

QFT2: Problem 22

Robert Hruby

20/03/2021

Find a expansion of $\langle 0 | T[\phi(x_1)\phi(x_2)\phi(x_3)\phi(x_4)\phi(x_5)\phi(x_6)] | 0 \rangle$
 Short form: $\langle x_1 x_2 x_3 x_4 x_5 x_6 \rangle$
 In terms of propagator $\langle 0 | T[\phi(x)\phi(y)] | 0 \rangle$ and represent result graphically.

We take our given expression and write it as generated same as the following formula / equality.

$$\langle 0 | T[e^{\int d^4 x K(x)\phi(x)}] | 0 \rangle = 1 * e^{\frac{1}{2} \int d^4 x d^4 y K(x) \langle 0 | T[\phi(x)\phi(y)] | 0 \rangle K(y)} \quad (1)$$

where $\langle 0 | T[\phi(x)\phi(y)] | 0 \rangle = i\Delta_F(x - y)$

Functional deviate will give us (2) and then apply Wick's theorem will give (3).

$$\frac{\delta}{\delta K(x_1)} \cdots \frac{\delta}{\delta K(x_6)} \langle 0 | T[e^{\int d^4 x K(x)\phi(x)}] | 0 \rangle \Big|_{K \equiv 0} \quad (2)$$

$$\frac{\delta}{\delta K(x_1)} \cdots \frac{\delta}{\delta K(x_6)} e^{\frac{1}{2} \int d^4 x d^4 y K(x) \langle 0 | T[\phi(x)\phi(y)] | 0 \rangle K(y)} \Big|_{K \equiv 0} \quad (3)$$

Since $K = 0$, there will be only 1 non-vanishing point eg. Only 3rd expansion will contribute, therefore.

$$\frac{\delta^6}{\delta K(x_1) \dots \delta K(x_6)} \frac{1}{3!} \frac{1}{8} \int d^4 y_1 \dots d^4 y_6 K(y_1) \dots K(y_6) \langle 0 | T[\phi(y_1)\phi(y_2)] | 0 \rangle \langle 0 | T[\phi(y_3)\phi(y_4)] | 0 \rangle \langle 0 | T[\phi(y_5)\phi(y_6)] | 0 \rangle \quad (4)$$

$$\frac{1}{(6)(8)} \sum_{\sigma \in S_6} \int dy_1 \dots dy_6 \delta(x_{\sigma(1)} - y_1) \dots \delta(x_{\sigma(6)} - y_6) \langle 0 | T[\phi(y_1)\phi(y_2)] | 0 \rangle \langle 0 | T[\phi(y_3)\phi(y_4)] | 0 \rangle \langle 0 | T[\phi(y_5)\phi(y_6)] | 0 \rangle \quad (5)$$

$$\frac{1}{48} \sum_{\sigma \in S_6} \langle 0 | T[\phi(x_{\sigma(1)})\phi(x_{\sigma(2)})] | 0 \rangle \langle 0 | T[\phi(x_{\sigma(3)})\phi(x_{\sigma(4)})] | 0 \rangle \langle 0 | T[\phi(x_{\sigma(5)})\phi(x_{\sigma(6)})] | 0 \rangle \quad (6)$$

there us $6! = 720$ Terms.. \rightarrow but only $(5)(3) = 15$ are different.

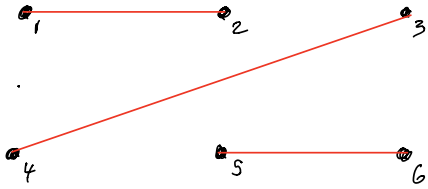
From this point short notation will be used.

possible contractions logic =

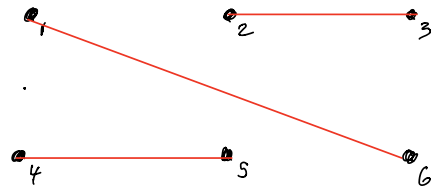
$$\begin{aligned}
& \left(\langle x_1 x_2 \rangle \right) * \left(\langle x_3 x_4 \rangle \langle x_5 x_6 \rangle + \langle x_3 x_5 \rangle \langle x_4 x_6 \rangle + \langle x_4 x_5 \rangle \langle x_3 x_6 \rangle \right) + \\
& \left(\langle x_1 x_3 \rangle \right) * \left(\langle x_2 x_4 \rangle \langle x_5 x_6 \rangle + \langle x_2 x_5 \rangle \langle x_4 x_6 \rangle + \langle x_2 x_6 \rangle \langle x_4 x_5 \rangle \right) + \\
& \left(\langle x_1 x_4 \rangle \right) * \left(\langle x_2 x_3 \rangle \langle x_5 x_6 \rangle + \langle x_2 x_5 \rangle \langle x_3 x_6 \rangle + \langle x_2 x_6 \rangle \langle x_3 x_5 \rangle \right) + \\
& \left(\langle x_1 x_5 \rangle \right) * \left(\langle x_2 x_3 \rangle \langle x_4 x_6 \rangle + \langle x_2 x_4 \rangle \langle x_3 x_6 \rangle + \langle x_2 x_6 \rangle \langle x_3 x_4 \rangle \right) + \\
& \left(\langle x_1 x_6 \rangle \right) * \left(\langle x_2 x_3 \rangle \langle x_4 x_5 \rangle + \langle x_2 x_4 \rangle \langle x_3 x_5 \rangle + \langle x_2 x_5 \rangle \langle x_3 x_4 \rangle \right)
\end{aligned}$$

$$\begin{aligned}
\langle x_1 x_2 x_3 x_4 x_5 x_6 \rangle = & \langle x_1 x_2 \rangle \langle x_3 x_4 \rangle \langle x_5 x_6 \rangle + \langle x_1 x_6 \rangle \langle x_2 x_3 \rangle \langle x_4 x_5 \rangle \\
& + \langle x_1 x_4 \rangle \langle x_3 x_5 \rangle \langle x_2 x_6 \rangle + \langle x_1 x_5 \rangle \langle x_3 x_6 \rangle \langle x_2 x_4 \rangle \\
& + \langle x_1 x_3 \rangle \langle x_4 x_6 \rangle \langle x_2 x_5 \rangle + \langle x_1 x_2 \rangle \langle x_4 x_5 \rangle \langle x_3 x_6 \rangle \\
& + \langle x_1 x_2 \rangle \langle x_3 x_5 \rangle \langle x_4 x_6 \rangle + \langle x_1 x_4 \rangle \langle x_2 x_3 \rangle \langle x_5 x_6 \rangle \\
& + \langle x_1 x_5 \rangle \langle x_2 x_3 \rangle \langle x_4 x_6 \rangle + \langle x_1 x_5 \rangle \langle x_2 x_6 \rangle \langle x_3 x_4 \rangle \\
& + \langle x_1 x_6 \rangle \langle x_3 x_4 \rangle \langle x_2 x_5 \rangle + \langle x_1 x_3 \rangle \langle x_4 x_5 \rangle \langle x_2 x_6 \rangle \\
& + \langle x_1 x_3 \rangle \langle x_2 x_4 \rangle \langle x_5 x_6 \rangle + \langle x_1 x_6 \rangle \langle x_2 x_4 \rangle \langle x_3 x_5 \rangle \\
& + \langle x_1 x_4 \rangle \langle x_2 x_5 \rangle \langle x_3 x_6 \rangle
\end{aligned}$$

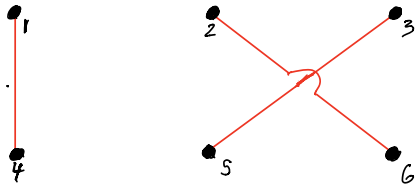
①



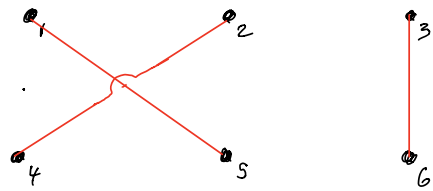
②



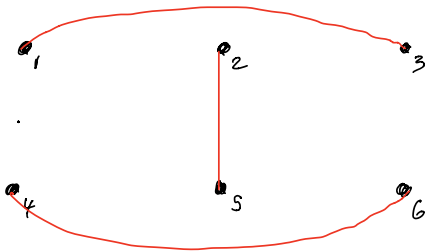
③



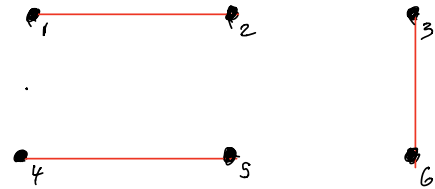
④



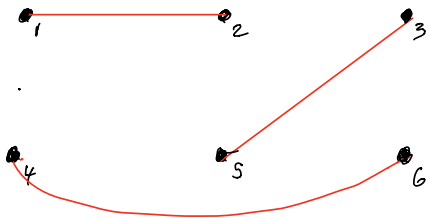
⑤



⑥



⑦



⑧

