^4z (-3 \text{diagram: circle with a dot})\right]} \sim$$

$$\frac{1}{1-x} \sim 1+x \sim \left[1 - \frac{i^4}{4!} \int d^4z \left(6i \times \text{diagram: line from } z \text{ to } x \text{ with a dot at } z + \text{diagram: line from } x \text{ to } z \text{ with a dot at } x\right) dz\right] \exp\left(-\frac{i}{2} \int J \Delta_F J\right)$$

Teoria ϕ^3 :

$$\mathcal{L}_I = -\frac{g}{3!} \phi^3$$

$$Z[J] = \exp\left(-i \frac{g}{3!} \int d^4x \left(-i \frac{\delta}{\delta J(x)}\right)^3\right) \exp\left(-\frac{i}{2} \int J \Delta_F J\right)$$

$$= \left[1 - \frac{i g}{3!} \int d^4x \left(-i \frac{\delta}{\delta J(x)}\right)^3 - \frac{g^2}{3!2} \left[\int d^4x \left(-i \frac{\delta}{\delta J(x)}\right)^3\right]^2 + \mathcal{O}(g^3)\right] \exp\left(-\frac{i}{2} \int J \Delta_F J\right)$$

$$x \cdot \left(-i \frac{\delta}{\delta J(x)}\right)^3 \exp\left(-\frac{i}{2} \int J \Delta_F J\right) = \left[-3i \times \text{diagram: line from } x \text{ to } z \text{ with a dot at } z - \text{diagram: line from } z \text{ to } x \text{ with a dot at } x\right] \exp\left(-\frac{i}{2} \int J \Delta_F J\right)$$

$$\left(-i \frac{\delta}{\delta J(x)}\right)^3 \left(-i \frac{\delta}{\delta J(z)}\right)^3 \exp\left(-\frac{i}{2} \int J \Delta_F J\right) = \left[-6i \times \text{diagram: circle with a dot} - 9i \times \text{diagram: line from } z \text{ to } x \text{ with a dot at } z - \text{diagram: line from } x \text{ to } z \text{ with a dot at } x - \right.$$

$$\left. - 9 \times \text{diagram: line from } x \text{ to } z \text{ with a dot at } z - \text{diagram: line from } z \text{ to } x \text{ with a dot at } x - 9 \times \text{diagram: circle with a dot} + 3i \times \text{diagram: line from } x \text{ to } z \text{ with a dot at } z - \text{diagram: line from } z \text{ to } x \text{ with a dot at } x + 3i \times \text{diagram: line from } x \text{ to } z \text{ with a dot at } z - \right.$$

$$\left. + 3i \times \text{diagram: line from } x \text{ to } z \text{ with a dot at } z - \text{diagram: line from } z \text{ to } x \text{ with a dot at } x + \text{diagram: line from } x \text{ to } z \text{ with a dot at } z - \text{diagram: line from } z \text{ to } x \text{ with a dot at } x\right] \exp\left(-\frac{i}{2} \int J \Delta_F J\right)$$

$$Z[0]^{(2)} = \left[1 - \frac{g^2}{3!2} \int d^4x d^4z (-6i \text{ } \bigcirc_z - 9i \text{ } \bigcirc_x) \right]$$

$$\rightarrow \tilde{Z}[J]^{(2)} = \left(\frac{Z[J]}{Z[0]} \right)^{(2)}$$

Eulerova formula pro planární grafy:

$$L = E - V + 1$$

loop edge vertex

13. přednáška

$$\int x \frac{Q}{z} x d^2 z \sim \int d^2 z \int d^4 x_1 d^4 x_2 J(x_1) \Delta_F(x_1 - z) \Delta_F(0) \Delta_F(z - x_2) J(x_2)$$

C. S. Coleman (70's)

$$\begin{aligned} & \exp(-i \int d^4 x \mathcal{L}(-i \frac{\delta}{\delta J(x)})) \exp(-\frac{i}{2} \int d^4 x_1 d^4 x_2 J(x_1) \Delta_F(x_1 - x_2) J(x_2)) = \\ & = \exp(\frac{i}{2} \int d^4 x_1 d^4 x_2 \frac{\delta}{\delta \phi(x_1)} \Delta(x_1 - x_2) \frac{\delta}{\delta \phi(x_2)}) \exp(i \int d^4 x (-\mathcal{L}_I(\phi) + J(x) \phi(x))) \Big|_{\phi=0} \end{aligned}$$

Obecně:

$$F(\frac{\partial}{\partial b}) G(b) = G(\frac{\partial}{\partial x}) F(x) e^{x \cdot b} \Big|_{x=0}$$

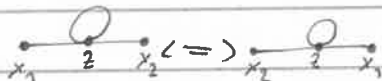
14. püdnoska

$$\langle x_1 \dots x_n \rangle = (-1)^n \frac{\delta^n \tilde{Z}[J]}{\delta J(x_1) \dots \delta J(x_n)} \Big|_{J=0}$$

$$\tilde{Z}[J] = \left[1 - \frac{i}{4!} \int d^4z (6i x \cdot \frac{\partial}{\partial z} + X^z) + O(\lambda^2) \right] \exp(-\frac{i}{2} \int x \Delta_F(x-y) J_y)$$

$$\begin{aligned} a) & (-1)^4 \frac{\delta^4}{\delta J(x_1) \dots \delta J(x_4)} \left(\frac{-i}{8} \right) \int d^4z \int d^4y_1 \int d^4y_2 \Delta_F(y_1, z) \Delta_F(0) \Delta_F(z, y_2) J_{y_1} J_{y_2} \int d^4z_1 d^4z_2 J(z_1) \Delta_F(z_1, z_2) J(z_2) = \\ & = \left(\frac{-i}{8} \right) \int d^4y_1 d^4y_2 d^4z_1 d^4z_2 \Delta_F(y_1, z) \Delta_F(0) \Delta_F(z, y_2) \Delta_F(z_1, z_2) \frac{\delta^4 J(y_1) J(y_2) J(z_1) J(z_2)}{\delta J(x_1) \delta J(x_2) \delta J(x_3) \delta J(x_4)} \end{aligned}$$

$$\rightarrow \left(\frac{-i}{8} \right) \int d^4z \Delta_F(x_1, z) \Delta_F(0) \Delta_F(z, x_2) \Delta_F(x_3, x_4)$$



$$a) \left(\frac{-i}{8} \right) \int d^4z \left(\frac{\partial}{\partial z} \right) \int d^4z_1 d^4z_2 J(z_1) \Delta_F(z_1, z_2) J(z_2) =$$

$$= \left(\frac{-i}{8} \right) 4 \int d^4z \left(\frac{\partial}{\partial z} \right) \left(\frac{0}{0} + \frac{0}{0} + |p+q| + \cancel{p} + \cancel{q} \right)$$

$$b) \left(\frac{-i}{8} \right) \int d^4z X \exp(-\frac{i}{2} \int J \Delta J) \rightarrow \frac{\delta^4}{\delta J(x_1) \dots \delta J(x_4)} \int d^4z X \cdot 1 =$$

$$= \left(\frac{-i}{8} \right) \int d^4z_1 d^4z_2 d^4z_3 d^4z_4 \Delta_F(z_1, z_2) \Delta_F(z_2, z_3) \Delta_F(z_3, z_4) \Delta_F(z_4, z_1) \frac{\delta^4 J(z_1) \dots J(z_4)}{\delta J(x_1) \dots \delta J(x_4)} =$$

$$= \left(\frac{-i}{4!} \right) 24 \int d^4z X$$

$$\langle x_1 \dots x_n \rangle^{(n)} = \left(= +11 + \cancel{x} \right) \cdot \frac{i!}{2 \cdot 4!} 4 \cdot 3 \int d^4 x \left(\frac{0}{2} + \frac{0}{2} + |p+q| + \cancel{x}^q + \cancel{x} \right) -$$

$$- \frac{i!}{2 \cdot 4!} 24 \int d^4 x \cancel{x}$$

$$\langle x_1 \dots x_n \rangle = \frac{\int \mathcal{D}\varphi \varphi(x_1) \dots \varphi(x_n) \exp(i \int d^4 x (\mathcal{L}_0 - V))}{\int \mathcal{D}\varphi \exp(i \int d^4 x (\mathcal{L}_0 - V))}$$

$$= \frac{\int \mathcal{D}\varphi \varphi(x_1) \dots \varphi(x_n) \exp(-i \int d^4 x V) \exp(i S_0[\varphi])}{\int \mathcal{D}\varphi \exp(i S_0[\varphi])} \frac{\int \mathcal{D}\varphi \exp(i S_0[\varphi])}{\int \mathcal{D}\varphi \exp(i \int d^4 x (\mathcal{L}_0 - V))} =$$

$$= \frac{\langle \varphi(x_1) \dots \varphi(x_n) \exp(-i \int d^4 x V) \rangle_0}{\langle \exp(-i \int d^4 x V) \rangle_0} \stackrel{V \sim \phi^4(O(x^2))}{=} \frac{\langle \varphi(x_1) \dots \varphi(x_n) (1 - \frac{i!}{4!} \int d^4 x \varphi^4(x)) \rangle_0}{\langle 1 - \frac{i!}{4!} \int d^4 x \varphi^4(x) \rangle_0} =$$

Cell-Man

$$\stackrel{\downarrow}{=} \frac{\langle 0 | T [\varphi(x_1) \dots \varphi(x_n) (1 - \frac{i!}{4!} \int d^4 x \varphi^4(x))] | 0 \rangle}{\langle 0 | T [1 - \frac{i!}{4!} \int d^4 x \varphi^4(x)] | 0 \rangle}$$

$$(\text{Wick's thm}) \cdot \int d^4 x \langle 0 | T [\underbrace{\varphi(x_1) \dots \varphi(x_n)}_{\Lambda = 2M} \underbrace{\varphi(x) \dots \varphi(x)}_4] | 0 \rangle$$

$$\rightarrow \text{počet odlišných kontraktů: } \frac{(2M)!}{2^{MM} M!} = \dots 105$$

16. přednáška

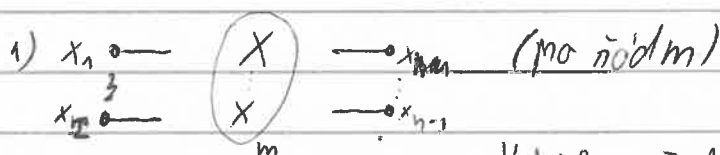
$$\langle x_1 \dots x_n \rangle = \frac{\int \mathcal{D}\phi \phi(x_1) \dots \phi(x_n) \exp(iS[\phi])}{\int \mathcal{D}\phi \exp(iS[\phi])} =$$

$$\frac{\langle \phi(x_1) \dots \phi(x_n) \exp(-iV[\phi]) \rangle_0}{\langle \exp(-iV[\phi]) \rangle_0}$$

→ Feynmanova pravidla (pozicií prvků) pro n -bodovou Greenovu funkci

$$V = \frac{\lambda \phi^4}{4!}$$

$$\rightarrow \langle \phi(x_1) \dots \phi(x_n) (1 - \frac{i\lambda}{4!} \int d^4z \phi^4(z) + \frac{(i\lambda)^2}{4!2!} \int d^4z_1 \int d^4z_2 \phi^4(z_1) \phi^4(z_2) + O(\lambda^3)) \rangle$$



Vytvořte všechny možné topologicky odlišné diagramy. Valuace diagramů neuvádějte

- 2) Každá čára v diagramu přináší faktor $\int d^4x$
- 3) Každému vnořené přináší multiplikativní faktor $-i$
- 4) Každý vnořené integruje přes $\int d^4z$
- 5) Každému diagramu přináší „symmetry“ faktor

$$\frac{n!}{(n!)^m m!} = \frac{1}{m!} \text{ symmetry faktor}$$

než menším

18. přednáška

Grossmanovské proměnné

$$\int d\theta_i = 0, \int d\theta_i \theta_j = 0, \int d\theta_i \theta_i = 1 \quad (*)$$

$$\theta_i \theta_j + \theta_j \theta_i = 0 \rightarrow \theta_i^2 = 0$$

$$f(x, \theta) = p_0(x) + p_i(x) \theta_i + p_{ij}(x) \theta_i \theta_j + \dots + p_{i_1, \dots, i_n}(x) \theta_{i_1} \dots \theta_{i_n}$$

delta funkce: $\mathcal{I}(\theta) := \theta$

Transformace Grossmanovských proměnných:

$$\hat{\theta}_i := a_{ij} \theta_j$$

$$\int d\hat{\theta}_n \dots d\hat{\theta}_1 f(x, \hat{\theta}) = \int d\theta_n \dots d\theta_1 f(x, \hat{\theta}(\theta)) \quad (?) = \oplus$$

|| ← žádný další člen rangu do integrace nepřispívá ()*

$$\int d\hat{\theta}_n \dots d\hat{\theta}_1 p_{i_1, \dots, i_n} \hat{\theta}_{i_1} \dots \hat{\theta}_{i_n} = \epsilon_{i_1, \dots, i_n} p_{i_1, \dots, i_n}(x) \underbrace{\int d\hat{\theta}_n \dots d\hat{\theta}_1 \hat{\theta}_{i_1} \dots \hat{\theta}_{i_n}}_{1} = n! p_{i_1, \dots, i_n}$$

$$\oplus = (?) \int d\theta_n \dots d\theta_1 \underbrace{p_{i_1, \dots, i_n}(x) \hat{\theta}_{i_1} \dots \hat{\theta}_{i_n}}_{n! p_{i_1, \dots, i_n} \hat{\theta}_{i_1} \dots \hat{\theta}_{i_n}} = (?) \int d\theta_n \dots d\theta_1 n! p_{i_1, \dots, i_n}(x) a_{i_1 j_1} \dots a_{i_n j_n} \theta_{j_1} \dots \theta_{j_n}$$

$$\stackrel{(2)}{=} n! p_{i_1, \dots, i_n} \epsilon_{i_1, \dots, i_n} a_{i_1 j_1} \dots a_{i_n j_n} \underbrace{\int d\theta_n \dots d\theta_1 \theta_{j_1} \dots \theta_{j_n}}_{1} = (?) n! p_{i_1, \dots, i_n} \det a$$

$$\rightarrow (?) = (\det a)^{-1}$$

$$\rightarrow \int d\hat{\theta}_n \dots d\hat{\theta}_1 f(x, \hat{\theta}) = \int d\theta_n \dots d\theta_1 f(x, \hat{\theta}(\theta)) \frac{1}{\det a}, \quad \hat{\theta}_i = a_{ij} \theta_j$$

$$\int d\theta_1 d\theta_2 \exp(\frac{1}{2} \theta_1 a_{12} \theta_2 + \frac{1}{2} \theta_2 a_{21} \theta_1) = \int d\theta_1 d\theta_2 \exp(\theta_1 a_{12} \theta_2) = \oplus$$

$$\exp(\theta_1 a_{12} \theta_2) = 1 + \theta_1 a_{12} \theta_2 \leftarrow \text{antisymetrické}$$

$$\oplus = a_{12} \int d\theta_1 d\theta_2 \theta_1 \theta_2 = a_{12} = \sqrt{\det a} =: Pf(a) \quad (\text{Pfaffian})$$

$$a = \begin{pmatrix} 0 & a_{12} \\ -a_{12} & 0 \end{pmatrix} \Rightarrow \det a = a_{12}^2$$

Poznámka:

$$A \in \mathbb{R}^{2n, 2n} \text{ antisymetrická} \rightarrow \exists O \in SO(2n) : O A O^T = \tilde{A}_J$$

$$\begin{matrix} \text{dvoje } \mathbb{R}^+ \\ a_1, b_1, \dots \in \mathbb{R}^+ \end{matrix} \quad \begin{pmatrix} a_1 \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \\ b_2 \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \\ \vdots \end{pmatrix}$$

standardní form
Jacobiho bloky diagonální form

$$\text{Transformace } T = \begin{pmatrix} \pm a^{-\frac{1}{2}} & & 0 \\ & \pm a^{-\frac{1}{2}} & \\ 0 & & \pm b^{\frac{1}{2}} \\ & & \pm b^{\frac{1}{2}} \\ & & \ddots \end{pmatrix}$$

$$\Rightarrow T O A O^T = \begin{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} & & \\ & \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} & \\ & & \ddots \\ & & & \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \end{pmatrix} = \tilde{A}_J$$

$$\int d\theta_1 \dots d\theta_{2n} \exp(\frac{1}{2} \theta^T A \theta) = \int d\hat{\theta}_1 \dots d\hat{\theta}_{2n} \exp(\frac{1}{2} \hat{\theta}^T O^T T^{-1} \tilde{A}_J T^{-1} O \hat{\theta}) =$$

$$= \int d\hat{\theta}_1 \dots d\hat{\theta}_{2n} \exp(\frac{1}{2} \hat{\theta}^T \tilde{A}_J \hat{\theta}) =$$

$$= \int d\hat{\theta}_1 \dots d\hat{\theta}_{2n} \det(T^{-1} O) \exp(\frac{1}{2} \hat{\theta}^T \tilde{A}_J \hat{\theta}) =$$

$$= \det(T^{-1} O) \int d\hat{\theta}_1 \dots d\hat{\theta}_{2n} \exp(\frac{1}{2} \hat{\theta}^T \tilde{A}_J \hat{\theta}) =$$

$$= \det(T^{-1} O) \int d\hat{\theta}_1 \dots d\hat{\theta}_{2n} \exp(\hat{\theta}_1 \hat{\theta}_2 + \hat{\theta}_3 \hat{\theta}_4 + \dots + \hat{\theta}_{2n-1} \hat{\theta}_{2n}) = \oplus$$

$$\# = \det(T^{-1}) \int d\theta_1 \dots d\theta_n \exp(\theta_1 \theta_2) \exp(\theta_3 \theta_4) \dots \exp(\theta_{2n-1} \theta_{2n}) =$$

$$= \det T^{-1} = \sqrt{\det A} = Pf(A)$$

"Kompleifikation" Grassmannvariablen

$$\theta_i \mapsto \theta_i^*, (\theta_i^*)^* = \theta_i$$

$$\int d\theta_{2n} \dots d\theta_1 \exp(\theta^T A \theta + \eta^T \theta) \quad , \quad \boxed{\int d\theta_i \eta_i = 0} \quad , \quad \boxed{\int d\theta f(\theta) = \int d\theta f(\theta + \alpha)}$$

$$= \int d\theta_{2n} \dots d\theta_1 \exp\left[\frac{i}{2} (\theta_i - A_{ij}^{-1} \eta_j) A_{ik} (\theta_k - A_{ke}^{-1} \eta_e) + \frac{i}{2} \eta^T A^{-1} \eta\right] =$$

$$= \exp\left(\frac{i}{2} \eta^T A^{-1} \eta\right) \int d\theta_{2n} \dots d\theta_1 \exp\left(\frac{i}{2} \theta^T A \theta\right) = \sqrt{\det A} \exp\left(\frac{i}{2} \eta^T A^{-1} \eta\right)$$

$$\int d\theta d\theta^* \exp(\theta^* A \theta + \eta^* \theta + \theta^* \eta) = \det A \exp(-\eta^* A^{-1} \eta)$$

Funkcionalni integral (Grossmanovski 'po me'imo')

$$\theta_i \mapsto \phi_B(x)$$

$\hookrightarrow 1, \dots, 4$

$$\theta_i^* \mapsto \phi_A(x)$$

Generijski funkcional:

$$Z[\eta, \bar{\eta}] = N \int \mathcal{D}\phi \mathcal{D}\bar{\phi} \exp(i \int d^4x [\mathcal{L}_0(\phi, \bar{\phi}) + \bar{\eta}\phi + \bar{\phi}\eta])$$

$$\downarrow \quad \text{to } \gamma^\mu \partial_\mu$$
$$\mathcal{L}_0 = \bar{\phi}(i \not{\partial} - m)\phi$$

$$\mathcal{D}\phi \mathcal{D}\bar{\phi} := \lim_{h \rightarrow \infty} \prod_{a=1}^h \prod_{i=1}^h d\phi_a(x_i) d\bar{\phi}_a(x_i)$$

19. püdnos'ka

$$Z_0[\eta, \bar{\eta}] = N \int \mathcal{D}\phi \mathcal{D}\bar{\phi} \exp(iS_0[\phi, \bar{\phi}] + i \int d^4x \bar{\eta}(x) \phi + i \int d^4x \phi \bar{\eta})$$

$$= \tilde{N} \det(i\partial - m) \exp(-i \int d^4x d^4y \bar{\eta}(x) A^{-1}(x, y) \eta(y)) \quad \text{--- ④}$$

$$S_0[\phi, \bar{\phi}] = \int d^4x \bar{\phi}(i\partial - m)\phi = \int d^4x d^4y \bar{\phi}(x) \underbrace{\mathcal{D}(x, y)}_{A(x, y)} (i\partial - m) \phi(y)$$

Pozna'mka:

$$(i\partial - m)_y S_F(y, z) = \mathcal{D}(y - z)$$

$$\rightarrow \int d^4x \underbrace{\mathcal{D}(x, y)}_{A(x, y)} (i\partial - m)_y \underbrace{S_F(y, z)}_{A^{-1}(y, z)} = \mathcal{D}(y - z)$$

$$\text{④} = Z_0[0, 0] \exp(-i \int d^4x d^4y \bar{\eta}(x) S_F(x, y) \eta(y)) \quad \text{--- ④}$$

$$\frac{\delta^2}{\delta \bar{\eta} \delta \eta} \frac{Z_0[\eta, \bar{\eta}]}{Z_0[0, 0]} \bigg|_{\tilde{Z}_0[\eta, \bar{\eta}]} = i S_F(x, y)$$

$$\tilde{Z}_0[\eta, \bar{\eta}] \bigg|_{\eta, \bar{\eta} = 0}$$

Pozna'mka:

$$S_F(x, y) = - S_F(y, x)$$

Wick's theorem pro Diracovskí pole

Zavedeme zkratky $\eta, \bar{\eta}$ a pole' operátory $\hat{\phi}, \hat{\bar{\phi}}$

$$\text{Předpokládáme: } \{\eta, \bar{\eta}\} = \{\eta, \hat{\phi}\} = \{\bar{\eta}, \hat{\phi}\} = \{\eta, \hat{\bar{\phi}}\} = \{\bar{\eta}, \hat{\bar{\phi}}\} = 0$$

$$\begin{aligned} 1) [\eta_x \hat{\phi}_x, \hat{\bar{\phi}}_y \eta_y] &= \hat{\bar{\phi}}_y [\eta_x \hat{\phi}_x, \eta_y] + [\eta_x \hat{\phi}_x, \hat{\bar{\phi}}_y] \eta_y \\ &= \hat{\bar{\phi}}_y \eta_x \underbrace{\{\phi_x, \eta_y\}}_0 - \hat{\bar{\phi}}_y \underbrace{\{\bar{\eta}_x, \eta_y\}}_0 \hat{\phi}_x + \underbrace{\eta_x \{\hat{\phi}_x, \hat{\bar{\phi}}_y\}}_{\text{C (číslo)}} \eta_y - \underbrace{\{\eta_x, \hat{\bar{\phi}}_y\} \hat{\phi}_x \eta_y}_0 \end{aligned}$$

$$2) \mathcal{L}_J(x) = \bar{\eta}(x) \hat{\phi}(x) + \hat{\bar{\phi}}(x) \eta(x)$$

$$\begin{aligned} [\mathcal{L}_J(x), \mathcal{L}_J(y)] &= [\bar{\eta}(x) \hat{\phi}(x), \bar{\eta}(y) \hat{\phi}(y)] + [\bar{\eta}(x) \hat{\phi}(x), \hat{\bar{\phi}}(y) \eta(y)] + \\ &\quad + [\hat{\bar{\phi}}(x) \eta(x), \bar{\eta}(y) \hat{\phi}(y)] + [\hat{\bar{\phi}}(x) \eta(x), \hat{\bar{\phi}}(y) \eta(y)] = \\ &= \dots = 0 \quad (\text{číslo}) \end{aligned}$$

$$[[\mathcal{L}_J(x), \mathcal{L}_J(y)], \mathcal{L}_J(z)] = 0$$

Poznámka:

$$\text{Pro bosony: } \mathcal{L}_J(x) = J(x) \phi(x) + J(x) \phi^+(x)$$

Transformace:

$$\begin{aligned} &\prod_{i=1}^m \left(\frac{-i \mathcal{J}}{\mathcal{J} \eta(x_i)} \right) \prod_{j=1}^m \left(i \frac{\mathcal{J}}{\mathcal{J} \bar{\eta}(y_j)} \right) \langle 0 | T [\exp(i \int d^4x (\bar{\eta} \hat{\phi} + \hat{\bar{\phi}} \eta))] | 0 \rangle \Big|_{\eta = \bar{\eta} = 0} = \\ &= \langle 0 | T [\hat{\phi}(x_1) \dots \hat{\phi}(x_m) \hat{\bar{\phi}}(y_1) \dots \hat{\bar{\phi}}(y_m)] | 0 \rangle \end{aligned}$$

20. prednáška

Skalárny + Fermionový pole

$$\mathcal{L} = \bar{\psi}(i\partial + M)\psi + \frac{1}{2}(\partial_\mu \phi)^2 - \frac{1}{2}m^2\phi^2 + \mathcal{L}_I(\phi, \psi, \bar{\psi})$$

Yukawin potenciál

$$\mathcal{L}_{Y,I} = -g \bar{\psi}\psi\phi = -g \bar{\psi}\phi\psi \quad (\text{preto } \phi \text{ je reálna číslo})$$

$$\mathcal{L}_{Y,I} = -g \bar{\psi}\gamma^5\psi\phi \quad (\text{preto } \phi \text{ je reálna číslo})$$

$$Z[\eta, \bar{\eta}, J] = \exp(i \int d^4x \mathcal{L}_I(-i \frac{\delta}{\delta \eta(x)}, i \frac{\delta}{\delta \bar{\eta}(x)}, i \frac{\delta}{\delta J(x)}).$$

$$= \exp(i \int d^4x [\bar{\psi}(x) \eta(x) + \bar{\eta}(x) \psi(x) + \phi(x) J(x)] / 0) =$$

$$= \exp(i \int d^4x \mathcal{L}_I(-i \frac{\delta}{\delta \eta(x)}, i \frac{\delta}{\delta \bar{\eta}(x)}, i \frac{\delta}{\delta J(x)})). \quad \textcircled{+}$$

$$= N \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \exp(i S_0[\psi, \bar{\psi}] + i \int d^4x \bar{\eta}(x) \psi(x) + i \int d^4x \bar{\psi}(x) \eta(x)).$$

$$= N \int \mathcal{D}\phi \exp(i S_0[\phi] + i \int d^4x J(x) \phi(x)) =$$

$$= \textcircled{+} \cdot N \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\phi \exp(i S[\psi, \bar{\psi}, \phi] + i \int d^4x \bar{\eta}(x) \psi(x) + i \int d^4x \bar{\psi}(x) \eta(x) + i \int d^4x J(x) \phi(x))$$

$$S[\psi, \bar{\psi}, \phi] = \int d^4x [\bar{\psi}(i\partial + M)\psi + \frac{1}{2}(\partial_\mu \phi)^2 - \frac{1}{2}m^2\phi^2 - g \phi \bar{\psi}\psi]$$

Generující funkcionál Greenových funkcí:

$$\begin{aligned}\tilde{Z}[\eta, \bar{\eta}, J] &= \frac{Z[\bar{\eta}, \eta, J]}{Z[0, 0, 0]} = \\ &= \frac{\int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\phi \exp(iS[\psi, \bar{\psi}, \phi] + i\int d^4x \bar{\eta} \psi + i\int d^4x \bar{\psi} \eta + i\int d^4x J\phi)}{\int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\phi \exp(iS[\psi, \bar{\psi}, \phi])}\end{aligned}$$

$$\begin{aligned}\langle \Omega | T[\Phi_1(x_1) \dots \Phi_n(x_n) \Psi(y_1) \dots \Psi(y_m) \bar{\Psi}(z_1) \dots \bar{\Psi}(z_m)] | \Omega \rangle &= \\ &= \frac{\prod_{i=1}^n (-i \frac{\delta}{\delta \Phi_i}) \prod_{j=1}^m (-i \frac{\delta}{\delta \bar{\Psi}_j}) \prod_{l=1}^m (i \frac{\delta}{\delta \Psi_l}) \tilde{Z}[\eta, \bar{\eta}, J]}{\tilde{Z}[\eta, \bar{\eta}, J]_{\eta, \bar{\eta}, J=0}} = \\ &= \frac{\int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\phi \phi(x_1) \dots \phi(x_n) \Psi(y_1) \dots \Psi(y_m) \bar{\Psi}(z_1) \dots \bar{\Psi}(z_m) \exp(iS[\psi, \bar{\psi}, \phi])}{\int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\phi \exp(iS[\psi, \bar{\psi}, \phi])}\end{aligned}$$

21. přednáška

Powellov' počít v p-prostorech

$$\mathcal{T}(x_1, \dots, x_n) = \langle \Omega | T[\phi_H(x_1) \dots \phi_H(x_n)] | \Omega \rangle$$

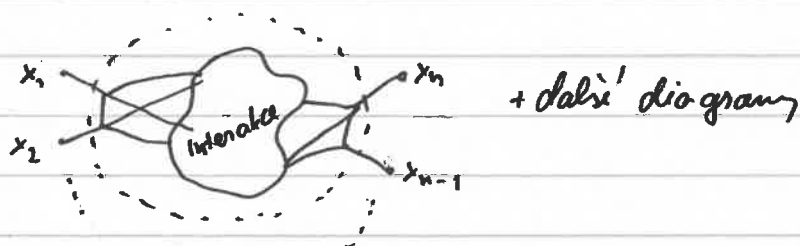
$$\mathcal{T}(p_1, \dots, p_n) = \int d^4x_1 \dots d^4x_n \exp(-ip_1x_1) \dots \exp(ip_nx_n) \mathcal{T}(x_1, \dots, x_n)$$

Feynmanova pravidla

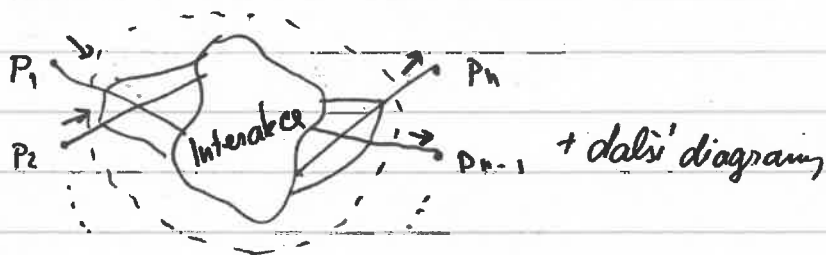
$$x_1 \xrightarrow{\quad} x_2 \sim i\Delta_F(x_1 - x_2) = -i \int \frac{d^4q}{(2\pi)^4} \frac{\exp(-iq(x_1 - x_2))}{q^2 - m^2 + i\epsilon}$$

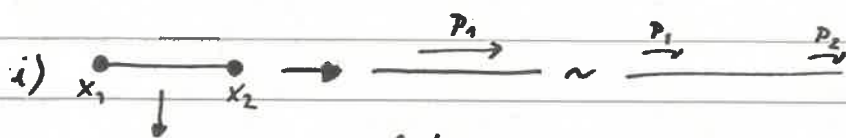
$$\text{X}^* \sim -i\lambda \int d^4x$$

x-prostor:



p-prostor:

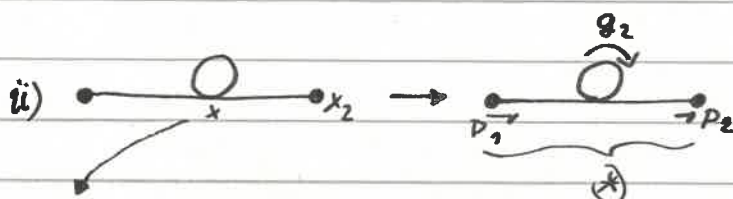


i) 

$$i\Delta_F(x_1-x_2) \rightarrow \int d^4x_1 d^4x_2 \exp(-ip_1x_1) \exp(ip_2x_2) \int \frac{d^4q}{(2\pi)^4} \frac{\exp(-iq(x_1-x_2))}{q^2-m^2+i\epsilon}$$

$$= \int \frac{d^4x_1 d^4x_2 d^4q}{(2\pi)^4} \exp(-ix_1(p_1+q)) \exp(ix_2(p_2+q)) \frac{1}{q^2-m^2+i\epsilon} =$$

$$= (2\pi)^4 \delta(p_2-p_1) \frac{i}{p_1^2-m^2+i\epsilon}$$

ii) 

vertex $\rightarrow -i\lambda$

linka $\rightarrow$ propagator $i\Delta_F(x-y)$

$$i\mathcal{J} = -i\lambda \int d^4x i\Delta_F(x-x) i\Delta_F(x_1-x) i\Delta_F(x-x_2)$$

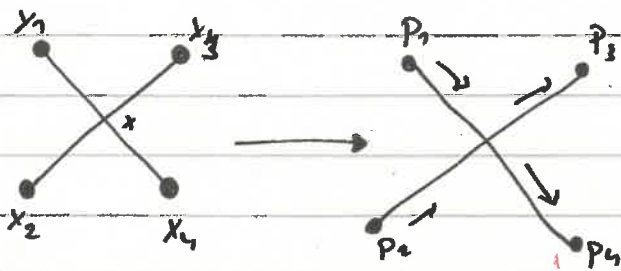
$$\textcircled{+} \sim -i\lambda \int d^4x_1 d^4x_2 \exp(-ip_1x_1) \exp(ip_2x_2) \int d^4x \int \frac{d^4q_1}{(2\pi)^4} \frac{\exp(iq_1(x_1-x_2))}{q_1^2-m^2+i\epsilon}$$

$$\cdot \int \frac{d^4q_2}{(2\pi)^4} \frac{i \exp(iq_2(x_1-x_2))}{q_2^2-m^2+i\epsilon} \cdot \int \frac{d^4q_3}{(2\pi)^4} \frac{i}{q_3^2-m^2+i\epsilon}$$

$$= -i\lambda \int d^4x_1 d^4x_2 d^4x \frac{d^4q_1}{(2\pi)^4} \frac{d^4q_2}{(2\pi)^4} \frac{d^4q_3}{(2\pi)^4} \exp(ix_1(p_1+q_1)) \exp(ix_2(p_2+q_2)) \exp(ix(q_1-q_2))$$

$$\cdot \prod_{i=1}^3 \frac{1}{q_i^2-m^2+i\epsilon} =$$

$$= -i\lambda (2\pi)^4 \delta(p_1-p_2) \prod_{i=1}^3 \frac{1}{p_i^2-m^2+i\epsilon} \int \frac{d^4q}{(2\pi)^4} \frac{1}{q^2-m^2+i\epsilon}$$



$$-i\lambda \int d^4x i\Delta_F(x_1-x) i\Delta_F(x_2-x) i\Delta_F(x_3-x) i\Delta_F(x_4-x)$$

p-proton

$$\rightarrow -i\lambda \int d^4x_1 d^4x_2 d^4x_3 d^4x_4 \exp(i p_1 x_1) \exp(-i p_2 x_2) \exp(i p_3 x_3) \exp(i p_4 x_4) \cdot$$

$$\cdot \int d^4x \cdot \prod_{i=1}^4 \left[\int \frac{d^4q_i}{(2\pi)^4} \frac{i \exp(-i q_i (x_i - x))}{q_i^2 - m^2 + i\epsilon} \right]$$

$$= -i\lambda \int d^4x \cdot \underbrace{\int \frac{d^4q_1}{(2\pi)^4} \exp(-i q_1 (x_1 - x))}_{(2\pi)^4 \delta(p_1 + q_1)} \cdots \underbrace{\int \frac{d^4q_2}{(2\pi)^4} \exp(-i q_2 (x_2 - x))}_{(2\pi)^4 \delta(p_2 + q_2)} \underbrace{\int \frac{d^4q_3}{(2\pi)^4} \exp(i q_3 (x_3 - x))}_{(2\pi)^4 \delta(p_3 - q_3)} \cdot$$

$$\cdot \underbrace{\int \frac{d^4q_4}{(2\pi)^4} \exp(i q_4 (x_4 - x))}_{(2\pi)^4 \delta(p_4 - q_4)} \exp(i x (q_1 + \dots + q_4)) \prod_{i=1}^4 \frac{i}{q_i^2 - m^2 + i\epsilon} =$$

$$= -i\lambda \int d^4x \exp(i x (p_4 + p_3 - p_2 - p_1)) \prod_{i=1}^4 \frac{i}{p_i^2 - m^2 + i\epsilon} =$$

$$= -i\lambda (2\pi)^4 \delta(p_4 + p_3 - p_2 - p_1) \prod_{i=1}^4 \frac{i}{p_i^2 - m^2 + i\epsilon}$$

Ponaučení:

i) vnější'm linkám jsou přiřazeny hybnosti ($x_i \sim p_i$),
kde p_i jsou argumenty $\mathcal{T}(p_1, \dots, p_n)$ a každé vnější lince odpovídá
propagátoru $\frac{i}{p_i^2 - m^2 + i\epsilon}$

ii) Fall, ne

$$\sim \delta(p_1 + \dots + p_4 - p_{4n} - \dots - p_n)$$

je důležitým nástrojem invariantní Greenovy funkce a jejího maticového

Feynmanova pravidla v p -prostoru (skalární)

- sestavit všechny topologicky odlišné diagramy s daným počtem vnějších linií (daným řádem Greenovy funkce) a daným počtem vnitřních (řád pochopného počtu) $\leftarrow$ vnitř

- vnějším liniím vstupujícím do interakce přičíst p_i
liniím vystupujícím z interakce přičíst $-p_i$

- vnějším liniím přičíst propagátor $i\Delta_F(p_i)$

$$\text{---} \overset{p_i}{\curvearrowright} \sim i\Delta_F(p_i) = \frac{1}{p_i^2 - m^2 + i\epsilon}$$

$$\text{---} \leftarrow \overset{p_i}{\curvearrowright} \sim i\Delta_F(-p_i) = \frac{1}{p_i^2 - m^2 + i\epsilon}$$

- vnitřním liniím přičíst propagátor $i\Delta_F(q_i)$

$$\text{---} \overset{q_i}{\curvearrowright} \sim i\Delta_F(q_i) = \frac{1}{q_i^2 - m^2 + i\epsilon}$$

- liniím vnitřních přičíst hybnosti, tak aby se zachovávala na vnitřních čtyřhybnostech.

$$\begin{array}{c} q_1 \quad q_2 \\ \diagdown \quad \diagup \\ \text{---} \\ \diagup \quad \diagdown \\ q_2 - q_1 \end{array} \quad (q_1 - q_2 + \epsilon = 0) \sim -iq$$

$$\text{---} \sim -i\lambda$$

- integrovat přes všechny smyčky
- vyčíslit symetrie faktorem a uctít

22. prednáška

n-bodová Greenova funkcia:

$$\langle \Omega | T[\phi_H(x_1) \dots \phi_H(x_n)] | \Omega \rangle \rightarrow \mathcal{I}(p_1, \dots, p_n) \sim \delta(p_1 + p_2 + \dots + p_k - p_{k+1} - \dots - p_n)$$

explicitni' zo'kon zachán' hybnosti

LSZ - formalismus

časticová fyzika / fenomenologie

$$a \langle p_1, \dots, p_m | q_1, \dots, q_n \rangle_{in} = i \langle p_1, \dots, p_m | S | q_1, \dots, q_n \rangle_{in}$$

teoretici χ/gft

účinný príst

$$\langle \Omega | T[\phi_H(x_1) \dots \phi_H(x_{n+m})] | \Omega \rangle$$

časticové spektrum - spektro'lu' hustota $\mathcal{I}\phi$ (spektrálna konstanta)

$$\text{Heisenbergova pole } \phi_H(x) = e^{iHx} \phi_S(x) e^{-iHx}$$

$$|\Psi\rangle_H = |\Psi(\epsilon=0)\rangle_S$$

Zajímavá časť $\Delta_+(x-y) = \langle \Omega | \phi(x) \phi(y) | \Omega \rangle$ (Schwingerova 2-bodová funkcia)

Pro vlnu' částeček

$$\begin{aligned}
 \langle 0 | \phi(x) \phi(y) | 0 \rangle &= \sum_p \sum_q e^{-ixp} e^{iyq} \langle 0 | a_p a_q^\dagger | 0 \rangle = \\
 &= \sum_p \sum_q e^{-ixp} e^{iyq} \langle 0 | \underbrace{[a_p, a_q^\dagger]}_{\delta_{pq}} | 0 \rangle = \\
 &= \int \frac{d^3q}{(2\pi)^3 2\omega_q} e^{-iq(x-y)} = \\
 &= \int \frac{d^3q}{(2\pi)^3 2\omega_q} e^{-iq(x-y)} \mathcal{J}(q^2 - m_0^2) \theta(q_0)
 \end{aligned}$$

$$\mathcal{J}(f(x)) = \sum_i \frac{\mathcal{J}(x-x_i)}{|f'(x_i)|} \quad \begin{matrix} \text{hroizy} \\ \text{funkce } f \end{matrix}$$

$$\sum_{\alpha} d\alpha X_{\alpha}$$

$$\langle \Omega | \phi_H(x) \mathbb{I} \phi_H(y) | \Omega \rangle = \sum_{\alpha} \langle \Omega | \phi_H(x) | \alpha \rangle \langle \alpha | \phi_H(y) | \Omega \rangle$$

Thm.

Hyperboloid $\sqrt{(2m)^2 + p^2}$ reprezentuje spodu' hranici
níže částicového spektra.

Důkaz:

$$f((1-s)x_1 + sx_2) \leq (1-s)f(x_1) + sf(x_2), \quad s \in [0,1]$$

(Jensenova nerovnost pro konvexní funkce)

23. přednáška

LSZ - redukční formalismus

$$\text{out} \langle \{B\} | \{A\} \rangle_{\text{in}}$$



$$q_1, \dots, q_m \quad p_1, \dots, p_n$$